**ISO9001:2008 Quality Management System Authentication**

**CE Authentication**


EDS800 series

0.2-1.5KW

mini type

Ver. 3.0



# Users' Manual

SHENZHEN ENCOM ELECTRIC TECHNOLOGIES CO., LTD

# Foreword

Encom products are designed and produced according to EN61800-5-1: 2007，EN 61010-1：2010, EN61800-3: 2004+A1：2012 standards under ISO9001:2008 quality management system.

Thank you for purchasing EDS800 series mini universal inverter from Shenzhen Encom Electric Technologies CO., LTD.

EDS800 series can fulfill all kinds of demand for general-purpose inverter by advanced control manner which make high torque, high precision and wide-range speed regulation drive be available. EDS800 is organic combine of customer's general need and industrial requirement to provide practical PID adjuster, simple PLC, programmable input output terminal control, long-distance synchronous control, impulse frequency provision and other special inverter control with powerful function for customer and to provide highly-integrated incorporative solution of high value for reducing system cost and improving system reliability for device manufacturing and automatization engineering customers.

EDS800's big torque low noise and low electromagnetic disturbance during operation can fulfill customer's environmental protection requirement by space voltage vector PWM control technique and electromagnetic compatibility unitary design.

Assembling wiring, parameter setting, troubleshooting and daily maintenance notice are available in this manual. To make sure that you can correctly assemble and operate EDS800 series inverters to exert their excellent performance, please read this user manual detailedly before you assemble the device and conserve the manual appropriately before the end-user get them.

Please contact our office or dealer in all places at any moment if you have any doubts or special demands when using these inverters, and you can also contact our after service center in our headquarters directly. We will serve you with all our heart.

We reserve our right to notice you if we change contents of this manual.

# Contents

# 1 Safety information and use notice points

In order to ensure the safety of your personal and equipment, before using the inverter, please read this chapter of contents conscientiously.

## 1.1 Safety precautions

There are three kinds of safe relevant warnings in this service manual, they are as follows:

This symbol explains items that need to be paid attention to when being operated.

note

This symbol is briefed on some useful information.

This symbol briefs on: If does not operate on request, may cause death, severely injured or serious property loss.

.

(1) Forbid to connect U, V, W output end to AC power supply, otherwise cause the complete damage of the inverter.
(2) Don't make P- and P + short-circuited, otherwise cause the inverter to be damaged.
(3) The inverter is forbidden to install on the flammables, otherwise have danger of fire.
(4) Don't install it in the environment with explosive gas, otherwise have danger of causing explosion.
(5) After connecting main loop, should carry on insulating treatment to bare wiring end, otherwise have danger of getting an electric shock.
(6) If being connected to the power supply, don't operate the inverter with moist hands, otherwise have danger of getting an electric shock.
(7) The ground terminal of the inverter must be grounded well.
(8) Inverter being connected to power supply, please don't open cover and carry on wiring, can connect the wire or check only after closing power for 10 minutes.
(9) Only qualified personnel may carry on wiring and forbid leaving over any conductive thing in machine, otherwise have danger of getting an electric shock or causing damage of the inverter.
(10) Inverter stored for over 2 years, should be stepped up gradually with voltage regulator first while having the electricity, otherwise have danger of getting electric shock and explosion.

(1) It is prohibited that connect AC220V signal to control ends except TA, TB, TC, otherwise have danger of damaging property.

(2) If the inverter is damaged or without all parts, please don't install and operate it, otherwise have danger of fire or cause personnel to be injured.

(3) When installing, should choose a place where can endure the inverter, otherwise have danger of injuring personnel or damaging property while falling down.

## 1.2 Use range

(1) This inverter is only suitable for three phases AC asynchronous motor in general industrial field.

(2) While applying inverter to such equipments that relate much to the life, great property, safety devices etc., must handle cautiously, and consult with producer, please.

(3) This inverter belongs to the control device of general industrial motor, if used in dangerous equipment, must consider the security safeguard procedures when the inverter breaks down.

## 1.3 Use notice points

(1) EDS800 series inverter is voltage-type inverter, so temperature, noise and vibration slightly increasing compared to power source running when using, belongs to normal phenomenon.

(2) If need to run for a long time with constant torque of low-speed, must select motor of frequency conversion for use. Use general asynchronous AC motor when running at a low speed, should control temperature of the motor or carry on heat dissipation measure forcedly, so as not to burn the generator.

(3) Such mechanical device needing lubricating as the gearbox and gear wheel, etc., after running at a low speed for a long time, may be damaged as lubrication result become poor, please take necessary measure in advance.

(4) When the motor running with frequency above specified, besides considering the vibration, noise increase of the motor, must also confirm speed range of the motor bearing and the mechanical device.

(5) For hoist and great inertia load, etc., the inverter would shut off frequently due to over-current or over-voltage failure, in order to guarantee normal work, should consider choosing proper brake package.

(6) Should switch on/off the inverter through terminal or other normal order channels. It is prohibited that switch on/off the inverter frequently by using strong electric switch such as magnetic control conductor, otherwise will cause the equipment to be damaged.

(7) If need to install such switch as the magnetic control conductor, etc. between inverter output and the motor, please guarantee the inverter is switched on/off without output, otherwise may damage the inverter.

(8) The inverter may meet with mechanical resonance of the load within certain range of frequency output, can set up jumping frequency to evade.

(9) Before using, should confirm the voltage of the power is within the working voltage range allowed, otherwise should vary voltage or order special inverter.

(10) In the condition of altitude above 1000 meters, should use the inverter in lower volume, reduce output current by 10% of specified current after each 1500 meters height increasing.

(11) Should make insulation check to the motor before using it for the first time or after a long time placement. Please inspect with 500V voltage-type megohm meter according to method shown as graph1-1 and insulation resistance should not be smaller than 5 MΩ, otherwise inverter may be damaged.

(12) To forbid assembling capacitor for improving power factor or lightningproof voltage-sensible resistance etc., otherwise will cause malfunction trip of the inverter or damage of the parts, shown as graph 1-2.

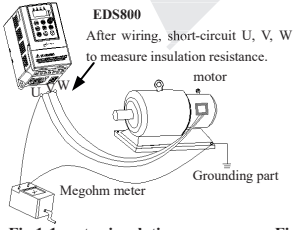



Fig.1-1 motor insulation measure

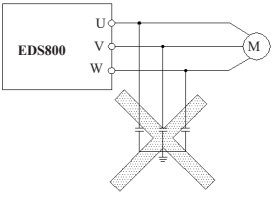



Fig.1-2 capacitor at output side forbidden

## 1.4 Scrap notice points

When disposing scrap inverter and its parts, please note:

(1) The unit: please discard as industrial useless.

(2) Electrolytic capacitor: when burning the inverter electrolytic capacitor in it may explode.

(3) Plastic: when plastic, rubber parts etc. in the inverter are burning, they may bring bad, poisonous gas, so please be ready to safeguards.

# 2 Type and specification of the inverter

## 2.1 Incoming inverter inspect

(1) Check if there is damage during transportation and inverter itself has damage or fall-off parts.
(2) Check if parts presented in packing list are all ready.
(3) Please confirm rated data of the inverter is in line with your order requirement.

Our product is guaranteed by strict quality system during manufacturing, packing, transportation etc., please contact our company or local agent rapidly if some careless omission or mistake arise, we'll deal with it as soon as possible.

## 2.2 Type explanation

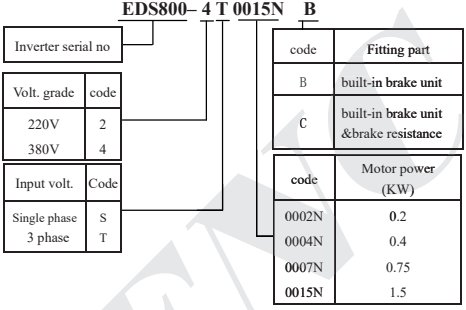



**Fig. 2-1 type description**

**note** If the inverter hasn't relevant content or can be defaulted, code after "/" will be ignored.

## 2.3 Nameplate explanation

Nameplate presented as figure 2-2 with type and rating data at the bottom of inverter right side.

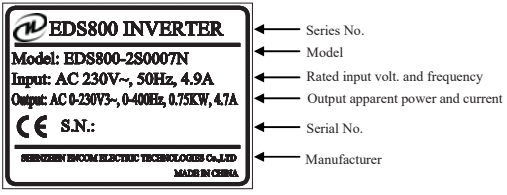



**Fig.2-2 Nameplate**

## 2.4 Series type explanation

**Table 2-1 series type explanation**

| Inverter type | Rated power (KVA) | Rated output current (A) | Adapted motor (KW) |
|---|---|---|---|
| EDS800-2S0002N | 0.6 | 1.6 | 0.2 |
| EDS800-2S0004N | 1.1 | 3 | 0.4 |
| EDS800-2S0007N | 1.8 | 4.7 | 0.75 |
| EDS800-2S0015N | 2.8 | 7.5 | 1.5 |
| EDS800-4T0007N | 1.5 | 2.3 | 0.75 |
| EDS800-4T0015N | 2.4 | 3.7 | 1.5 |

## 2.5 Appearance and parts name explanation

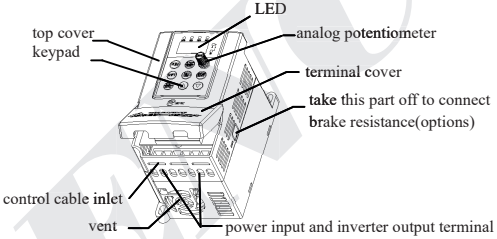



**Fig. 2-3 Parts name sketch for EDS800**

## 2.6 Outer size and gross weight

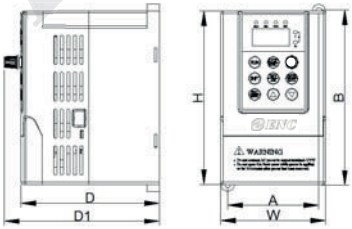



**Fig.2-4 Outline Image**

**Table 2-2 EDS800-2S0002N~EDS800-4T0015N mounting size**

| Inverter type | W (mm) | H (mm) | D (mm) | D1 (mm) | A (mm) | B (mm) | Fixing aperture (mm) | Gross weight (kg) |
|---|---|---|---|---|---|---|---|---|
| EDS800-2S0002N | 89 | 148.5 | 112.5 | 124.7 | 74 | 138 | 5 | 1 |
| EDS800-2S0004N | | | | | | | | 1 |
| EDS800-2S0007N | | | | | | | | 1.1 |
| EDS800-2S0015N | | | | | | | | 1.2 |
| EDS800-4T0007N | | | | | | | | 1.1 |
| EDS800-4T0015N | | | | | | | | 1.1 |

## 2.7 Outer size of keypad and its fixing box (unit: mm)

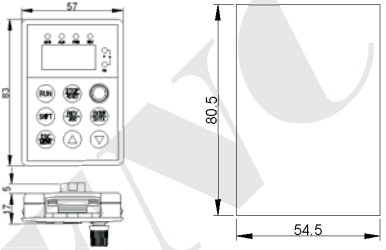



**Fig.2-5 outer size of keypad and outline of its fixing box**

## 2.8 Product technic index and spec.

| item | | Item description |
|---|---|---|
| Input | Rating volt.,frequency | 3 phase 380V, 50Hz/60Hz; single phase 220V, 50Hz/60Hz |
| | Allowed work volt. range | 3 phase voltage: 320V~460V;<br>single phase voltage: 200V~260V |
| output | Voltage | 380V grade: 0~380V; 220V grade: 0~220V |
| | Frequency | 0Hz-400Hz |
| | Over loading capacity | 150% of rating current for1 minute，200% of rating current for 0.5 second; |
| Control performance | Control mode | Optimum space voltage vector SVPWM constant volt. Frequency ratio V/F control |
| | Speed regulation range | 1:100 |
| | Start-up torque | 100% of rating torque at low frequency |

| | | | |
|---|---|---|---|
| | Running speed stable state precision | | ≤±0.5% of rating synchronous speed |
| | Frequency precision | | Digital setting: max. frequency×±0.01%; analog setting: max.frequency×±0.5% |
| | Frequency resolution | Analog setting | 0.1% of max. frequency-+96 |
| | | Digital setting | 0.01Hz |
| | | Exterior pulse | 0.5% of max. frequency |
| | Torque boost | | Automatic torque boost，manual torque boost 0.1%~20.0% |
| | V/F curve (volt. frequency characteristic) | | Set rating frequency randomly at range of 5~400Hz，can choose constant torque, degressive torque 1, degressive torque 2, degressive torque 3 in total 4 kinds of curve |
| | Accelerating decelerating curve | | 2 modes: straight line accelerating decelerating and S curve accelerating decelerating; 7 kinds of accelerating decelerating time (unit minute/second can be optioned), max. time 6000 minutes. |
| | brake | Powerconsumption brake | exterior brake resistance |
| | | DC brake | Optional start-up and stop，action frequency 0~15Hz，action volt. 0~15%，action time 0~20.0 s |
| | Jog | | Jog frequency range: 0.50Hz~50.00Hz; jog accelerating decelerating time 0.1~60.0s can be set |
| | Multisection speed running | | Realized by interior PLC or control terminal |
| | Interior PID controller | | Be convenient to make closed-loop system |
| | Automatic energy save running | | Optimize V/F curve automatically based on the load to realize power save running |
| | Automatic volt. regulation (AVR) | | Can keep constant output volt. When power source voltage varies. |
| | Automatic current limiting | | Limit running current automatically to avoid frequent over-current which will cause trip |
| Running function | Running order specified channel | | Key pad specified, control terminal specified, serial port specified |
| | Running frequency specified channel | | Digital provision, analog provision, impulse provision, serial port provision, combined provision，can be switched at any time by kinds of method |
| | pulse output channel | | Impulse square wave signal output of 0~20KHz，can realize output of physical parameter such as setting frequency, output frequency etc. |
| | Analog output channel | | 1 channel of analog signal output，AO channel can be 4~20mA or 0~10V; through it the inverter can realize output of physical parameter such as setting frequency, output frequency etc. |
| keypad | LED display | | Can display setting frequency, output frequency, output voltage, output current etc. in total 14 kinds of parameter |
| | Lock the button | | Lock all or part of the buttons(analog potentiometer can't be locked) |

| | | |
|---|---|---|
| Protection function | | Over-current protection, over-voltage protection, lack-voltage protection, over-heat protection, over-load protection, missing phase protection (in option)etc. |
| Fitting parts | | brake subassembly, remote-control keypad, connecting cable for remote-control keypad etc. |
| ambient | Use ambient | indoor，not bare to sunlight，no dust, no corrosive gas, no flammable gas, no oil fog, no vapor, no water drop or salt etc. |
| | altitude | Lower than 1000m |
| | Ambient temperature | -10ºC~+40ºC(under ambient temperature 40ºC ~50ºC, please reduce the volume or strengthen heat sink) |
| | Ambient humidity | Smaller than 95%RH, no condensation water |
| | vibration | Smaller than 5.9m/s²(0.6g) |
| | Storage temperature | -40ºC~+70ºC |
| Config-uration | Defending grade | IP20 |
| | Cooling mode | By fan with automatic temperature control |
| Mounting mode | | Wall hanging |

**note** To exert excellent performance of this inverter, please choose correct type and check relevant content according to this chapter before wiring for use.

Must choose correct type, otherwise may cause abnormal running of the motor or damage

# 3 Installation and wiring

## 3.1 Installation ambient

### 3.1.1 Demand for installation ambient

(1) Installed in drafty indoor place，ambient temperature within -10ºC~40ºC，need external compulsory heat sink or reduce the volume if temperature exceeds40ºC.

(2) Avoid installing in place with direct sunlight, much dust, floating fibre and metal powder.

(3) Forbid to install in place with corrosive, explosible gas.

(4) Humidity should be smaller than 95%RH，without condensation water.

(5) Installed in place of plane fixing vibration smaller than 5.9m/s²(0.6g).

(6) Keep away from electromagnetic disturbance source and other electronic apparatus sensible to electromagnetic disturbance.

### 3.1.2 Installation direction and space

(1) Normally the inverter should be mounted vertically, horizontal mounting will seriously affect heat dissipation and the inverter must be used in lower volume.

(2) Demand for minimum mounting space and distance，please see Fig.3-1.

(3) When install multiple inverters up and down, must apply leading divider between them, see fig. 3-2.

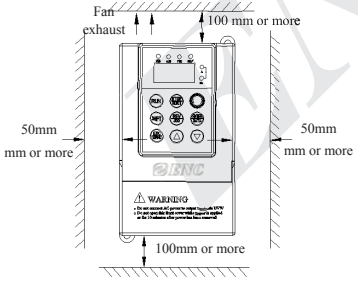



Fig. 3-1 mounting space

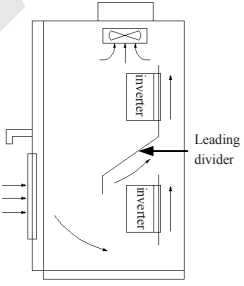



Fig. 3-2 mounting of multiple inverters

## 3.2 Parts disassembly and installation

### 3.2.1 Key board disassembly and installation

(1) disassembly

Let the forefinger press finger inlet on the keypad，depress fixing flexible plate on the top lightly, draw it outward, then you can disassemble the keypad.

(2) assembly

First place the fixing hook at the bottom of keypad onto mounting claw on keypad mounting hole, let forefinger press fixing flexible plate on top of keypad and then push it inside, release it in proper location(after a crisp sound).

### 3.2.2 Plastic cover disassembly

Put the finger into handle hole on the bottom of cover, lift it, then you can disassemble the cover.

## 3.3 wiring notice points

(1)Assure power cuf off completely for above 10 minutes before wiring, otherwise have danger of getting electric shock.
(2)Forbid connecting power wire to output U, V, W of the inverter.
(3)There is current leakage in the inverter and leak current of middle/high power inverter is bigger than 5mA, for safety reason，inverter and motor must be earthed safely, commonly use 3.5mm² above copper wire as ground wire and ground resistance smaller than 10Ω.
(4)Before shipment compression resistance test of the inverter is passed，so user should not conduct compression resistance test again.
(5)Should not assemble electromagnetic contactor and absorbing capacitance or other absorbing device, see Fig.3-3.
(6)To be convenient to over current protect of input side and power off maintenance inverter should be connected to power supply through relay.
(7)Connecting wire for relay input and output loop(X1~X8, OC1~OC4, FWD, REV), should use above 0.75mm² glued wire or shielding wire，one shielding layer end hung in the air, the other connected to grounding end ⏚ , connecting wire shorter than 20m.

(1)Before wiring, assure power supply is cut off completely for 10 minutes and all LED indicator ligh extinguished.
(2)Before internal wiring, confirm that DC volt. Between main loop end P+ and P- fall down to below DC36V.
(3)Wiring can only be done by professional person trained and qualified.
(4)Before electrification, check if voltage grade of the inverter is in line with that of power supply volt., otherwise will cause personnel injured and device damaged.

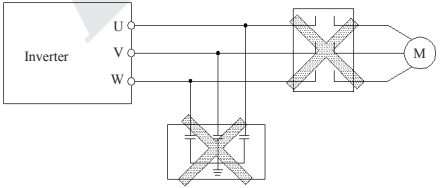



**Fig.3-3 banned magnetic control conductor and absorbing capacitance between inverter and motor**

## 3.4 Main loop terminal wiring

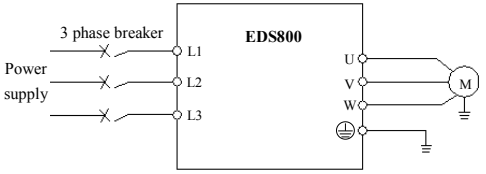



**Fig.3-4 main loop simple wiring**

### 3.4.1 Connection between inverter and fitting parts

(1) Must assemble disjunction device such as isolation switch etc. between powersource and the inverter to assure personal safety when repairing the inverter and needing compulsory power off.

(2) Power supply loop must have breaker or fuse with over current protection function to avoid malfunction expanding caused by failure of after device.

(3) AC input reactor

If high-order harmonics between inverter and Power supply is biggish which can't fulfil system requirement, or need to improve input side power factor, AC input reactor is needed.

(4) Magnetic control conductor only be applied to power supply control and don't apply magnetic control conductor to controlling on/off of the inverter.

(5) Input side EMI filter

Can use EMI filter to inhibit high-frequency conduction disturbance and emission disturbance from inverter power supply wire.

(6) Output side EMI filter

Can use EMI filter to inhibit emission disturbance noise and wire leakage current from output side.

(7) AC output reactor

Advise assembling AC outputreactor to avoid motor insulation damage, too large over current and inverter frequent protection when connecting wire from inverter to mo...

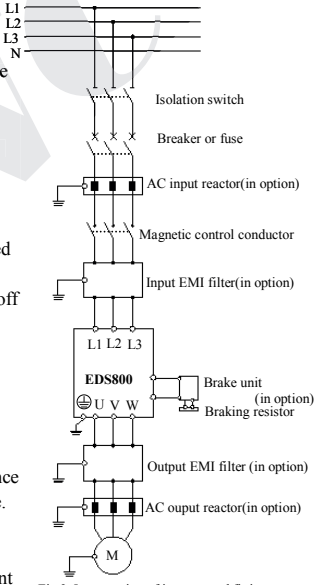



Fig.3-5 connection of inverter and fitting parts

exceeds 50m.But voltage drop of AC output reactor must be considered. Improve input output voltage of the inverter or let the motor in lower volume to avoid burning off the motor.

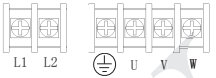
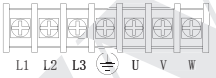
(8) Complete ground wire

Inverter and motor must be earthed and grounding resistor smaller than 10Ω.Grounding wire should be shorter enough and wire diameter be bigger enough(not smaller than 3.5mm²):

### 3.4.2 Main loop terminal wiring

For main loop input output terminal, see table 3-1.

**Table 3-1 main loop input output terminal description**

| Adapted type | Main loop terminal | End name | Function description |
|---|---|---|---|
| EDS800-2S0002N<br>~<br>EDS800-2S0015N |  | L1<br>L2<br><br>U,V,W | Zero wire<br>live wire<br>Grounding terminal<br>3 phase AC output end |
| EDS800-4T0007N<br>EDS800-4T0015N |  | L1,L2,L3<br><br>U,V,W | 3 phase AC intput end<br>Grounding terminal<br>3 phase AC output end |

## 3.5 Basic running wiring diagram

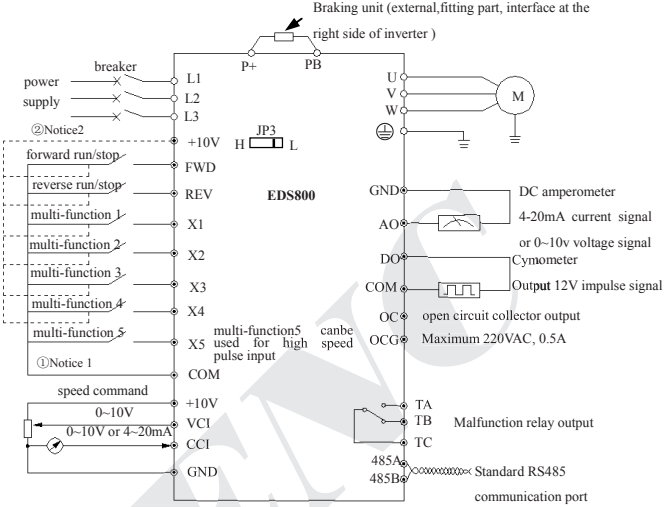



**Fig. 3-6 basic wiring diagram**

Notice1:When FWD,RWV,X1～X5 terminal imput signal need low level(or pup joint with COM) is effective. Please put JP3 on “L”.

Notice2:When FWD,REV,X1～X4 terminal imput signal need high level(or pup joint with +10v) is effective. Please put JP3 on “H”.

## 3.6 Control loop collocation and wiring

### 3.6.1 Location&function of terminal and jump-wire:

For location of terminal and switch on the CPU board, please see Fig.3-7.

Function description of terminal provided for the user, please see Table 3-2，function and setup description of switch, please see Table 3-3，terminal CN1 is for manufacturer’s use. Should carry on terminal wiring correctly and set switch on the CPU board before using the inverter，to use at least No.24 conducting wire as terminal connecting wire is recommended.

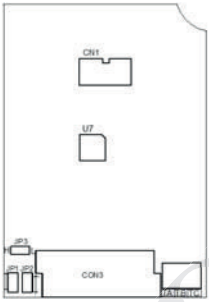



**Fig. 3-7 switch on CPU board**

**Table 3-2 function description of terminal provided for user**

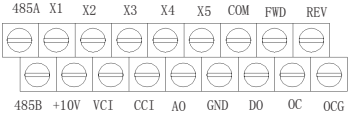
| symbol | function | Description |
|---|---|---|
| CON2 | Malfunction relay signal output | Always-open connect pin of the relay closed when malfunction in inverter occurs |
| CON3 | External terminal input output control | Use this port when external terminal control inverter running |

**Table 3-3 function description of switch provided for user**

| symbol | function | factory default |
|---|---|---|
| JP1 | Analog AO output,0～10v exchange with 4～20mA<br>When be put on "V"side,for 0～10v output;when be put on"I",for 4～20mA output | 0~10V |
| JP2 | Analog CCI input,0～10V exchange with 4～20mA.<br>When be put on "V"side,for 0～10V input;when be put on "I" side.for 4～20mA input. | 0~10V |
| JP3 | Xi terminal iinput effective level exchange:when put on"H"side,Xi input high level effective(the effective voltage is 5～12V);When put on "L" side. Xi input low level effective(the effective voltage is 0～6V) | Low level effective |

### 3.6.2 Explanation for control CPU board

(1) control loop terminal CON3 arranged as follows:




(2) CN2 terminal function description as Table 3-4.

**Table 3-4 CPU board CN2 terminal function table**

| item | symbol | name | Function description | Spec. |
|---|---|---|---|---|
| run command | FWD | Forward run command | Forward reverse run command, see F5.08 group double-wire and three-wire control function description | Input impedance: R=2K Ω<br>Max. input frequency: 200Hz<br><br>X5 can be pule input terminal<br>Max. output Freq.: 50KHz<br>Input voltage range: 12~15V |
| | REV | Reverse run command | | |
| Multi-function input termina | X1 | Multi-function input 1 | Used for multi-function input terminal, for detailed see Chapter 6 Section 6.6 terminal function parameter(F5 group)input end function description. | |
| | X2 | Multi-function input 2 | | |
| | X3 | Multi-function input 3 | | |
| | X4 | Multi-function input 4 | | |
| | X5 | Multi-function input 5 | | |
| | +10V | +10V power supply | Provide +10V power supply. (negative pole: GND) | Max. output current: 10mA |
| | COM | Common end+12V power supply negative pole | 12V grounds | |
| | GND | +10V power supply negative pole | Reference ground of analog signal and +10V power supply | |
| Analog value input | CCI | Analog value input CCI | voltage, current optioned by JP2, factory default is voltage. (reference ground: GND) | Input voltage range: 0~10V (input impedance: 70KΩ)<br>Input current range: 4~20mA (input impedance: 250Ω)<br>Resolution: 1/1000 |
| | VCI | Analog value input VCI | Accept analog voltage input | Input voltage range: 0~10V (input impedance: 70KΩ)<br>resolution: 1/1000 |

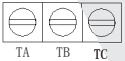
| | | | | |
|---|---|---|---|---|
| Analog value output | AO | Analog value output | Provide analog voltage/current output，can express 6 kinds of parameter see F5.17 parameter description，output voltage/current optioned by JP1，factory default output voltage.<br>(reference ground: GND) | Current output range: 4~20mA<br>voltage output range: 0~10V |
| Multifunction output end | OC | Relay output terminal | Used for multi-function switch output terminal, for detailed see Chapter 6 Section 6.6 terminal function parameter (F5 group) output end function description.<br>(common end: OCG) | Work voltage range:0~220V<br>Max. output current:500mA<br>For use method please see description of parameter F5.10 |
| | DO | H-speed impulse output terminal | Used for multi-function impulse signal output terminal, for detailed see Chapter 6 Section 6.6 terminal function parameter(F5 group) output end function description. (common end: COM) | Output impulse voltage: 12V<br>Output frequency range: depending on parameter F5.24, max.20KHz |

(4) RS485 terminal function description as table 3-5

**Table 3-5 CPU board RS485 terminal function table**

| item | symbol | name | Function description | spec |
|---|---|---|---|---|
| communication | 485A | 485 communication interface | 485 difference signal positive end | For standard 485 communication interface please use twisted-pair or STP |
| | 485B | | 485 difference signal negative end | |

(5) control terminal CON2，arranged as follows:




(6) CON2 terminal function description as Table 3-6.

**Table 3-6 CPU board CON2 terminal function**

| Item | symbol | name | Function description | Spec |
|---|---|---|---|---|
| Relay output terminal | TA | Inverter malfunction output relay | Normal: TB-TC closed, TA-TC open<br>Malfunction: TB-TC open, TA-TC closed | TB-TC: always-closed,<br>TA-TC: always-open contact capacity:<br>AC250V/2A (COSΦ=1)<br>AC250V/1A (COSΦ=0.4)<br>DC30V/1A |
| | TB | | | |
| | TC | | | |

### 3.6.3 Analog input output terminal wiring

(1) VCI terminal accepts analog voltage signal input，wiring as follow:

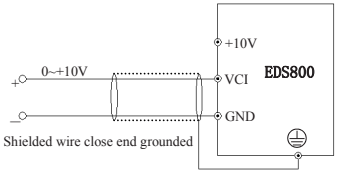



**Fig.3-8 VCI terminal wiring diagram**

(2) CCI terminal accepts analog signal input, input voltage(0~10V) or input current(4~20mA)，wiring mode as follows:

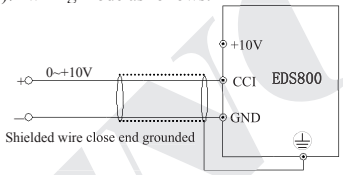



**Fig.3-9 CCI terminal wiring diagram**

(3) wiring of analog output terminals AO

Analog output terminals AO connected to analog meter and kinds of physical data can be indicated, terminal wiring mode as Fig.3-10.

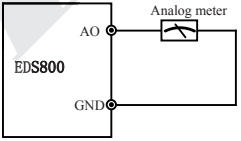



**Fig.3-10 analog output terminal wiring**

**note**

(1) When inputing anglog signal，can connect filter capacitor or common module inductance between VCI and GND or between CCI and GND .

(2) Analog input, output signal is easy to be disturbed，so must use shielded cable when wiring and well grounded, wiring length should be as short as possible.

### 3.6.4 Communication terminal wiring

EDS800 inverter provides 485 serial communication interface for the user.

Following wiring methods make single-main single-sub control system or single-main multi-sub control system possible. Using upper machine(PC or PLC controller)software can realize real time supervision to inverter in the industrial control system so that realize complicated run control such as long-distance control, high automatization etc; you can also take one inverter as mainframe and the others as submachine to form cascade or synchronous control network.

(1) When inverter 485 interface connected to other devices with 485 interface, you can connect wire as below figure.

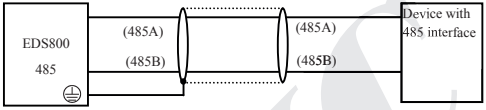



**Fig.3-11 communication terminal wiring**

(2) To connect remote control keypad, you can connect plug of remote control keypad to RS485 directly. No need to set any parameter，inverter local keypad and remote control keypad can work at one time.

(3) Connection between inverter RS485 interface and upper machine(with RS232 interface):

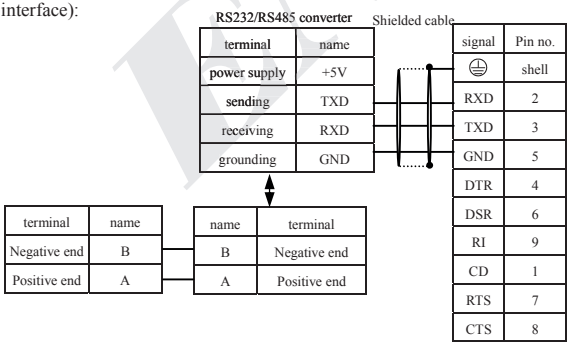



**Fig. 3-12 RS485 communication wiring**

(4)Multiple inverters can be connected together per RS485 and 31pcs inverter can be connected together at most. Communication system is more prone to disturbance a

connected inverters increasing, following wiring is recommended:

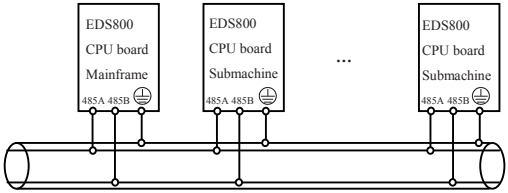



**Fig. 3-13 recommended wiring for multiple inverters communication (all inverters and motors well earthed)**

Normal communication still not available if using above wiring, can try to take following measure:

1> Provide separate power supply for PLC (or upper machine) or isolate its power supply.

2> Apply magnetic circle on the communication wire.

3> Reduce inverter carrier wave frequency properly.

**note**

(1) When form the network only by inverters, you must set local address parameter F2.15 of the mainframe EDS800 to 0.

(2) For programming of RS485 interface，please refer to chapter 10 MODBUS communication protocol.

## 3.7 Installation guide for anti-jamming

Main circuit of the inverter is composed of high-power semiconductor switch gear，so some electromagnetic noise will arise during work，to reduce or stop disturbance to environment，show you assembling method of inverter disturbance suppressing from many aspects such as disturbance suppressing, spot wiring, system grounding, leak current, usage of power supply filter etc. in this section to be referred to during spot assembling.

### 3.7.1 Restraining to noise disturbance

Disturbance brought by the working inverter may affect nearby electronic device，effect degree relates to surrounding electromagnetic environment of the inverter and anti-disturbance capacity of this device.

**(1) type of disturbance noise**

According to work principle of the inverter, there are mainly 3 kinds of noise disturbance source:

1> circuit conduction disturbance；

2> space emission disturbance；

3> electromagnetic induction disturbance;

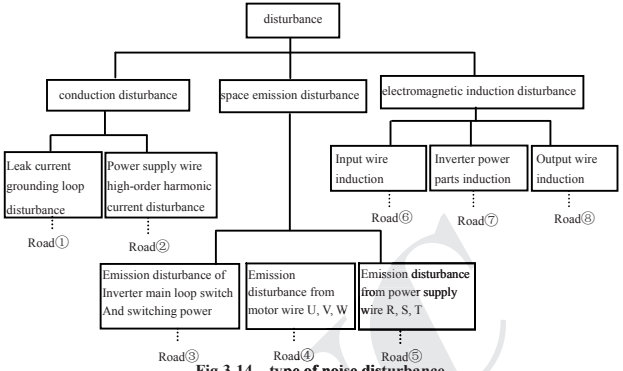



**Fig.3-14 type of noise disturbance**

**(2) noise spread road**

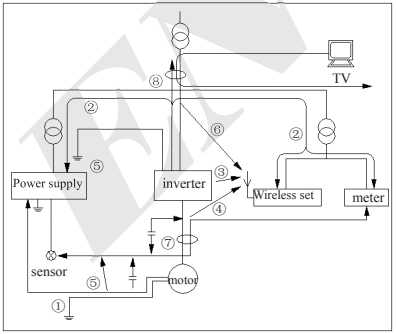



**Fig.3-15 noise disturbance spread road sketch**

(3) basic countermeasure for suppressing disturbance

**Table 3-7 disturbance suppressing countermeasure table**

| Noise spread road | Countermeasure of weakening effect |
|---|---|

| | |
|---|---|
| ① | When grounding wire of peripheral device and wiring of the inverter compose closed-loop, inverter grounding wire leakage current would make the device do wrong action. Can reduce wrong action if the device is not earthed here. |
| ② | High-order harmonic from the inverter would make voltage and current transmit through power supply wire when peripheral device and the inverter electrified by same power supply, would disturb other devices in this same power supply system，can take following suppressing measure: assemble electromagnetic noise filter at inverter input end；isolate other devices by isolation transformer; connect power supply for peripheral device with remote power source; install ferrite filter magnetic circle for L1, L2, L3 three-phase conducting wire of the inverter to suppress conduction of high-frequency harmonic current. |
| ③④⑤ | ● Keep device and signal wire prone to disturbance from the inverter. Should use shielded signal wire, shielding layer single end earthed and try best to keep away from the inverter and its input, output wire. If signal wire must intersect strong power cable, must keep them in real intersection and avoid parallel.<br>● Install high-frequency noise filter(ferrite common module choke, folksay magnetic circle) separately at input, output root，which can effectively suppress emission disturbance from dynamic wire.<br>● Should place motor cable shield of biggish thickness, for instance set it in tube with biggish thickness (above 2mm) or bury it in cement slot. Dynamic wire set into metal tube and use shielding wire to be grounded (use 4-core motor cable, one side is earthed through the inverter, the other side connected to motor shell). |
| ⑥⑦⑧ | To prevent parallel or bundled power and weak conducting wire；should keep away from inverter mounted device to the best and its wiring should keep away from power wire of the inverter such as L1, L2, L3, U, V, W etc.. Should pay attention to relative mounting place between device with strong electric field or strong magnetic field and the inverter, should keep distance and vertical intersection. |

### 3.7.2 Local wiring and earthing

(1) Avoid parallel cable from inverter to motor (U, V, W terminal education wire) and power supply wire (L1, L2, L3 terminal input wire). Should keep distance of 30cm above.

(2) Try your best to place motor table from U, V, W terminals in metal tube or metal wiring slot.

(3) Should use shielded cable as common control signal cable，shielding layerclose-to–inverter side earthed after connected with ⏚ terminal of inverter.

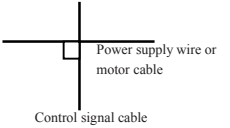



**Fig.3-16 system wiring demand**

(4) Cable educed from inverter ⏚ terminal must be connected directly to earth-plate and can't be connected to ground through grounding wire of other devices.

(5) Powerful cable(L1, L2, L3, U, V, W)should not parallel control signal cable closely, say nothing of being bundled together, must keep distance of 20~60cm

above (related to size of powerful current). Should cross each other vertically if intersection, as Fig.3-16.

(6) Powerful grounding wire must be connected to earth separately from weak grounding cable such as control signal and sensor cable etc.

(7) Forbid to connect other electricity consumption device to inverter power supply input end(L1, L2, L3).

### 3.7.3 Relation of long-distance wiring and current leak and the countermeasure

High-order harmonic will form between-line leak current through distributing capacitor and to-earth leak current when long-distance wiring between inverter and motor commence. Can adopt following method to suppress:

(1) install ferrite magnetic circle or output reactor at inverter output side.

End voltage of the motor will be reduced markedly when installing reactor of 5% above rated voltage dropn and make long-distance wiring to U, V, W. Fully loaded motor have the danger of burning itself，should work in lower volume or step up its input output voltage.

(2) Reduce carrier wave frequency but motor noise would increase accordingly.

### 3.7.4 Installation demand for electromagnetic on-off electronic device

Relay，magnetic control conductor and electromagnetic iron and so on, these electromagnetic on-off electronic device would bring lots of noise during work, so you should pay full attention to when installing them beside the inverter or in the same control chamber with the inverter and must install surge absorbing device as shown in Fig. 3-17.

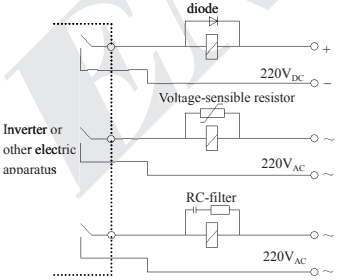



**Fig.3-17 installation demand for electromagnetic on-off device**

# 4 Run and operation explanation for inverter

## 4.1 Run of inverter

### 4.1.1 Running order channels

There are 3 kinds of order channel for controlling run action of the inverter such as run, stop, jog etc.:

**0: keypad**

Control by key RUN, STOP, REV JOG on keypad(factory default).

**1: control terminal**

Use control terminal FWD, REV, COM to make of double-line control，or use one terminal of X1～X5 and FWD or REV to make of three-line control.

**2: serial port**

Control run and stop of the inverter through upper machine or other device which can communicate with the inverter.

Choose order channel by setting function code F0.02；and also can choose by multi-function input terminal(F5.00~F5.07 choose function 29, 30, 31).

Please make switching debugging in advance when switch the order channel to check if it can fulfil system requirement，otherwise have danger of damaging device and injuring personal.

### 4.1.2 Frequency-provision channel

Under EDS800 common run mode there are 9 kinds of provision channel:

**0: keypad analog potentiometer provision；**

**1: direct digital frequency provision；**

**2: terminal UP/DOWN provision(store after power-off or stop)；**

**3: serial port provision；**

**4: analog value VCI provision；**

**5: analog value CCI provision；**

**6: reserved；**

**7: terminal pulse(PULSE) provision；**

**8: combination set;**

**9: terminal UP/DOWN provision(not store after power-off or stop)**

### 4.1.3 Work state

Work state of EDS800 is classified as waiting state and running state:

waiting state: If there is no running command after the inverter electrified or after stop command during running state, the inverter enters into waiting state.

running state: the inverter enters into running state after receiving run command.

### 4.1.4 Run mode

EDS800 inverter have 6 kinds of run mode，following is in turn according to their priority: jog run→closed-loop run→PLC run→multisection speed run→ traverse run→common run. Shown as Fig.4-1.

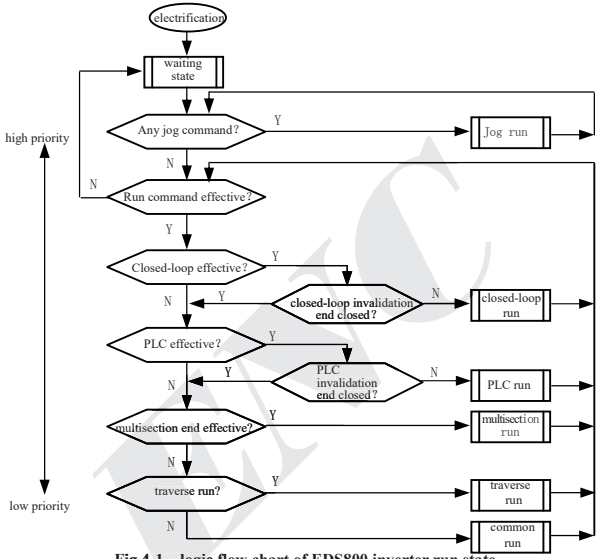



**Fig.4-1 logic flow chart of EDS800 inverter run state**

**0: jog run**

Upon receiving jog run command (for instance, press the REV JOG key on keypad) during waiting state, the inverter run at jog frequency (see function code F2.06~F2.08).

**1: closed-loop run**

The inverter will come into closed-loop run mode when closed –loop run control effective parameter is set(F3.00=1). Namely carry on PID adjustment to specified value and feedback value(proportion integral differential calculation, see F3 group function code) and PID adjustor output is inverter output frequency. Can make closed-loop run mode ineffective and switch to lower level run mode by multi-function terminal (function 20).

**2: PLC run**

The inverter will enter into PLC run mode and run according to run mode preset(see F4 group function code description) through setting PLC function effective parameter(F4.00 last bit≠0). Can make PLC run mode ineffective and switch to lower level run mode by multi-function terminal (function 21).

**3: multi-section speed run**

By nonzero combination of multi-function terminal(1, 2, 3, 4 function)，choose multisection frequency 1~15(F2.30~F2.44) to run at multisection speed.

**4: traverse run**

The inverter will enter into traverse run mode when traverse function effective parameter（F6.00=1）is set. Set relevant traverse run special parameter according to textile traverse craft to realize traverse run.

**5: common run**

Common open loop run mode of general inverter.

In above 6 kinds of run mode except "jog run" the inverter can run according to kinds of frequency setting method. In"PID run""PLC run""multisection run""common run"mode the inverter can also carry on pendular frequency adjustment.

## 4.2 Operation and use of key board

### 4.2.1 Keypad layout

Keypad is main unit for receiving command, displaying parameter. Outer dimension of EN-KB6 is as Fig.4-2:

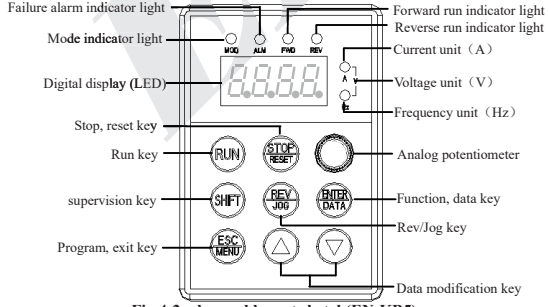



**Fig.4-2 keypad layout sketch(EN-KB5)**

### 4.2.2 Keypad function description

There are 8 key-presses and one adjusting button for analog potentiometer on inverter Keypad and function definition of each key is as shown in table 4-1:

**Table 4-1 keypad function table**

| key | name | Function description |
|---|---|---|
| ESC MENU | program/exit key | Enter into or exit programming state |
| SHIFT | shift/supervision key | Can choose modification digit of set data under editor state；can switch display status supervision parameter under other state. |
| ENTER DATA | function/data key | Enter into the next menu or data confirmation |
| REV JOG | Rev/Jog key | Under keypad mode, to press this key can set reverse run or Jog run according to the 2nd bit of parameter F0.03 |
| RUN | Run key | Enter into reverse run under keypad mode |
| STOP RESET | Stop/reset key | In common run status the inverter will be stopped according to set mode after pressing this key if run command channel is set as keypad stop effective mode. The inverter will be reset and resume normal stop status after pressing this key when the inverter is in malfunction status. |
| | Analog potentiometer | Be used to set frequency; when F0.00=0 value set by analog potentiometer is frequency provision |
| | Increasing button | To increase data or function code (to press it continuously can improve increasing speed) |
| | Decreasing button | To decrease data or function code (to press it continuously can improve decreasing speed) |

### 4.2.3 LED and indicator light

4 status indicator light: they are MOD（mode）, ALM（alarm）, FWD（forward run）, REV（reverse run）from left to right on the LED, their respective indicating meaning is as shown in table 4-2.

**Table 4-2 status indicator light description**

| item | | | Function description | |
|---|---|---|---|---|
| Display function | Digital display | | Display current run status parameter and set parameter | |
| | Status indicator light | A,Hz,V | unit for relevant current digital displayed physical parameter(for current is A, for voltage is V，for frequency is Hz) | |
| | | MOD | This indicator light is lit in nonsupervision status and extinguished if no key pressed for a minute, then come back to | |
| | | ALM | Alarm indicator light, indicate that the inverter is in over current or over voltage suppressing status or failure alarm status | |
| | | FWD | Forward run indicator light，indicate that the inverter output forward phase order and the connected motor rotate in forward direction | The inverter work in DC brake status if FWD, REV indicator light is lit at the same time |

| | | | | |
|---|---|---|---|---|
| | | REV | reverse run indicator light, indicate that the inverter output reversephase order and the connected motor rotate in reverse direction | |

### 4.2.4 Key board display status

EDS800 keypad display status is classified as waiting status parameter display, function code parameter editing status display, malfunction alarm status display, run status parameter display in total 4 kinds of status. LED indicator light will all be lit after the inverter electrified, and digital display LED will display character "-EN-", then enter into set frequency display. As shown in Fig.4-3 a.

**(1) waiting parameter display status**

The inverter is in waiting status and waiting status supervision parameter is displayed on keyboard, normally parameter F3.28 decide which status supervision parameter to be displayed. As shown in Fig.4-3 b，the unit is indicated by rightward unit indicator light.

To press SHIFT key，it can display different waiting status supervision parameter circularly(display 15 kinds of supervision parameter of C group acquiescently，whether the last 7 kinds of supervision parameter are displayed is difined by function code F2.11，F2.12, for detail please see C group status supervision parameter in function parameter schedule graph of chapter 5).

**(2) run parameter display status**

The inverter enters into run status when receiving effective run command and normally parameter F3.28 decide which status supervision parameter to be displayed on the keypad. As shown in Fig.4-3 c，unit is displayed by rightward unit indicator light.

To press SHIFT key，can display run status supervision parameter circularly (defined by function code F2.11 and F2.12). During displaying, can press ENTER DATA to switch to initial supervision parameter decided by F3.28, otherwise will display the last displayed parameter all along.


Fig.a electrification, display-EN-


Fig.b waiting status, display waiting status parameter


Fig.c run status, display run status parameter

**Fig.4-3 inverter electrification, waiting, run status display**

**(3) Failure alarm display status**

The inverter enters into failure alarm display status upon detecting failure signal and display failure code sparklingly (as shown in Fig.4-4);


**Fig.4-4 failure alarm**

To press SHIFT key can look over relative parameter after stopping running; Can press ESC MENU key to enter into program status to see about Fd group parameter if want to search failure information.

Can carry on failure restoration by STOP RESET key, control terminal or communication command on the keypad after troubleshooting. Keep displaying failure code if failure exist continuously.

For some serious failure, such as inverse module protect, over current, over voltage etc., must not carry on failure reset forcibly to make the inverter run again without failure elimination confirmed. Otherwise have danger of damaging the inverter!

**(4) function code editing status**

Under waiting, run or failure alarm status, press ESC MENU key, can enter into editing status(If user password is set, can enter into editing status after inputting the password, see also FF.00 description and Fig.4-10), and editing status is displayed according to three classes menu mode, as shown in Fig. 4-5. To press ENTER DATA key can enter into one class by one class. Under function parameter display status, to press ENTER DATA key to carry on parameter storage operation; To press ESC MENU key can only come back to upper class menu without stroring modified parameter.

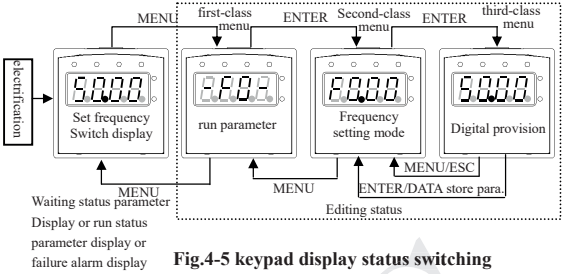



**Fig.4-5 keypad display status switching**

**(5) Special display function**

You can change set frequency under supervision state directly when keypad potentiometer is effective (F0.00=0) or keypad digital setting is effective (F0.00=1). Here the inverter displays set frequency if it's stop or displays output frequency if it's running. After set frequency stops changing for 1 second the inverter will go back to normal display status.

### 4.2.5 Method for operating keypad

Can carry on various operation to the inverter through keypad，for example:

**(1) status parameter display switching:**

After pressing key (SHIFT)，display C group status supervision parameter; after displaying one supervision parameter code for 1 second, will display this parameter value automatically.

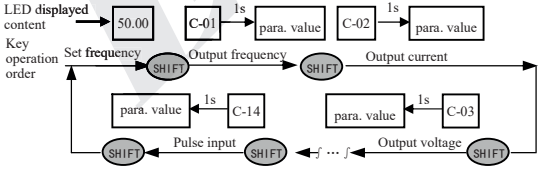



**Fig. 4-6 waiting status parameter display operating example**

Description:

1> All status parameters C-00～C-14 can be displayed when the inverter leaves factory. You can make a change by modifying function code F2.11, F2.12 if you want to, for detail please refer to F2.11, F2.12function code description.

2> Can press (ENTER DATA) key to switch into constant supervision C-01 display status directly when the user see about status supervision parameter.

**(2) function code parameter setting**

Take function code F2.06 modified from 5.00Hz to 6.00Hz as example. Boldface in Fig.4-7 shows flickering digit.

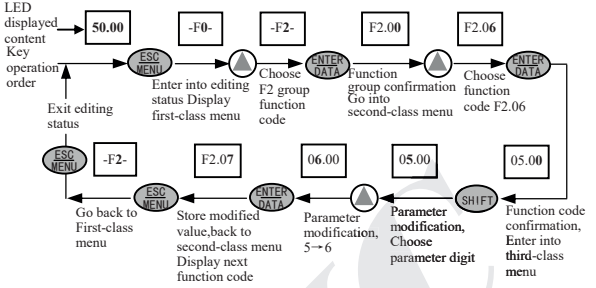



**Fig.4-7 example for parameter setting and modification**

Description: under third-class menu, if the parameter has no blinking digit，this function code can't be modified，possible reasons are as follows:

a. This function code shouldn't be modified, for example actual detected status parameter, run record parameter etc.;

b. This function code can't be modified under run status and can be changed after stopping running;

c. Parameter protected. All the function code can't be modified when function code F2.13=1 or 2，in order to avoid wrong operation. Need to set the function code F2.13 to 0 if you want to edit function code parameter.

**(3) specified frequency adjustment for common run**

Take example modifying specified frequency from 50.00Hz to 40.00Hz at F0.00=0 during running for explanation.

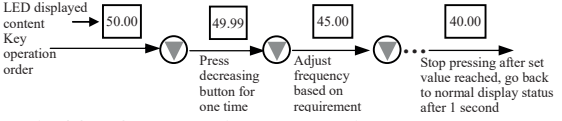



**Fig. 4-8 set frequency adjustment operation example**

(4) jog run operation

For example, keypad as current run command channel, jog run frequency 5Hz, waiting status.

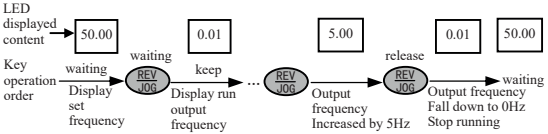



**Fig.4-9 jog run operating example**

**(5) operation for entering to function code editing status after setting user password**

"user password"FF.00 is set to"6886". Boldfaced digit in Fig.4-7 shows blinking bit.

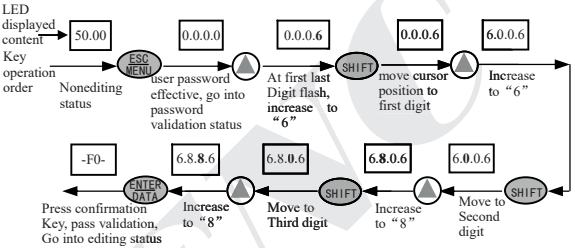



**Fig.4-10 inputting password to go into function code operation**

**(6) See about failure parameter under failure status**

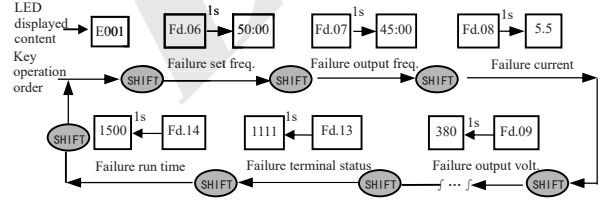



**Fig.4-11 failure status searching operation example**

Description:

1> If press SHIFT key under failure status the user can see about Fd group function code parameter, search range Fd.06～Fd.14，LED first display function code number when the user press SHIFT key and display parameter digit of this function code after 1s.

2> When the user see about failure parameter，can press ENTER DATA key directly to switch back to failure alarm display status (E0XX)

**(7) keypad key-press locking operation**

Under unlocked keypad situation，press ESC MENU key for 5s to lock the keypad. For detailed operation please refer to 2nd bit of F2.13 function code.

**(8) keypad key-press unlocking operation**

Under locked keypad situation，press ESC MENU key for 5s to unlock the keypad.

## 4.3 Inverter electrification

### 4.3.1 Check before electrification

Please carry on wiring based on operation requirement provided in “inverter wiring” of this Service manual.

### 4.3.2 First electrification

Close input side AC power supply switch after correct wiring and power supply confirmed, electrify the inverter and keypad LED display “-EN -”, contactor closed normally, LED displayed set frequency shows that electrification is finished. First electrification operation process is shown as Fig. 4-12.

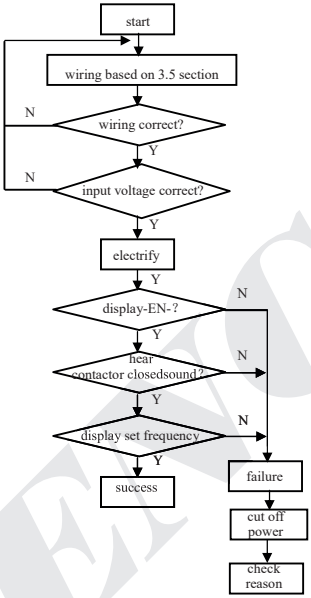



**Fig. 4-12 first electrification operation flow**

# 5 Function parameter schedule graph

## 5.1 Symbol description

× ---- parameter can't be changed in process of running

○ ---- parameter can be changed in process of running

* ---- read-only parameter, unmodifiable

## 5.2 Function parameter schedule graph

| F0 –basic run function parameter group | | | | | |
|---|---|---|---|---|---|
| function code | name | Set range | unit | Factory default | Modificat-ion |
| F0.00 | Frequency input channel selection | 0: keypad analog potentiometer setting<br>1: keypad digital setting<br>2: terminal UP/DOWN adjust setting (stored after power off)<br>3: serial port setting<br>4: VCI analog setting (VCI-GND)<br>5: CCI analog setting (CCI-GND)<br>6: reserved<br>7: terminal pulse (PULSE) setting<br>8: combination setting<br>9: terminal UP/DOWN adjust setting (not stored after power off)<br>10:provision serial port (stored after power off)<br>11:terminal PWM pulse setting freq. | 1 | 1 | ○ |
| F0.01 | Freq. digit setting | Lower limit Freq.~upper limit Freq. | 0.01Hz | 50.00Hz | ○ |
| F0.02 | Run command channel selection | 0: keypad run control<br>1: terminal run command control (keypad stop command ineffective)<br>2: terminal run command control (keypad stop command effective)<br>3: serial port run command control (keypad stop command ineffective)<br>4: serial port run command control (keypad stop command effective) | 1 | 0 | ○ |
| F0.03 | Run direction setting | 1st bit: 0, forward run; 1, reverse run<br>2nd bit: 0, reverse run allowed<br>1, reverse run banned<br>3rd bit: REV/JOG key selection<br>0: as reverse run key<br>1: as jog key | 1 | 00 | ○ |
| F0.04 | Acce/Dece mode selection | 0: linear accelerating decelerating mode<br>1: S curve accelerating decelerating mode | 1 | 0 | × |
| F0.05 | S curve start section time | 10.0（%）—50.0（%）(Acce/Dece time)<br>F0.05+F0.06≤90（%） | 0.1(%) | 20.0(%) | ○ |

| | | | | | |
|---|---|---|---|---|---|
| F0.06 | S curve risetime | 10.0（%）－70.0（%）(Acce/Dece time)<br>F0.05+F0.06≤90（%） | 0.1(%) | 60.0(%) | ○ |
| F0.07 | accelerating decelerating time unit | 0: second<br>1: minute | 1 | 0 | × |
| F0.08 | Acce time 1 | 0.1－6000.0 | 0.1 | 20.0 | ○ |
| F0.09 | Dece time 1 | 0.1－6000.0 | 0.1 | 20.0 | ○ |
| F0.10 | Upper limit freq. | Lower limit freq.－400.00Hz | 0.01Hz | 50.00Hz | × |
| F0.11 | Lower limit freq. | 0.00－Upper limit freq. | 0.01Hz | 0.00Hz | × |
| F0.12 | Lower limit freq. run mode | 0: run at lower limit freq.<br>1: stop running | 1 | 0 | × |
| F0.13 | Torque boost mode | 0: manual boost<br>1: automatic boost | 1 | 0 | ○ |
| F0.14 | Torque boost | 0.0－20.0（%） | 0.1(%) | 4.0(%) | ○ |
| F0.15 | V/F curve setting | 0: constant torque curve<br>1: degressive torque curve 1（the 2.0nd power）<br>2: degressive torque curve 2（the 1.7th power）<br>3: degressive torque curve 3（the 1.2th power）<br>4: End-user sets VF curve himself(determined by F2.37~F2.44)<br>F2.37 VF Freq. value 0<br>F2.38 VF voltage value 0<br>F2.39 VF Freq. value 1<br>F2.40 VF voltage value 1<br>F2.41 VF Freq. value 2<br>F2.42 VF voltage value 2<br>F2.43 VF Freq. value 3<br>F2.44 VF voltage value 3<br>Remark: VF frequency and voltage can't be 0 or maximum | 1<br><br><br><br><br><br><br><br><br><br><br><br><br>0.01Hz<br>0.01%<br>0.01Hz<br>0.01%<br>0.01Hz<br>0.01%<br>0.01Hz<br>0.01% | 0<br><br><br><br><br><br><br><br><br><br><br><br><br>0.50Hz<br>2.00%<br>20.00Hz<br>38.00%<br>25.00Hz<br>48.00%<br>40.00Hz<br>80.00% | × |
| F0.16 | reserved | | | | |

| F1 –start-up, stop, brake function parameter group | | | | | |
|---|---|---|---|---|---|
| Function code | name | Set range | unit | Factory default | Modification |
| F1.00 | Start-up run mode | 0: start at start-up freq.<br>1: first brake, then start at start-up freq.<br>2: reserved | 1 | 0 | × |
| F1.01 | start-up freq. | 0.0－10.00Hz | 0.01Hz | 0.00Hz | ○ |
| F1.02 | start-up freq. duration | 0.0－20.0S | 0.1s | 0.0s | ○ |
| F1.03 | Zero freq. DC braking volt. | 0－15（%） | 1 | 0 | ○ |
| F1.04 | Zero freq. DC braking time | 0.0－20.0S | 0.1s | 0.0s | ○ |
| F1.05 | Stop mode | 0: Dec stop<br>1: free stop<br>2: Dec＋DC brake stop | 1 | 0 | × |
| F1.06 | DC brake initiative freq. when stop running | 0.0－15.00Hz | 0.01Hz | 0.00Hz | ○ |
| F1.07 | DC brake time when stop running | 0.0－20.0s | 0.1s | 0.0s | ○ |
| F1.08 | DC brake voltage when stop running | 0－15（%） | 1 | 0 | ○ |

| F2 –auxiliary run function parameter group | | | | | |
|---|---|---|---|---|---|
| Function code | name | Set range | unit | Factory default | modif-ication |
| F2.00 | Analog filter time constant | 0.00－30.00s | 0.01s | 0.20s | ○ |
| F2.01 | Forward reverse run dead-section time | 0.0－3600.0s | 0.1s | 0.1s | ○ |
| F2.02 | Automatic energy save run | 0: no action<br>1: action | 1 | 0 | × |
| F2.03 | AVR function | 0: no action<br>1: action all the time<br>2: no action only during Dec | 1 | 0 | × |
| F2.04 | Slip frequency compensation | 0～150(%)0-no slip frequency compensation | 1 | 0 | × |
| F2.05 | Carrier wave freq. | 2－15.0K | 0.1K | depend on machine type | × |
| F2.06 | Jog run frequency | 0.10－50.00Hz | 0.01Hz | 5.00Hz | ○ |
| F2.07 | Jog Acc time | 0.1－60.0s | 0.1s | 20.0s | ○ |
| F2.08 | Jog Dec time | 0.1－60.0s | 0.1s | 20.0s | ○ |
| F2.09 | Frequency input channel combination | 0: VCI＋CCI<br>1: VCI－CCI<br>2: reserved<br>3: reserved<br>4: reserved<br>5: reserved<br>6: exterior pulse provision＋CCI<br>7: exterior pulse provision－CCI<br>8: reserved<br>9: reserved<br>10: reserved<br>11: reserved<br>12: reserved<br>13: VCI, CCI any nonzero value effective, VCI preferred<br>14: reserved<br>15: RS485+CCI<br>16: RS485-CCI<br>17: RS485+VCI<br>18: RS485-VCI<br>19: RS485+keypad potentiometer<br>20: RS485- keypad potentiometer<br>21: VCI+ keypad potentiometer<br>22: VCI- keypad potentiometer<br>23: CCI+ keypad potentiometer<br>24: CCI- keypad potentiometer<br>25: VCI*QWG（keypad potentiometer）<br>26: reserved<br>27: reserved<br>28: reserved | 1 | 0 | × |
| F2.10 | Principal subordinate | 0（%）－500（%） | 1(%) | 100(%) | |

| | | | | | |
|---|---|---|---|---|---|
| | Machine communication frequency provision proportion | | | | |
| F2.11 | LED display control 1 | 0000-1111<br>first bit: running time<br>0: not display<br>1: display<br>second bit: accumulative time<br>0: not display<br>1: display<br>third bit: input terminal status<br>0: not display<br>1: display<br>kilobit(fourth bit):<br>output terminal status<br>0: not display<br>1: display | 1 | 1111 | ○ |
| F2.12 | LED display control 2 | 0000-1111<br>first bit: analog input VCI<br>0: not display<br>1: display<br>second bit: reserved<br>third bit: analog input CCI<br>0: not display<br>1: display<br>kilobit(fourth bit): exterior pulse input<br>0: not display<br>1: display | 1 | 1111 | ○ |
| F2.13 | Parameter operation control | LED 1st bit:<br>0: all parameter allowed to be modified<br>1: except this parameter，all other parameter not allowed to be modified<br>2: except F0.01 and this parameter，all other parameter not allowed to be modified<br>LED 2nd bit:<br>0: no action<br>1: restore default value<br>2: clear history failure record<br>LED 3rd bit（After setting, It will be valid after pressing MENU key for 5 seconds and entering into Locc status）:<br>0: lock all buttons<br>1: lock all buttons but not STOP key<br>2: lock all buttons but not ▲ ▼, STOP key<br>3: lock all buttons but not RUN, STOP key<br>4: lock all buttons but not SHIFT, STOP key | 1 | 000 | × |
| F2.14 | Communication configuration | LED 1st bit: baud rate selection<br>0: 1200BPS<br>1: 2400BPS<br>2: 4800BPS<br>3: 9600BPS<br>4: 19200BPS | 1 | 003 | × |

| | | | | | |
|---|---|---|---|---|---|
| | | 5: 38400BPS<br>LED 2nd bit: data format<br>0: 1－8－1format, no checkout<br>1: 1－8－1 format, even checkout<br>2: 1－8－1 format, odd checkout<br>LED 3rd bit：response selection<br>0：Respond to host command and reply to data packet<br>1：Respond to host command, but not reply | | | |
| F2.15 | Local address | 0－127，0 is broadcast address.. | 1 | 1 | × |
| F2.16 | Communication overtime | 0.0 － 1000.0s ， 0 means communication timeout detection invalid. | 0.1s | 0.0s | × |
| F2.17 | Local responsion delay | 0－200ms | 1ms | 5ms | × |
| F2.18 | Acce time 2 | 0.1－6000.0 | 0.1 | 20.0 | ○ |
| F2.19 | Dece time 2 | 0.1－6000.0 | 0.1 | 20.0 | ○ |
| F2.20 | Acce time 3 | 0.1－6000.0 | 0.1 | 20.0 | ○ |
| F2.21 | Dece time 3 | 0.1－6000.0 | 0.1 | 20.0 | ○ |
| F2.22 | Acce time 4 | 0.1－6000.0 | 0.1 | 20.0 | ○ |
| F2.23 | Dece time 4 | 0.1－6000.0 | 0.1 | 20.0 | ○ |
| F2.24 | Acce time 5 | 0.1－6000.0 | 0.1 | 20.0 | ○ |
| F2.25 | Dece time 5 | 0.1－6000.0 | 0.1 | 20.0 | ○ |
| F2.26 | Acce time 6 | 0.1－6000.0 | 0.1 | 20.0 | ○ |
| F2.27 | Dece time 6 | 0.1－6000.0 | 0.1 | 20.0 | ○ |
| F2.28 | Acce time 7 | 0.1－6000.0 | 0.1 | 20.0 | ○ |
| F2.29 | Dece time 7 | 0.1－6000.0 | 0.1 | 20.0 | ○ |
| F2.30 | Multisection freq. 1 | Lower limit freq.－upper limit freq. | 0.01Hz | 5.00Hz | ○ |
| F2.31 | Multisection freq. 2 | Lower limit freq.－upper limit freq. | 0.01Hz | 10.00Hz | ○ |
| F2.32 | Multisection freq. 3 | Lower limit freq.－upper limit freq. | 0.01Hz | 20.00Hz | ○ |
| F2.33 | Multisection freq. 4 | Lower limit freq.－upper limit freq. | 0.01Hz | 30.00Hz | ○ |
| F2.34 | Multisection freq. 5 | Lower limit freq.－upper limit freq. | 0.01Hz | 40.00Hz | ○ |
| F2.35 | Multisection freq. 6 | Lower limit freq.－upper limit freq. | 0.01Hz | 45.00Hz | ○ |
| F2.36 | Multisection freq. 7 | Lower limit freq.－upper limit freq. | 0.01Hz | 50.00Hz | ○ |
| F2.37 | Multisection freq. 8 | Lower limit freq.－upper limit freq. | 0.01Hz | 5.00Hz | ○ |
| | VF frequency value 0 | 0.00－F2.39 | 0.01Hz | 0.50Hz | ○ |
| F2.38 | Multisection freq. 9 | Lower limit freq.－upper limit freq. | 0.01Hz | 10.00Hz | ○ |
| | VF voltage value 0 | 0.00－F2.40 | 0.01% | 2.00% | ○ |
| F2.39 | Multisection freq. 10 | Lower limit freq.－upper limit freq. | 0.01Hz | 20.00Hz | ○ |
| | VF frequency value 1 | F2.37－F2.41 | 0.01Hz | 20.00Hz | ○ |
| F2.40 | Multisection freq. 11 | Lower limit freq.－upper limit freq. | 0.01Hz | 30.00Hz | ○ |
| | VF voltage value 1 | F2.38－F2.42 | 0.01% | 38.00% | ○ |
| F2.41 | Multisection freq. 12 | Lower limit freq.－upper limit freq. | 0.01Hz | 40.00Hz | ○ |
| | VF frequency value 2 | F2.39－F2.43 | 0.01Hz | 25.00Hz | ○ |

| | | | | | |
|---|---|---|---|---|---|
| F2.42 | Multisection freq. 13 | Lower limit freq.—upper limit freq. | 0.01Hz | 45.00Hz | ○ |
| | VF voltage value 2 | F2.40—F2.44 | 0.01% | 48.00% | ○ |
| F2.43 | Multisection freq. 14 | Lower limit freq.—upper limit freq. | 0.01Hz | 50.00Hz | ○ |
| | VF frequency value 3 | F2.41—high limit frquency | 0.01Hz | 40.00Hz | ○ |
| F2.44 | Multisection freq. 15 | Lower limit freq.—upper limit freq. | 0.01Hz | 50.00Hz | ○ |
| | VF voltage value 3 | F2.42—100.0% (rated voltage) | 0.01% | 80.00% | ○ |
| F2.45 | Jumping freq. 1 | 0.00—400.00Hz | 0.01Hz | 0.00Hz | × |
| F2.46 | Jumping freq. 1 range | 0.00—30.00Hz | 0.01Hz | 0.00Hz | × |
| F2.47 | Jumping freq. 2 | 0.00—400.00Hz | 0.01Hz | 0.00Hz | × |
| F2.48 | Jumping freq. 2 range | 0.00—30.00Hz | 0.01Hz | 0.00Hz | × |
| F2.49 | Jumping freq. 3 | 0.00—400.00Hz | 0.01Hz | 0.00Hz | × |
| F2.50 | Jumping freq. 3 range | 0.00—30.00Hz | 0.01Hz | 0.00Hz | × |
| F2.51 | Setting run time | 0—65535 hours | 1 | 0 | ○ |
| F2.52 | Accumulative run time | 0—65535 hours | 1 | 0 | * |
| F2.53 | reserved | | | | |

**F3 group –closed-loop run function parameter group**

| Function code | name | Set range | unit | Factory default | modif-ication |
|---|---|---|---|---|---|
| F3.00 | Closed-loop run control selection | 0: closed-loop control ineffective<br>1: PID closed-loop control effective<br>2: constant pressure water supply PID control specialized (one tows one) | 1 | 0 | × |
| F3.01 | Provision channel selection | 0: digital provision<br>1: VCI analog 0—10V voltage provision<br>2: CCI analog provision<br>3: keypad potentiometer provision | 1 | 0 | ○ |
| F3.02 | Feedback channel selection | 0: VCI analog input voltage 0—10V<br>1: CCI analog input<br>2: VCI+CCI<br>3: VCI-CCI<br>4: Min { VCI, CCI }<br>5: Max { VCI, CCI }<br>6: pulse feedback | 1 | 0 | ○ |
| F3.03 | Specified value digital setting | 0.000~9.999V(setF3.00=1,F3.21=9.999) | 0.001 | 0.200 | ○ |
| | Target pressure value setting | 0.000~F3.21Mpa(setF3.00=2) | 0.001 | 0.200 | ○ |
| F3.04 | Minimum specified value | 0.0—maximum specified value; percentage relative to 10.00V | 0.1 (%) | 0.0 (%) | ○ |
| F3.05 | feedback value responding to minimum specified value | 0.0—100.0(%) | 0.1 (%) | 0.0 (%) | ○ |
| F3.06 | maximum specified | Minimum specified value—100.0 (%) | 0.1 (%) | 100.0(%) | |

| | | | | | |
|---|---|---|---|---|---|
| | value | | | | |
| F3.07 | feedback value responding to maximum specified value | 0.0－100.0（%） | 0.1(%) | 100.0(%) | ○ |
| F3.08 | proportion gain Kp | 0.000－9.999 | 0.001 | 0.150 | ○ |
| F3.09 | Integral gain Ki | 0.000－9.999 | 0.001 | 0.150 | ○ |
| F3.10 | Differential gain Kd | 0.000－9.999 | 0.001 | 0.000 | ○ |
| F3.11 | Sampling cycle T | 0.01－1.00s | 0.01s | 0.10s | ○ |
| F3.12 | Deviation margin | 0.0－20.0% Relative to the percentage of set value. | 0.1(%) | 2.0(%) | ○ |
| F3.13 | Integral separation PID adjusting threshold | 0.0－100.0% | 0.1(%) | 100.0(%) | ○ |
| F3.14 | Closed-lop preset frequency | 0－upper limit frequency | 0.01Hz | 0.00Hz | ○ |
| F3.15 | Closed-loop preset frequency holding time | 0.0-6000s | 0.1s | 0.0s | ○ |
| F3.16 | Sleep frequency threshold | 0.00－400.00Hz | 0.01Hz | 0.01Hz | ○ |
| F3.17 | Revival frequency threshold | 0.00－400.00Hz | 0.01Hz | 0.01Hz | ○ |
| F3.18 | Sleep delay time | 0.0－6000.0s | 0.1s | 0.0s | ○ |
| F3.19 | Revival delay time | 0.0－6000.0s | 0.1s | 0.0s | ○ |
| F3.20 | Reserved | | | | |
| F3.21 | Long-distance pressure meter range | 0.001－9.999Mpa | 0.001 | 1.000 | ○ |
| F3.22 | Reserved | | | | |
| F3.23 | Reserved | | | | |
| F3.24 | Reserved | | | | |
| F3.25 | Reserved | | | | |
| F3.26 | Water supply supervision parameter display | 0: C-11, C-12 denote voltage value of VCI, CCI<br>1: C-11, C-12 denote PID specified pressure and feedback pressure | 1 | 0 | ○ |
| F3.27 | Closed-loop adjusting characteristic | 0: Forward function<br>1: Reverse function | | 0 | ○ |
| F3.28 | LED initial supervision parameter selection | 0: set frequency<br>1: output frequency<br>2: output current<br>3: output voltage<br>4: DC bus bar voltage<br>5: motor speed<br>6: heat sink temperature<br>7: run time<br>8: accumulative run time<br>9: input terminal status<br>10: output terminal status<br>11: analog input VCI/PID provision | | 1 | ○ |

| | | | | | |
|---|---|---|---|---|---|
| | | 12: analog input CCI/PID feedback<br>13: analog input YCI<br>14: exterior pulse inputs | | | |
| F3.29 | YCI run-in delay time | 0.0－9.999s | 0.1s | 0.0s | ○ |
| | PID feedback signal loss detection | 0.0－9.999s | 0.1s | 0.0s | ○ |
| F3.30 | Failure relay TA, TB, TC function selection | 0: inverter running（RUN）<br>1: frequency arriving signal（FAR）<br>2: frequency level detect signal (FDT1)<br>3: reserved<br>4: overload warning alarm signal (OL)<br>5: output frequency reach high limit（FHL）<br>6: output frequency reach low limit（FLL）<br>7: inverter under voltage blockage stop (LU)<br>8: external failure stop-running（EXT）<br>9: inverter zero speed running<br>10: PLC running<br>11: simple PLC section running finished<br>12: PLC finish a cycle running<br>13: reserved<br>14: inverter ready to run (RDY)<br>15: inverter failure<br>16: traverse high and low limit restriction<br>17: interior counter reach final value<br>18: interior counter reach specified value<br>19: set run time arriving<br>20: interior timing arriving<br>21: reserved<br>22:FWD running<br>23: REV running<br>24: reserved | | 15 | ○ |
| F3.31 | Reserved | | | | |

| F4 –simple PLC function parameter group | | | | | |
|---|---|---|---|---|---|
| Function code | name | Set range | unit | Factory default | modif-ication |
| F4.00 | Simple PLC running setting | LED first bit:<br>0: no action<br>1: stop after single circulation<br>2: keep final value after single circulation<br>3: consecutive circulation<br>LED second bit:<br>0: start again from first section<br>1: continue to run at mid-section frequency<br>LED third bit: PLC run time unit<br>0: second<br>1: minute<br>LED 4th bit: PLC running state power off treatment method<br>0：power off no memory | 1 | 0000 | × |

| | | | | | |
|---|---|---|---|---|---|
| | | 1：Running with memory when power off, renew running after power on (terminal control exceptional)<br>2：Running with memory when power off, automotive running after power on | | | |
| F4.01 | Section 1 setting | 000－621<br>LED first bit: frequency setting<br>0: multisection freq. i (i=1~7)<br>1: freq. determined by F0.00 function code<br>LED second bit: run direction selection<br>0: forward run<br>1: reverse run<br>2: determined by run command<br>LED third bit: Acc/Dec time selection<br>0: Acc/Dec time 1<br>1: Acc/Dec time 2<br>2: Acc/Dec time 3<br>3: Acc/Dec time 4<br>4: Acc/Dec time 5<br>5: Acc/Dec time 6<br>6: Acc/Dec time 7 | 1 | 000 | ○ |
| F4.02 | Section 1 run time | 0－6000.0 | 0.1 | 10.0 | ○ |
| F4.03 | Section 2 setting | 000－621 | 1 | 000 | ○ |
| F4.04 | Section 2 run time | 0－6000.0 | 0.1 | 10.0 | ○ |
| F4.05 | Section 3 setting | 000－621 | 1 | 000 | ○ |
| F4.06 | Section 3 run time | 0－6000.0 | 0.1 | 10.0 | ○ |
| F4.07 | Section 4 setting | 000－621 | 1 | 000 | ○ |
| F4.08 | Section 4 run time | 0－6000.0 | 0.1 | 10.0 | ○ |
| F4.09 | Section 5 setting | 000－621 | 1 | 000 | ○ |
| F4.10 | Section 5 run time | 0－6000.0 | 0.1 | 10.0 | ○ |
| F4.11 | Section 6 setting | 000－621 | 1 | 000 | ○ |
| F4.12 | Section 6 run time | 0－6000.0 | 0.1 | 10.0 | ○ |
| F4.13 | Section 7 setting | 000－621 | 1 | 000 | ○ |
| F4.14 | Section 7 run time | 0－6000.0 | 0.1 | 10.0 | ○ |

| F5 –terminal correlative function parameter group | | | | | |
|---|---|---|---|---|---|
| Function code | name | Set range | unit | Factory default | modif-ication |
| F5.00 | Input terminal X1 function selection | 0: leave control terminal unused<br>1: multisection speed control terminal<br>2: multisection speed control terminal<br>3: multisection speed control terminal<br>4: multisection speed control terminal<br>5: external forward run jog control<br>6: external reverse run jog control | 1 | 0 | × |

| | | | | | |
|---|---|---|---|---|---|
| | | 7: Acc/Dec time option terminal 1<br>8: Acc/Dec time option terminal 2<br>9: Acc/Dec time option terminal 3<br>10: external device failure input<br>11: external reset input<br>12: free stop input<br>13: external stop-running order<br>14: stop DC braking input command DB<br>15: inverter run banned<br>16: frequency increasing control (UP)<br>17: frequency degression control (DOWN)<br>18: Acc/Dec ban command<br>19: three-line run control<br>20: closed-loop ineffective<br>21: PLC ineffective<br>22: simple PLC pause control<br>23: PLC stop status reset<br>24: frequency provision channel option 1<br>25: frequency provision channel option 2<br>26: frequency provision channel option 3<br>27: frequency switched to CCI<br>28: command switched to terminal<br>29: run command channel option 1<br>30: run command channel option 2<br>31: run command channel option 3<br>32: traverse jump-in<br>33: external interruption input<br>34: interior counter reset end<br>35: interior counter triggering end<br>36: interior timer reset end<br>37: interior timer triggering end<br>38: pulse frequency input<br>(only effective for X5)<br>39: reserved<br>40: reserved<br>41: reserved<br>42: reserved | | | |
| F5.01 | Input terminal X2 function selection | Same as above | | | × |
| F5.02 | Input terminal X3 function selection | Same as above | | | × |
| F5.03 | Input terminal X4 function selection | Same as above | | | × |
| F5.04 | Input terminal X5 function selection | Same as above | | | × |
| F5.05 | reserved | | | | |
| F5.06 | reserved | | | | |
| F5.07 | reserved | | | | |

| | | | | | |
|---|---|---|---|---|---|
| F5.08 | FWD/REV run mode selection | 0: double-line control mode 1<br>1: double-line control mode 2<br>2: three-line control mode 1<br>3: three-line control mode 2 | 1 | 0 | × |
| F5.09 | UP/DOWN velocity | 0.01－99.99Hz/s | 0.01Hz/s | 1.00Hz/s | ○ |
| F5.10 | Open circuit collector output terminal OC output setting | 0: inverter running（RUN）<br>1: frequency arriving signal（FAR）<br>2: frequency level detect signal (FDT1)<br>3: reserved<br>4: overload warning alarm signal (OL)<br>5: output frequency reach high limit（FHL）<br>6: output frequency reach low limit（FLL）<br>7: inverter under voltage blockage stop (LU)<br>8: external failure stop-runnin（EXT）<br>9: inverter zero rotate speed running<br>10: PLC running<br>11: simple PLC section running finished<br>12: PLC finish a cycle running<br>13: reserved<br>14: inverter ready to run (RDY)<br>15: inverter failure<br>16: traverse high and low limit restriction<br>17: interior counter reach final value<br>18: interior counter reach specified value<br>19: set run time arriving<br>20: interior timing arriving<br>21: reserved<br>22:FWD running<br>23: REV running<br>24: reserved | 1 | 0 | × |
| F5.11 | reserved | | | | |
| F5.12 | reserved | | | | |
| F5.13 | reserved | | | | |
| F5.14 | Frequency arriving (FAR) checkout scope | 0.00－50.00Hz | 0.01Hz | 5.00Hz | ○ |
| F5.15 | FDT1 (frequency level) electric level | 0.00－high limit frequency | 0.01Hz | 10.00Hz | ○ |
| F5.16 | FDT1 lag | 0.00－50.00Hz | 0.01Hz | 1.00Hz | ○ |
| F5.17 | Analog output (AO1) selection | 0: output frequency(0－high limit frequency)<br>1: set frequency(0－high limit frequency)<br>2: output current(0－2×rated current)<br>3: output voltage(0－1.2×load motor rated voltage)<br>4: bus-bar voltage(0－800V)<br>5: PID provision (0.00-10.00V)<br>6: PID feedback (0.00-10.00V)<br>7: reserved<br>8: reserved<br>9: reserved | 1 | 0 | ○ |
| F5.18 | Analog output (AO) gain | 0.00－2.00 | 0.01 | 1.00 | |

| | | | | | |
|---|---|---|---|---|---|
| F5.19 | Analog output (AO) offset | 0.00－10.00V | 0.01 | 0.00 | ○ |
| F5.20 | reserved | | | | |
| F5.21 | reserved | | | | |
| F5.22 | reserved | | | | |
| F5.23 | DO terminal output function selection | Same as F5.17 | 1 | 0 | ○ |
| F5.24 | DO maximum pulse output frequency | 0.1－20.0(max. 20KHz)Max. DO port output pulse frequency corresponds to Max. value selected by F5.23 | 0.1KHz | 10.0 | ○ |
| F5.25 | Set interior counting value reaches provision | 0－9999 | 1 | 0 | ○ |
| F5.26 | Specified interior counting value reaches provision | 0－9999 | 1 | 0 | ○ |
| F5.27 | Interior timer setting | 0.1－6000.0s | 0.1 | 60.0 | ○ |

**F6 –traverse special function parameter group**

| Function code | name | Set range | unit | Factory default | modif-ication |
|---|---|---|---|---|---|
| F6.00 | Traverse function selection | 0: traverse function not used<br>1: traverse function used | 1 | 0 | × |
| F6.01 | traverse run mode | LED first bit: jump-in mode<br>0: automatic jump-in mode<br>1: terminal manual jump-in mode<br>LED second bit:<br>0: changing traverse amplitude<br>1: fixed traverse amplitude<br>notice: traverse center frequency input channel set by F0.00 function parameter | 1 | 00 | × |
| F6.02 | Traverse amplitude threshold | 0.0－50.0（%） | 0.1(%) | 0.0(%) | ○ |
| F6.03 | Sudden jumping frequency | 0.0－50.0（%） | 0.1(%) | 0.0(%) | ○ |
| F6.04 | traverse cycle | 0.1－999.9s | 0.1s | 10.0s | ○ |
| F6.05 | Triangle wave risetime | 0.0－98（%）（traverse cycle） | 0.1(%) | 50.0(%) | ○ |
| F6.06 | traverse preset frequency | 0.00－400.00Hz | 0.01Hz | 0.00Hz | ○ |
| F6.07 | traverse preset frequency latency time | 0.0－6000s | 0.1s | 0.0s | ○ |

**F7–frequency provision function parameter group**

| Function code | name | Set range | unit | Factory default | modif-ication |
|---|---|---|---|---|---|
| F7.00 | VCI min. provision | 0.00－F7.02 | 0.01V | 0.00V | ○ |
| F7.01 | VCI min. provision corresponding freq. | 0.00－high limit frequency | 0.01Hz | 0.00Hz | ○ |
| F7.02 | VCI max. provision | 0.00－10.00V | 0.01V | 10.00V | ○ |

| | | | | | |
|---|---|---|---|---|---|
| F7.03 | VCI max. provision corresponding freq. | 0.00－high limit frequency | 0.01Hz | 50.00Hz | ○ |
| F7.04 | CCI min. provision | 0.00－F7.06 | 0.01V | 0.00V | ○ |
| F7.05 | CCI min. provision corresponding freq. | 0.00－high limit frequency | 0.01Hz | 0.00Hz | ○ |
| F7.06 | CCI max. provision | 0.00－10.00V | 0.01V | 10.00V | ○ |
| F7.07 | CCI max. provision corresponding freq. | 0.00－high limit frequency | 0.01Hz | 50.00Hz | ○ |
| F7.08 | Max. Input pulse width | 0.1-999.9ms(whenF0.00=11) | 0.1ms | 100.0ms | ○ |
| F7.09 | Min. provision pulse width | 0.0-F7.11(Max.provision pulse) (whenF0.00=11) | 0.1ms | 0.0ms | ○ |
| F7.10 | min. provision corresponding freq. | 0.00－high limit frequency | 0.01Hz | 0.00Hz | ○ |
| F7.11 | Max. provision pulse width | F7.09(Min.provision pulse)-F7.08(Max.input pulse) | 0.1ms | 100.0ms | ○ |
| F7.12 | max. provision corresponding freq. | 0.00- high limit frequency | 0.01Hz | 50.00Hz | ○ |
| F7.13 | PULSE max. input pulse | 0.1－20.0K | 0.1K | 10.0K | ○ |
| F7.14 | PULSE min. provision | 0.0－F7.16(PULSE max. provision) | 0.1K | 0.0K | ○ |
| F7.15 | PULSE min. provision corresponding freq. | 0.00－high limit frequency | 0.01Hz | 0.00 Hz | ○ |
| F7.16 | PULSE max. provision | F7.14 (PULSE min. provision) －F7.13 (max. input pulse) | 0.1K | 10.0K | ○ |
| F7.17 | PULSE max. provision corresponding freq. | 0.00－high limit frequency | 0.01Hz | 50.00Hz | ○ |

| F8–motor and vector control parameter group | | | | | |
|---|---|---|---|---|---|
| Function code | name | Set range | unit | Factory default | modif-ication |
| F8.00 | reserved | | | | |
| F8.01 | Motor rated voltage | 1－480V | 1V | Depend on device type | × |
| F8.02 | Motor rated current | 0.1－999.9A | 0.1A | Depend on device type | × |
| F8.03 | Motor rated frequency | 1.00－400.00Hz | 0.01Hz | Depend on device type | × |
| F8.04 | Motor rated speed | 1－9999r/min | 1r/min | Depend on device type | × |
| F8.05 | Motor pole | 2-14 | 2 | Depend on device type | × |
| F8.06 | Motor rated power | 0.1－999.9KW | 0.1 | Depend on device type | × |
| F8.07 | reserved | | | | |
| F8.08 | reserved | | | | |
| F8.09 | reserved | | | | |
| F8.10 | reserved | | | | |
| F8.11 | reserved | | | | |
| F8.12 | reserved | | | | |
| F8.13 | reserved | | | | |
| F8.14 | reserved | | | | |
| F8.15 | reserved | | | | |

| | | | | | |
|---|---|---|---|---|---|
| F8.16 | Frequency display offset | 0.00Hz-2.00Hz | 0.01Hz | 0.20Hz | ○ |
| F8.17 | reserved | | | | |

| F9 –protection correlative function parameter group | | | | | |
|---|---|---|---|---|---|
| Function code | name | Set range | unit | Factory default | modif-ication |
| F9.00 | reserved | | | | |
| F9.00 | Instantaneous power off restarting latency time | 0.0－10.0S<br>0 indicates ineffective power off restarting<br>Remark: no automatic reset function for overload and overheating | 0.1S | 0.0S | × |
| F9.01 | Failure self-renew times | 0－10<br>0 shows no automatic reset function<br>Remark: no automatic reset function for overload and overheating | 1 | 0 | × |
| F9.02 | Failure self-renew interval | 0.5－20.0S | 0.1S | 5.0S | × |
| F9.03 | Motor overload protection mode selection | 0: no action<br>1: inverter close off output | 1 | 1 | × |
| F9.04 | Motor overload protection coefficient | 20.0-120.0（%） | 0.1(%) | 100.0(%) | × |
| F9.05 | Overload warning alarm checkout level | 20－200（%） | 1(%) | 130(%) | ○ |
| F9.06 | Overload warning alarmDelay time | 0.0－20.0s | 0.1s | 5.0s | ○ |
| F9.07 | Overvoltage stall selection | 0: ban<br>1: allow | 1 | 1 | × |
| F9.08 | Overvoltage stall point | 120-150(%) | 1(%) | 140(%) | ○ |
| F9.09 | Automatic current limit level | 110－200( %) | 1(%) | 150(%) | × |
| F9.10 | Frequency declining rate during current limiting | 0.00－99.99Hz/s | 0.01Hz/s | 10.00Hz/s | ○ |
| F9.11 | Automatic current limiting action selection | 0: constant speed ineffective<br>1: constant speed effective<br>remark: Acc/Dec always effective | 1 | 0 | × |

| Fd –failure record function parameter group | | | | | |
|---|---|---|---|---|---|
| Function code | name | Set range | unit | Factory default | modif-ication |
| Fd.00 | Previous one time failure record | Previous one time failure record | 1 | 0 | * |
| Fd.01 | Previous two time failure record | Previous two time failure record | 1 | 0 | * |
| Fd.02 | Previous three time failure record | Previous three time failure record | 1 | 0 | * |
| Fd.03 | Previous four time failure record | Previous four time failure record | 1 | 0 | * |
| Fd.04 | Previous five time failure record | Previous five time failure record | 1 | 0 | * |
| Fd.05 | Previous six time failure record | Previous six time failure record | 1 | 0 | * |
| Fd.06 | Set freq. of previous failure | Set freq. of previous failure | 0.01Hz | 0 | * |

| | | | | | |
|---|---|---|---|---|---|
| Fd.07 | output freq. of previous failure | output freq. of previous failure | 0.01Hz | 0 | * |
| Fd.08 | output current of previous failure | output current of previous failure | 0.1A | 0 | * |
| Fd.09 | output voltage of previous failure | output voltage of previous failure | 1V | 0 | * |
| Fd.10 | DC bus-bar voltage of previous failure | DC bus-bar voltage of previous failure | 1V | 0 | * |
| Fd.11 | Load motor speed of previous failure | Load motor speed of previous failure | 1(r/m) | 0 | * |
| Fd.12 | Module temperature of previous failure | Module temperature of previous failure | 1℃ | 0 | * |
| Fd.13 | Input terminal status of previous failure | Input terminal status of previous failure | | 0 | * |
| Fd.14 | Accumulative run time of previous failure | Accumulative run time of previous failure | | 0 | * |

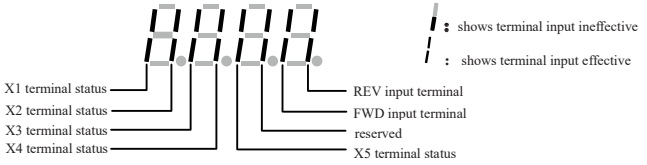
**FF –password and manufacturer function parameter group**

| Function code | name | Set range | unit | Factory default | modif-ication |
|---|---|---|---|---|---|
| FF.00 | User password | 0000－9999 | 1 | 0000 | × |
| FF.01 | Manufacturer password | 0000－9999 | 1 | 0000 | × |
| FF.02<br>FF.0X | Manufacturer's special parameter | | | | |

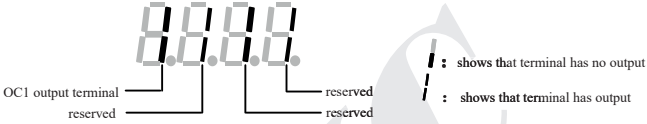
**C –supervision function parameter group**

| Function code | name | Set range | unit | Factory default | modif-ication |
|---|---|---|---|---|---|
| C-00 | Set frequency | Current set frequency | 0.01HZ | | |
| C-01 | Output freq. | Current output freq. | 0.01HZ | | * |
| C-02 | Output current | Virtual value of current output current | 0.1A | | * |
| C-03 | Output voltage | Virtual value of current output voltage | 1V | | * |
| C-04 | DC bus-bar voltage | Current DC bus-bar voltage | 1V | | * |
| C-05 | Load motor speed | Product of output frequency and load motor speed emendation factor | 1(r/m) | | * |
| C-06 | Module temperature | IGBT heat sink temperature | 1℃ | | * |
| C-07 | Run time | Inverter electrification run time | 1h | | * |
| C-08 | accumulative run time | Inverter accumulative run time | 1h | | * |
| C-09 | Input terminal status | Switch value input terminal status | －－ | | * |
| C-10 | output terminal status | Switch value output terminal status | －－ | | * |
| C-11 | Analog input VCI | Analog input value of VCI | V | | * |
| C-12 | Analog input YCI | Analog input value of YCI | V | | * |
| C-13 | reserved | | | | |
| C-14 | Exterior pulse input | Exterior pulse input | 0.1KHz | | * |

(1) input terminal status corresponding relation is as follows:




(2) output terminal status corresponding relation is as follows:



# 6 Detailed function description

Listed column content for parameter function code description in this chapter is as follows:

| code | name | Set range or description | Factory default |
|---|---|---|---|

## 6.1 Basic run function parameter group: F0

| F0.00 | Frequency input channel selection | Range：0～11 | 1 |
|---|---|---|---|

**0: keypad analog potentiometer.** Set running frequency by keypad analog potentiometer.

**1: keypad frequency number setting.** Initial set frequency value is F0.01，can change set frequency by changing F0.01 parameter through keypad，and you can also modify F0.01 by ▲,▼ key.

**2: terminal UP/DOWN adjust set frequency(stored after power off or stop).** Initial set frequency value is the value stored during the last power off time，and you can adjust set running frequency by terminal UP/DOWN.

**3: serial port provision.** Serial port frequency set initial value is F0.01，change set frequency by setting F0.01 through serial port.

**4: VCI analog setting(VCI－GND).**Frequency setting determined by VCI terminal analog voltage，input voltage range: DC0~10V.

**5: CCI analog setting (CCI－GND).** Frequency setting determined by CCI terminal analog voltage /current，input range: DC0~10(CCI switch choose V side)，DC: 4~20mA (CCI switch choose A side).

**6: reserved.**

**7: terminal pulse (PULSE) setting.** Frequency set by terminal pulse( only input through X5，see F5.03, F5.04 definition)，input pulse signal spec: voltage range15~24V；frequency ange 0~20.0KHz.

**8: combination setting.** See function parameter F2.09，set frequency by each channel combination setting.

**9: terminal UP/DOWN adjust set frequency( not stored after power off or stop)**Initial set frequency value is F0.01，and adjust set running frequency by terminal UP/DOWN.

**10:serial port specified(memory after electric off):**when the inverter is disconnected with electic,it will keep the currently running frequency and next time

it will keep the former frequency running the electric on .

**11: terminal PWM pulse set frequency.**

**note** Relation between frequency and input information is determined by function code F7.00~F7.17 when frequency input channel is 4, 5, 6, 7，please see Section 6.8.

| F0.01 | Freq. digital setting | Range：low limit ～high limit | 50.00Hz |
|---|---|---|---|

F0.01 parameter is original set frequency of the inverter when frequency setting channel is defined as number setting (F0.00＝1, 3).

| F0.02 | Run command channel selection | Range：0～4 | 0 |
|---|---|---|---|

**0: keypad run frequency command channel.** Start and stop the inverter by RUN , STOP , REV/JOG key on the keypad.

**1: terminal run command channel(keypad STOP command ineffective).** Start and stop the inverter by exterior control terminal FWD, REV, X1~X5 etc..

**2: terminal run command channel(keypad STOP command effective).** Start and stop the inverter by exterior control terminal FWD, REV, X1~X5 etc..

**3: serial port run command channel(keypad STOP command ineffective).** Start and stop the inverter by RS485 interface.

**4: serial port run command channel(keypad STOP command effective).** Start and stop the inverter by RS485 interface.

The inverter can change run command channel by modifying F0.02 during waiting and running，please confirm that modification is allowed during running on the spot.

| F0.03 | Run direction setting | Range：0, 1 | 100 |
|---|---|---|---|

This function is only effective for keypad and serial port run command channel ineffective for terminal run command channel.

The 1st bit:

**0: inverter forward run**

**1: inverter reverse run**

The 2nd bit:

**0: reverse run allowed**

**1: reverse run banned.** The inverter will stop output when there is reverse run command.

The 3rd bit: **REV/JOG key selection**

**0: as REV key**

**1: as JOG key**

note

If the 2nd bit is set to"1", this function is effective for keypad run command channel, terminal run command channel and serial port run command channel.

| F0.04 | Accelerating decelerating mode selection | Range：0, 1 | 0 |
|---|---|---|---|

**0: linear Acce/Dece mode.** Output frequency increases or decreases according to constant slope, just as shown in Fig.6-1.

**1: S curve Acce/Dece mode.** Output frequency increases or decreases according to S curve, just as shown in Fig.6-2.

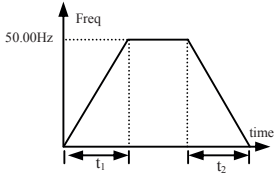



**Fig.6-1 linear Acce/Dece**

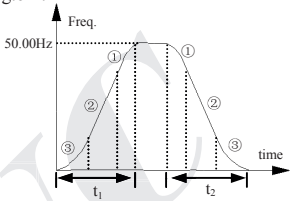



**Fig.6-2 S curve Acce/Dece**

| F0.05 | S curve starting time | Range：10.0(%)－50.0(%) （Acc/Dec time）F0.05＋F0.06≤90(%) | 20.0(%) |
|---|---|---|---|
| F0.06 | S curve rising time | Range：10.0(%)－80.0(%) （Acc/Dec time）F0.05＋F0.06≤90(%) | 60.0(%) |

F0.05, F0.06 is only effective when S curve Acc/Dec mode( F0.04＝1)is selected during Acc/Dec selection, and **F0.05＋F0.06**≤90%.

S curve starting time is shown as Fig. 6-2③，slope of output frequency variation increases by degrees from 0.

S curve rising time is shown as Fig.6-2②，slope of output frequency variation is constant.

S curve ending time is shown as Fig.6-2①，slope of output frequency variation steps down to 0.

note

S curve Acc/Dec mode，suitable for starting and stopping elevator, deferent belt, carrier transporter load etc..

| F0.07 | Acc/Dec time unit | Range：0, 1 | 0 |
|---|---|---|---|

This function determines Acc/Dec time unit.

**0: second**

**1: minute**

note

(1) This function is effective for all Acc/Dec process except for jog run.
(2) To choose second as time unit is recommended.

| | | | |
|---|---|---|---|
| **F0.08** | **Acc time 1** | **Range：0.1－6000.0** | **20.0** |
| **F0.09** | **Dec time 1** | **Range：0.1－6000.0** | **20.0** |

Accelerating time is defined as time for inverter accelerating from 0Hz to high limit frequency，see $t_1$ in Fig.6-3，Dec time is defined as time for inverter decelerating from high limit frequency to 0Hz, see $t_2$ in Fig.6-3.

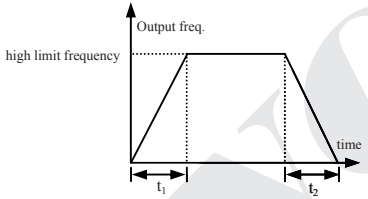



**Fig.6-3 Acc/Dec time definition**

note

(1) In EDS800 series inverter 7 kinds of Acc/Dec time are defined in total，here we only define Acc/Dec time 1，Acc/Dec time 2~7 are defined in F2.18~F2.29，please refer to Section 6.3.
(2) Can choose time unit minute or second for Acc/Dec time 1~7 by F0.07, factory default is second.

| | | | |
|---|---|---|---|
| **F0.10** | **high limit frequency** | **Range：low limit－400.00Hz** | **50.00Hz** |
| **F0.11** | **low limit frequency** | **Range：0.00－high limit** | **0.00Hz** |
| **F0.12** | **Low limit freq. run mode** | **Range：0:run at low limit freq. 1:stop running** | **0** |

The inverter will decrease output frequency gradually in set decelerating time when actual set frequency is lower than low limit frequency，after reaching low limit frequency，the inverter will run at low limit frequency if F0.18 is set to 0；The inverter will reduce output frequency sequentially to zero frequency run if F0.12 is set to 1.

| | | | |
|---|---|---|---|
| **F0.13** | **Torque boost mode** | **Range：0：manual 1：automatic** | **0** |

**0: manual boost.** Torque boost voltage is determined completely by parameter

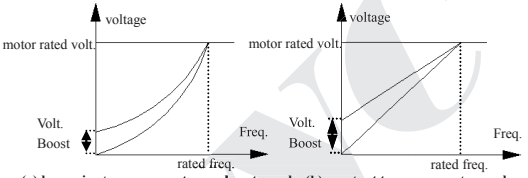
F0.14，its characteristic is boost voltage fixed，but the motor is prone to magnetic saturation when lightly loaded.

**1: automatic torque boost.** Torque boost voltage varies as stator current of the motor changes，bigger stator current corresponds to bigger boost voltage.

$$\text{Boost volt.} = \frac{\text{F0.14}}{100} \times \text{motor rated volt.} \times \frac{\text{inverter output current}}{2 \times \text{inverter rated current}}$$

| F0.14 | Torque boost | Range：0.0－20.0(%) | 4.0(%) |
|---|---|---|---|

To improve inverter's low frequency torque characteristic，can carry on boost compensation for output voltage，degressive torque curve and constant torque curve torque boost are separately shown as Fig.6-4 (a), (b).




(a)degressive torque curve torque boost graph (b) constant torque curve torque boost graph

**Fig.6-4 torque boost graph**

note Improper setting to this parameter can cause motor heating or over current protection.

| F0.15 | V/F curve setting | Range：0～4 | 0 |
|---|---|---|---|

This function code defines EDS800 flexible V/F setting mode to satisfy different load characteristic. Can choose 4 kinds of fixed curve according to definition of F0.15.

If F0.15=0，V/F curve bears constant torque characteristic；as curve 0 in Fig.6-5.

If F0.15=1，V/F curve bears 2.0 order power degressive torque characteristic；as curve 3 in Fig.6-5.

If F0.15=2，V/F curve bears 1.7 order power degressive torque characteristic；as curve 2 in Fig.6-5.

If F0.15=3，V/F curve bears 1.2 order power degressive torque characteristic；as curve 1 in Fig.6-5.

The user can choose 1, 2, 3 V/F curve run mode according to load characteristic to reach better energy save result while the inverter is driving degressive torque l

such as blower and water pump etc.

If F0.15=4, you can set V/F curve yourself by setting F2.37-F2.44 parameters.

As shown in Fig.6-5b, by setting three inflexion point (V1,F1), (V2,F2), (V3,F3), you can define V/F curve arbitrarily to apply to special load.

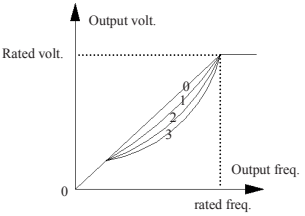
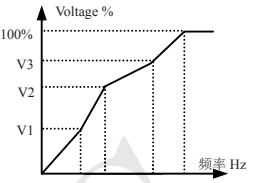



Fig.6-5 V/F curve




V1~V3: The 1th-3th voltage percentage of VF multi section

F1~F3: The1th-3th of multi section VF frequency points

Fb: Setting frequency

**b Users set the general form of V/F curve**

| F0.16 | Reserved | | |
|---|---|---|---|

## 6.2 Start-up, stop, braking function parameter group: F1

| F1.00 | Start-up run mode | Range: 0, 1, 2 | 0 |
|---|---|---|---|

0: start from starting frequency. The inverter start according to F1.01 starting frequency and F1.02 starting frequency holding time.

1: first braking then starting. First brake according to DC braking voltage and time (F1.03, F1.04), then start at starting frequency.

2: reserved.

note

(1) start-up mode 0: Advise the user to adopt start-up mode 0 in common application occasion and when driving synchronous motor.

(2) start-up mode 1: Be applicable to small inertia load with forward run or reverse run phenomena when the moter doesn't drive anv device, for big inertia load, advise not to adopt start-up mode 1.

| F1.01 | Starting frequency | Range: 0.0－10.00Hz | 0.00 Hz |
|---|---|---|---|
| F1.02 | Starting freq. holding time | Range: 0.0－20.0s | 0.0s |

Starting frequency means initial frequency at which the inverter start up, as fs shown in Fig.6-6; Starting freq. holding time means consecutive run time during which the inverter run at starting frequency, as $t_1$ shown in Fig.6-6.

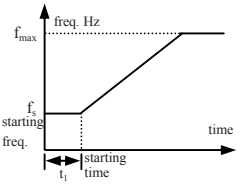



**Fig.6-6 starting freq. and starting time**

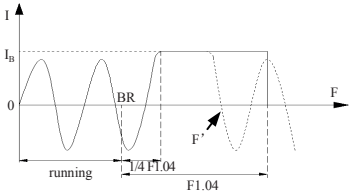



**Fig.6-7 Zero freq. DC braking Volt. And Time**

note

Starting frequency is not limited by low limit frequency.

| | | | |
|---|---|---|---|
| **F1.03** | **Zero freq. DC braking volt.** | **Range：0－15(%)** | **0(%)** |
| **F1.04** | **Zero freq. DC braking time** | **Range：0.0－20.0s** | **0.0s** |

Zero Freq. DC braking is special function for FKM (Flat Knitting Machine). Specific function is: the inverter enters into braking status automatically during running when running frequency is lower than F3.29 (Zero Freq. Braking frequency), and realizes continuance of current phase intelligently, fast and smooth orientation for motor's rotor. The inverter will stop braking automatically and switch into running if specified frequency increased or reverse running instruction provided in the braking, Curve figure as Fig6-7:

(1). $I_B$ is zero Freq. braking current, to set according to actual braking torque by setting F1.03.

(2). BR is specified zero Freq. braking signal point, inverter enters into zero Freq. braking status automatically after 1/4 F1.04.

(3). F'is any time in braking. When specified frequency increased or reverse running instruction provided, the inverter will end zero Freq. braking and enter into running status. But the inverter is still in running status and waits for frequency raising instruction.

(4). After F1.04, the inverter stops output and the motor is in zero Freq. running status if there is neither frequency raising instruction nor reverse instruction.

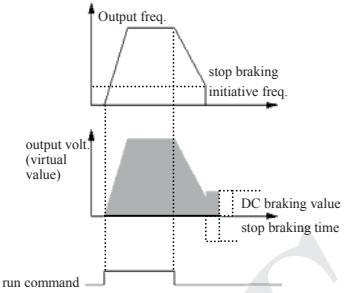



**Fig.6-8 Dec stop+DC braking**

| F1.05 | Stop mode | Range：0, 1, 2 | 0 |
|---|---|---|---|

**0: Dec stop.** The inverter reduces output frequency gradually according to set Dec time upon receival of stop command and stops running after frequency is reduced to 0.

**1: free stop.** The inverter stop outputting at once when receiving stop command and the load stops freely according to mechanical inertia.

**2: Dec plus DC braking stop.** The inverter reduces output frequency gradually according to set Dec time upon receival of stop command and start DC braking when F1.06 stop braking initiative frequency is reached.

| F1.06 | Stop DC braking initiative frequency | Range：0.0－15.00Hz | 0.00Hz |
|---|---|---|---|
| F1.07 | Stop DC braking time | Range：0.0－20.0S | 0.0S |
| F1.08 | Stop DC braking voltage | Range：0－15（%） | 0 |

F1.08 is percentage relative to inverter rated input voltage. Have no DC braking process if stop braking time is 0.0s，as shown in Fig.6-8.

## 6.3 Auxiliary run function parameter group: F2

| F2.00 | Analog filtering time constant | Range：0.00－30.00S | 0.20S |
|---|---|---|---|

The time constant used when the inverter filter sampled value when frequency is set by exterior analog channel. Can improve the situation by increasing this filtering time constant if connecting wire is long or disturbance is serious which cause unstable set frequency.

Analog filtering time constant must be bigger than F3.11(sampling cycle), otherwise the system would run unsteadily.

| F2.01 | FWD REV run dead-section time | Range：0.0—3600.0s | 0.1s |
|---|---|---|---|

During process of transiting from forward run to reverse run or from reverse run to forward run, transition time during which the inverter wait at zero output frequency, as t1 shown in Fig.6-9.

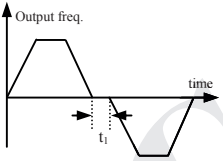



**Fig.6-9 FWD REV run dead-section time**

| F2.02 | Automatic energy save run | Range：0, 1 | 0 |
|---|---|---|---|

To reach better energy save result, the inverter would detect load current to get the purpose of automatic energy save.

**0: no action**

**1: action**

Empty or lightly loaded motor can get the purpose of energy save by detecting load current to adjust output voltage properly. Automatic energy save run is mainly applied to occasion of stable load, speed.

note This function commonly applied to load such as blower and water pump etc.

| F2.03 | AVR function | Range：0, 1, 2 | 0 |
|---|---|---|---|

AVR namely automatic voltage adjusting function. Indicate that the inverter can output constant voltage by AVR function when the inverter input voltage fluctuates.

**0: no action**

**1: action all the time**

**2: no action only during Dec**

note

1. when input voltage is higher than rated value, under normal situation should set F2.03=1. When F1.05=0 namely inverter in decelerating stop，motor Dec time is short and running current would be bigger. But the motor decrease speed placidly with small run current and long Dec time if choose AVR action all the time.
2. should set F2.03=0, namely AVR function ineffective when the motor system oscillates which caused by choosing AVR function.

| F2.04 | Slip freq. compensation | Range：0～150(%) | 0 |
|---|---|---|---|

This function can adjust output frequency properly as the load varies to compensate slip frequency of the asynchronous motor dynamically, so that control motor speed in constant value. If act with automatic torque boost function, can get better low speed moment characteristic. As shown in Fig.6-10.

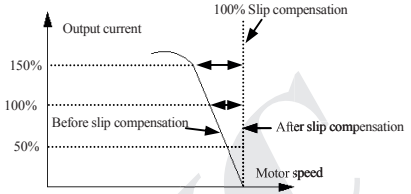



**Fig.6-10 slip freq. compensation graph**

| F2.05 | Carrier freq. | Range：2－15.0K | Depend on device type |
|---|---|---|---|

Carrier frequency mainly affects motor noise and heat consumption during running. Relation between carrier frequency and motor noise, current leakage, disturbance is as follows:

Carrier frequency increase( ↑ )，motor noise decrease( ↓ )，motor current leakage increase( ↑ )，disturbance to environment increase( ↑ )；

Carrier frequency decrease ( ↓ )，motor noise increase ( ↑ )，motor current leakage decrease ( ↓ )，disturbance to environment decrease ( ↓ ).

Should decrease carrier frequency properly to reduce heat consumption of the inverter when ambient temperature is high and motor load is heavy. Relation of EDS800 each type and carrier frequency is as shown in Table 6-1.

**Table 6-1 relation table of device type and carrier frequency**

| carrier freq. / device type | Max.carrier freq. (KHz) | Min. carrier freq (KHz) | factory default (KHz) |
|---|---|---|---|
| 0.2KW | 15 | 2.0 | 2 |
| 0.4KW | 15 | 2.0 | 2 |
| 0.75KW | 14 | 2.0 | 2 |
| 1.5KW | 13 | 2.0 | 2 |

note

(1) To get better control characteristic，suggest that the ratio of carrier frequency to inverter max. run frequency be not smaller than 36.
(2) Error exists in current displayed value when carrier frequency is small.

| | | | |
|---|---|---|---|
| **F2.06** | **Jog run frequency** | **Range：0.10－50.00Hz** | **5.00Hz** |
| **F2.07** | **Jog Acc time** | **Range：0.1－60.0s** | **20.0s** |
| **F2.08** | **Jog Dec time** | **Range：0.1－60.0s** | **20.0s** |

**Jog frequency has the highest priority.** Under any status, the inverter would transit to run at jog frequency at once according to set jog accelerating, decelerating time as long as jog command is inputted, as shown in Fig.6-11.

Jog accelerating time means time during which the inverter accelerate from 0Hz to high limit frequency，Jog Dec time means time during which the inverter decelerate from high limit frequency to 0Hz.

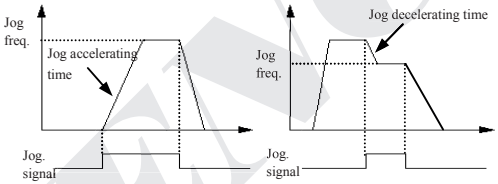



**Fig.6-11 jog run**

note

**(1) Keypad, control terminal and serial port can do jog control all.**
**(2) The inverter will stop according to Dec stop mode after jog run command is withdrawn.**

| | | | |
|---|---|---|---|
| **F2.09** | **Freq. input channel combination** | **Range：0～28** | **0** |

**0: VCI＋CCI**
**1: VCI－CCI**
**2: reserved**
**3: reserved**
**4: reserved**
**5: reserved**
**6: external pulse provision＋CCI**
**7: external pulse provision－CCI**
**8: reserved**
**9: reserved**

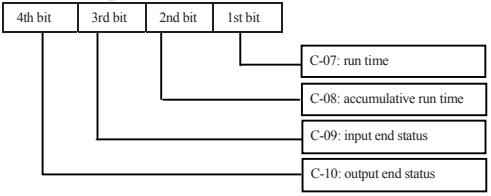
**10 : reserved**
**11 : reserved**
**12 : reserved**
**13 : VCI, CCI any nonzero value effective, VCI preferred**
**14 : reserved**
**15 : 485+CCI**
**16 : 485-CCI**
**17 : 485+VCI**
**18 : 485-VCI**
**19 : 485+ keypad analog potentiometer**
**20 : 485- keypad analog potentiometer**
**21 : VCI+ keypad analog potentiometer**
**22 : VCI- keypad analog potentiometer**
**23 : CCI+ keypad analog potentiometer**
**24 : CCI- keypad analog potentiometer**
**25 : VCI*QWG（keypad analog potentiometer）**
**26 : reserved**
**27 : reserved**
**28 : reserved**

| | | | |
|---|---|---|---|
| **F2.10** | **host inverter communication freq. provision proportion** | **Range：0－500(%)** | **100(%)** |

Host&sub inverter communication freq. provision proportion，this parameter need to be set in sub inverter but not need in host inverter.

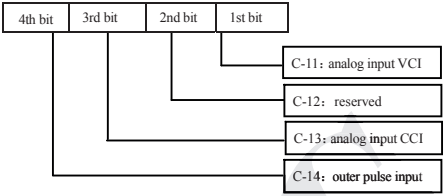
| | | | |
|---|---|---|---|
| **F2.11** | **LED display control 1** | **Range：0000－1111** | **1111** |

F2.11 make use of 4 bits of the parameter to set if C-07—C-10 is displayed in parameter, thereinto 0 indicates not displayed, 1 indicates displayed. Set parameter of 4 bit is as following figure:



| F2.12 | LED display control 2 | Range：0000－1111 | 1111 |
|---|---|---|---|

F2.12 make use of 4 bit of the parameter to set if C-11－C-14 is displayed in parameter, thereinto 0 indicates not displayed, 1 indicates displayed. Set parameter of 4 bit is as following figure:




| F2.13 | Parameter operation control | Range：LED 1st bit: 0~2<br>LED 2nd bit: 0~2<br>LED 3rd bit: 0~4 | 000 |
|---|---|---|---|

LED 1st bit

0: all parameter allowed to be modified

1: except this parameter，all other parameter not allowed to be changed

2: except F0.01 and this parameter，all other parameter not allowed to be changed

LED 2nd bit

0: no action

1: renew factory default

2: clear history failure record

LED 3rd bit（After setting, It will be valid after pressing MENU key for 5 seconds and entering into Locc status）

0: lock all buttons

1: all the buttons locked except STOP key

2: all the buttons locked except ▲▼ , STOP key

3: all the buttons locked except RUN, STOP key

4: all the buttons locked except SHIFT, STOP key

note

(1)Factory default of this function parameter is 0，i.e., all the function parameter can be modified.After modifying the parameter, please first set this function code to 0 if you want to modify function code setting.After modifying the parameter you can change this function code setting to expected protection grade if parameter protection is needed.
(2) After clearing memory information or renewing manufacturer parameter, the 1st bit of this function code will resume 0 automatically.
(3) After the 3rd bit of F2.13 is setted, the keypad will be locked after you press ESC for 5 seconds, and then corresponding keys is locked. Please press ESC for 5 seconds again for unlocking the keypad.

| | | | |
|---|---|---|---|
| **F2.14** | **communication deployment** | **Range：LED 1st bit：0～5<br>LED 2nd bit: 0, 1, 2<br>LED3rd bit: 0, 1** | **003** |

F2.14 make use of 1st bit, 2nd bit, 3rd bit to set baud rate and data format of serial communication，thereinto LED 1st bit represents communication baud rate, set value as follows:

**0: 1200BPS**
**1: 2400BPS**
**2: 4800BPS**
**3: 9600BPS**
**4: 19200BPS**
**5: 38400BPS**

LED 2nd bit: represents data format，set value as follows:

**0: 1－8－1 format, no checkout.** Namely: 1 bit for starting, 8 bits for data, 1 bit for stop, no checkout.

**1: 1－8－1 format, even checkout.** Namely: 1 bit for starting, 8 bits for data, 1 bit for stop, even checkout.

**2: 1－8－1 format, odd checkout.** Namely: 1 bit for starting, 8 bits for data, 1 bit for stop, odd checkout.

LED 3rd bit:：response selection

0：Respond to host command and reply to data packet

1：Respond to host command, but not reply

| | | | |
|---|---|---|---|
| **F2.15** | **Local address** | **Range：0－127, 0 is broadcast address** | **1** |

In serial port communication, the function code is used to identify the address of the inverter. When set to 0, this inverter only receives not send.

0 is broadcast address，can only receive and execute broadcast command from upper machine but not respond to upper machine.

| | | | |
|---|---|---|---|
| **F2.16** | **Communication overtime checkout time** | **Range：0.0－1000.0s,** 0 means communication timeout detection invalid | **0.0s** |

When serial port communication fails and its continuous time exceed set value of this function code，the inverter judge it as communication failure.

The inverter would not detect serial port communication signal, namely this function ineffective when set value is 0.

| | | | |
|---|---|---|---|
| **F2.17** | **Local response delay time** | **Range：0－200ms** | **5ms** |

Local response delay time represents the time within which the inverter serial port receive and execute command from upper device and then respond to upper device, this function is just used for setting this delay time.

| | | | |
|---|---|---|---|
| **F2.18** | **Accelerating time 2** | **Range：0.1－6000.0** | **20.0** |
| **F2.19** | **Decelerating time 2** | **Range：0.1－6000.0** | **20.0** |
| **F2.20** | **Accelerating time 3** | **Range：0.1－6000.0** | **20.0** |
| **F2.21** | **Decelerating time 3** | **Range：0.1－6000.0** | **20.0** |
| **F2.22** | **Accelerating time 4** | **Range：0.1－6000.0** | **20.0** |
| **F2.23** | **Decelerating time 4** | **Range：0.1－6000.0** | **20.0** |
| **F2.24** | **Accelerating time 5** | **Range：0.1－6000.0** | **20.0** |
| **F2.25** | **Decelerating time 5** | **Range：0.1－6000.0** | **20.0** |
| **F2.26** | **Accelerating time 6** | **Range：0.1－6000.0** | **20.0** |
| **F2.27** | **Decelerating time 6** | **Range：0.1－6000.0** | **20.0** |
| **F2.28** | **Accelerating time 7** | **Range：0.1－6000.0** | **20.0** |
| **F2.29** | **Decelerating time 7** | **Range：0.1－6000.0** | **20.0** |

Can define 3 kinds of accelerating decelerating time and can choose accelerating decelerating time 1～7 during inverter run process by different combination of control terminal，please see definition for function of accelerating decelerating time terminal in F5.00～F5.07.

**note** Accelerating decelerating time 1 is defined in F0.08 and F0.09.

| | | | |
|---|---|---|---|
| F2.30 | Multi-step freq. 1 | Range：Lower limit freq.—upper limit freq. | 5.00Hz |
| F2.31 | Multi-step freq. 2 | Range：Lower limit freq.—upper limit freq. | 10.00Hz |
| F2.32 | Multi-step freq. 3 | Range：Lower limit freq.—upper limit freq. | 20.00Hz |
| F2.33 | Multi-step freq. 4 | Range：Lower limit freq.—upper limit freq. | 30.00Hz |
| F2.34 | Multi-step freq. 5 | Range：Lower limit freq.—upper limit freq. | 40.00Hz |
| F2.35 | Multi-step freq. 6 | Range：Lower limit freq.—upper limit freq. | 45.00Hz |
| F2.36 | Multi-step freq. 7 | Range：Lower limit freq.—upper limit freq. | 50.00Hz |
| F2.37 | Multi-step freq. 8 | Range：Lower limit freq.—upper limit freq. | 5.00Hz |
| | VF freq. value 0 | Range:0.00—F2.39 | 0.50Hz |
| F2.38 | Multi-step freq. 9 | Range：Lower limit freq.—upper limit freq. | 10.00Hz |
| | VF voltage value 0 | Range:0.00—F2.40 | 2.00% |
| F2.39 | Multi-step freq. 10 | Range：Lower limit freq.—upper limit freq. | 20.00Hz |
| | VF freq. value 1 | Range:F2.37—F2.41 | 20.00Hz |
| F2.40 | Multi-step freq. 11 | Range：Lower limit freq.—upper limit freq. | 30.00Hz |
| | VF voltage value 1 | Range:F2.38—F2.42 | 38.00% |
| F2.41 | Multi-step freq. 12 | Range：Lower limit freq.—upper limit freq. | 40.00Hz |
| | VF freq. value 2 | Range:F2.39—F2.43 | 25.00Hz |
| F2.42 | Multi-step freq. 13 | Range：Lower limit freq.—upper limit freq. | 45.00Hz |
| | VF voltage value 2 | Range:F2.40—F2.44 | 48.00% |
| F2.43 | Multi-step freq. 14 | Range：Lower limit freq.—upper limit freq. | 50.00Hz |
| | VF freq. value 3 | Range:F2.41- high limit freq. | 40.00Hz |
| F2.44 | Multi-step freq. 15 | Range：Lower limit freq.—upper limit freq. | 50.00Hz |
| | VF voltage value 3 | Range:F2.42—100.0%(rated voltage) | 80.00% |

These parameters are compound, two kinds of function can't be used simultaneously, for details please check below:

When F0.15=4, F2.37~F2.44 are for V/F curve setting, for detailed function description, please see that for F0.15.

When F0.15≠4, F2.37~F2.44 are used for multi-section frequency. Setting m

and function are the same as F2.30.

| | | | |
|---|---|---|---|
| **F2.45** | **Jumping freq. 1** | **Range：0.00－400.00Hz** | **0.00Hz** |
| **F2.46** | **Jumping freq. 1 range** | **Range：0.00－30.00Hz** | **0.00Hz** |
| **F2.47** | **Jumping freq. 2** | **Range：0.00－400.00Hz** | **0.00Hz** |
| **F2.48** | **Jumping freq. 2 range** | **Range：0.00－30.00Hz** | **0.00Hz** |
| **F2.49** | **Jumping freq. 3** | **Range：0.00－400.00Hz** | **0.00Hz** |
| **F2.50** | **Jumping freq. 3 range** | **Range：0.00－30.00Hz** | **0.00Hz** |

F2.45～F2.50 function is set for keeping inverter output frequency away from resonance frequency of mechanical load.

Inverter set frequency can jump around some frequency point according to mode shown in Fig. 6-12, at most 3 jumping range can be defined.

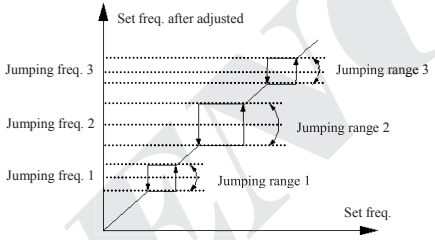



**Fig.6-12 jumping frequency and range graph**

| | | | |
|---|---|---|---|
| **F2.51** | **Set run time** | **Range：0－65535h** | **0** |
| **F2.52** | **Run time accumulation** | **Range：0－65535h** | **0** |

After run accumulative time reach set run time (F2.51)，the inverter will output indicator signal，please refer to F5.10 function introduction.

F2.52 denotes accumulative run time of the inverter from leaving factory to now.

| | | | |
|---|---|---|---|
| **F2.53** | **Reserved** | | |

## 6.4 Closed-loop run control parameter: F3

Analog feedback control system:

Input pressure specified value through VCI port, send 4~20mA feedback value of pressure sensor to inverter CCI input port，make up of analog closed-loop control

system by built-in PID adjustor，as shown in Fig.6-13.

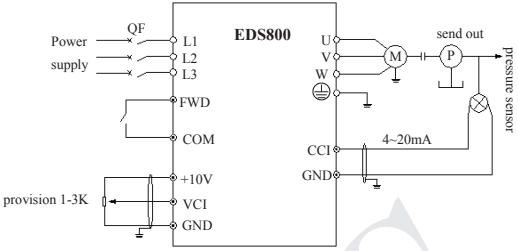



**Fig.6-13 built-in PID analog feedback control system graph**

note

Specified value can also be provided with option by F0.00 function code.

EDS800 built-in PID adjustor make up of control system and its work principle chart is as follows:

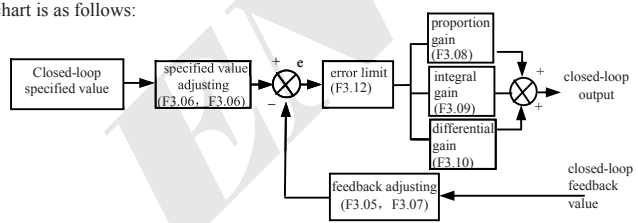



**Fig.6-14 PID control principle diagram**

In above Fig.6-14 ,definition of closed-loop specified value, feedback value, error limit and proportion integral differential parameter is same as that of common PID adjustor parameter, see respectively (F3.01~F3.12) definition，relation of specified value and expected feedback value is as shown in Fig.6-15. Thereinto specified value take 10V as reference and feedback take 20mA as reference.

Specified value adjusting and feedback value adjusting in Fig.6-14 is for confirming corresponding relation and unitive dimension between specified value and feedback value.

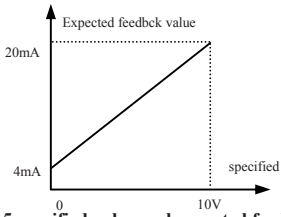



**Fig.6-15 specified value and expected feedback value**

When the system is determined，basic steps for setting closed-loop parameter are as follows:

(1) determine closed-loop provision and feedback channel(F3.01, F3.02)

(2) need to set relation between closed-loop provision and feedback for analog closed-loop (F3.04~F3.07)

(3) set closed-loop presetting frequency function (F3.14, F3.15)

(4) set closed-loop proportion gain, integral gain, differential gain, sampling cycle, error limit (F3.08~F3.12)

| F3.00 | Closed-loop run control selection | Range：0, 1, 2 | 0 |
|---|---|---|---|

**0: closed-loop run control ineffective**

**1: PID closed-loop run control effective**

**2：constant pressure water supply PID control specialized (one tows one)**

F3.00=1, when ordinary PID regulation, the deviation is within deviation limitation, no PID caculation, keep the stable output.

F3.00=2, constant pressure regulation, the deviation is within deviation limitation and running frequency is above the sleep mode frequency, it runs for energy saving, the output frequency descend runnig at 3HZ/Min. When the deviation is within deviation limitation and running frequency is below or equal to sleep mode frequency, after the time of sleep delay, the frequency will go down to 0HZ to run, and the inverter will be sleep mode. When feedback pressure less than revive pressure, afer the time of revive delay, the inverter will run according to PID regulation.

| F3.01 | Provision channel selection | Range：0～3 | 0 |
|---|---|---|---|

**0: digital provision.**

**1: VCI analog 0－10V voltage provision**

**2: CCI analog provision. Can choose 0~10V voltage or 4~20mA current provision**

**3: keypad analog potentiometer provision**

| F3.02 | Feedback channel selection | Range：0～6 | 0 |
|---|---|---|---|

**0: VCI analog input voltage 0－10V**

**1: CCI analog input**

**2: VCI+CCI**

**3: VCI-CCI**

**4: Min { VCI, CCI }**

**5: Max { VCI, CCI }**

When CCI analog input is selected to be current input, it will be converted to voltage value in the inverter.

**6: pulse feedback**

| | | | |
|---|---|---|---|
| **F3.03** | **Specified value digital** | **Range: 0.00－9.999V** | **0.200V** |
| | **Target pressure value setting** | **Range:0.00－F3.21Mpa** | **0.200(Mpa)** |

When F3.00=1, figure given value F3.03 will be as specified value of closed-loop control system directly. At this time please setF3.21to 9.999(v);

When F3.00=2, Start PID control constant pressure water supply, At this point the water supply system F3.03 will become the target pressure value. Upper limit is F3.21Mpa.

| | | | |
|---|---|---|---|
| **F3.04** | **min. specified value** | **Range: 0.0－max. specified value** | **0.0(%)** |
| **F3.05** | **corresponding feedback value of min. specified value** | **Range：0.0－100.0(%)** | **0.0(%)** |
| **F3.06** | **max. specified value value** | **Range：min. specified value -100.0(%)** | **100.0(%)** |
| **F3.07** | **corresponding feedback value of max. specified value** | **Range：0.0%－100.0(%)** | **100.0(%)** |

F3.04~F3.07 define relation curve of analog closed-loop provision and expected feedback. Their set value is percentage of provision and feedback actual value relative to reference (10V or 20mA).

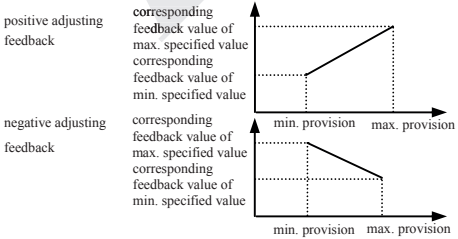



**Fig.6-16 provision，feedback curve**

| | | | |
|---|---|---|---|
| **F3.08** | **Proportion gain Kp** | **Range：0.000－9.999** | **0.150** |
| **F3.09** | **Integral gain Ki** | **Range：0.000－9.999** | **0.150** |
| **F3.10** | **Differential gain Kd** | **Range：0.000－9.999** | **0.000** |
| **F3.11** | **Sampling cycle T** | **Range：0.01－1.00S** | **0.10S** |

The more big Kp proportion gain is, the more quick the response is，but overbig is prone to bringing surge.

Only applying proportion gain Kp adjustment can't eliminate offset completely，can apply integral gain Ki and differential gain to make up of PID control in order to eliminate residual offset. The bigger Ki is, the more quickly the system responds to changing offset, but overbig is prone to bringing surge.

Sampling cycle T is sampling cycle for feedback value，during each sampling cycle PID adjustor calculate for one time，the longer the sampling cycle is , the slower the system responds.

| | | | |
|---|---|---|---|
| **F3.12** | **Offset limit** | **Range：0.0－20.0(%)** | **2(%)** |

For Max. offset of closed-loop specified value，as shown in Fig.6-17，PID adjustor stops adjusting when feedback value is within this range. To utilize this function reasonably redound to harmonizing the conflict between system output precision and stabilization.

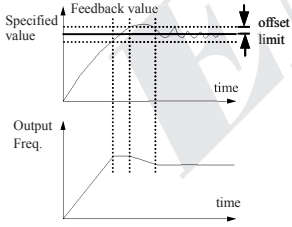



**Fig.6-17 offset limit**

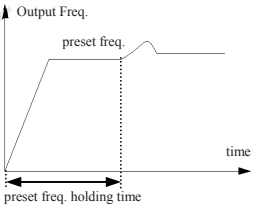



**Fig.6-18 closed-loop preset freq. run**

| | | | |
|---|---|---|---|
| **F3.13** | **integral separation PID adjusting threshold** | **Range：0.0－100.0%** | **100.0%** |

PID integral separation，integral don't react when specified value and feedback value are bigger than this limit, only when specified value and feedback value are smaller than or equal to this limit，integral react. Can adjust system response speed by adjusting this parameter.

| | | | |
|---|---|---|---|
| F3.14 | closed-loop preset frequency | Range：0-high limit freq. | 0.00Hz |
| F3.15 | closed-loop preset frequencyholding time | Range：0.0-6000S | 0.0S |

This function can make closed-loop adjusting enter into stable phase quickly.

After closed-loop run starts, the inverter first accelerates to preset frequency F3.14 in terms of accelerating time, and after running at this frequency for a period of time F3.15, it runs according to closed-loop characteristic. As shown in Fig.6-18.

note Set preset freq. and holding time to "0' if closed-loop preset freq. function is not needed.

| | | | |
|---|---|---|---|
| F3.16 | Revival frequency | Range：0.00－400.00Hz | 0.00Hz |
| F3.17 | Sleep frequency | Range：0.00－400.00Hz | 0.00Hz |

Revival frequency define frequency limit from sleep status to work status. If set frequency is bigger than this limit and the situation sustains for a revival delay time, the inverter will enter into work status from sleep status.

Sleep frequency define frequency limit from work status to sleep status. If set frequency is smaller than this limit and the situation sustains for a sleep delay time, the inverter will enter into sleep status from work status.

This function can realize sleep function and make energy save run possible, avoid the inverter staring at threshold frequency frequently.

| | | | |
|---|---|---|---|
| F3.18 | Sleep delay time | Range：0.0－6000.0s | 0.0s |

This parameter is to set delay time when entering into sleep function. EDS800 will stop running if the output frequency is lower than sleep frequency and holding time longer than this sleep delay time.

| | | | |
|---|---|---|---|
| F3.19 | Revival delay time | Range：0.0－6000.0s | 0.0 |

This parameter is to set delay time when entering into revival function.

| | | | |
|---|---|---|---|
| F3.20 | Reserved | | |

| | | | |
|---|---|---|---|
| F3.21 | Long-distance manometer range | Range：0.001－9.999Mpa | 1.000 |

To set 10V or 20mA by this parameter.

| | | | |
|---|---|---|---|
| F3.22 | Reserved | | |
| F3.23 | Reserved | | |
| F3.24 | Reserved | | |
| F3.25 | Reserved | | |

| F3.26 | Water supply supervision Para. display | Range：0, 1 | 0 |
|---|---|---|---|

0: C-11, C-12 display voltage value of VCI, CCI.

1: C-11, C-12 display PID specified pressure and feedback pressure.

| F3.27 | Closed-loop adjusting characteristic | Range：0, 1 | 0 |
|---|---|---|---|

0: Forward function. motor speed increases as specified value increases.

1: Reverse function. motor speed decreases as specified value increases.

| F3.28 | LED initial supervision Para. selection | Range：0~14 | 1 |
|---|---|---|---|

This parameter defines initial supervision parameter selection during running or stop. For example F3.28=3, LED displays output voltage initially, please press SHIFT key if you want to see about other supervision parameter.

0: set frequency:It displays set-frequency when standby and displays output frequency when running.

1: output frequency:It displays output frequency while running and standby.

2: output current

3: output voltage

4: DC bus bar voltage

5: motor speed

6: heat sink temperature

7: run time

8: accumulative run time

9: input terminal status

10: output terminal status

11: analog input VCI/PID provision

12: analog input CCI/PID feedback

13: analog input YCI

14: exterior pulse input

| F3.29 | YCI run-in delay time | Range: 0.0—9.999s | 0.0s |
|---|---|---|---|
| | PID feedback signal loss detection | Range: 0.0—9.999s | 0.0s |

YCI input delay time: the inverter first run at RS485 set frequency after start-up and change set frequency to RS485+YCI after delay time passed.

PID feedback signal loss detection: When F3.29=0.0, PID feedback signal loss detection protection function invalid, when F3.29≠0, feedback signal<12.5% given value and the constant time＞F3.29, then you can judge the feedback signal loss.

avoid damaging the equipment. Fault code is displayed as E017.

| F3.30 | Failure relay TA, TB, TC function selection | Range：0~24 | 15 |
|---|---|---|---|

**Table 6-2 Failure relay TA，TB，TC function selection**

| item | corresponding function | item | corresponding function |
|---|---|---|---|
| 0 | Inverter running signal (RUN) | 1 | Frequency arriving signal (FAR) |
| 2 | Frequency level detectingsignal (FDT1) | 3 | reserved |
| 4 | Overload warning signal( OL) | 5 | Output Freq. reach high limit( FHL) |
| 6 | Output Freq. reach low limit( FLL) | 7 | Inverter stops for under voltage blockage (LU) |
| 8 | Stop for exterior failure( EXT) | 9 | Inverter zero speed running |
| 10 | In PLC run process | 11 | Simple PLC segment run finished |
| 12 | PLC finish one cycle run | 13 | reserved |
| 14 | Inverter is ready for run( RDY) | 15 | Inverter failure |
| 16 | traverse high&low limit restriction | 17 | Interior counter final value arrive |
| 18 | Interior counter specified value arrive | 19 | Set runtime arrive |
| 20 | Interior timer timing arrive | 21 | reserved |
| 22 | FWD running | 23 | REV running |
| 24 | reserved | | |

Now introduce function listed in Table 6-2 as follows:

**0: inverter during running( RUN).** The inverter is in run status，output indicator signal.

**1: frequency arriving signal( FAR).** Refer to function description of F5.14.

**2: Frequency level detecting signal( FDT1).** Refer to function description of F5.15~F5.16.

**3: reserved**

**4: overload warning signal( OL).** Inverter output current exceed F9.05 overload detect level and time exceed F9.06 overload detect time，output indicator signal.

**5: output frequency reach high limit( FHL).** When set frequency≥high limit frequency and run frequency reach high limit frequency，output indicator signal.

**6: output frequency reach low limit( FLL).** When set frequency≤low limit frequency and run frequency reach low limit frequency，output indicator signal.

**7: Inverter stops for under voltage blockage( LU).** When the inverter is running, LED displays“P.OFF” and output indicator signal if DC bus-bar voltage is lower than limitative level.

**8: stop for exterior failure( EXT).** When the inverter give the alarm (E014

and stops for exterior failure, output indicator signal.

**9 : inverter zero speed running.** When the inverter output zero frequency but
in run status, output indicator signal.

**10 : In PLC run process**

**11: Simple PLC segment run finished.** After simple PLC current segment run is finished，output indicator signal(single pulse signal，width 500ms).

**12 : PLC finish one cycle run**

**13 : reserved**

**14 : Inverter is ready for run( RDY).** If this signal is effective, shows that bus-bar voltage is normal and run prohibition terminal is ineffective, the inverter can receive start-up command.

**15 : Inverter fault.** If failure takes place when the inverter is running, the inverter output indicator signal.

**16 : Traverse high&low limit restriction.** After choosing traverse function, if frequency fluctuant range based on center frequency of traverse is above high limit frequency F0.10 or under low limit frequency F0.11, the inverter will output indicator signal, as shown in Fig. 6-19.

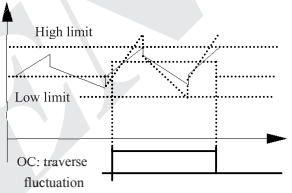



**Fig.6-19 traverse range restriction**

**17 : Interior counter final value arrive**

**18 : Interior counter specified value arrive**

17~18 please refer to function description of F5.25~F5.26.

**19 : Set runtime arrive.** When accumulative runtime of the inverter (F2.52) reach set runtime(F2.51)，output indicator signal.

**20 : Interior timer timing arrive.** Refer to function description for F5.27.

**21 : Reserved**

**22 : FWD running**

**23 : REV running**

**24 : Reserved**.

| | | | |
|---|---|---|---|
| **F3.31** | **Reserved** | | |

## 6.5 Simple PLC run function parameter group: F4

The user can set by himself the output frequency direction and running time of the inverter during a running cycle by simple PLC function according to spot craft demand, as shown in Fig.6-21.

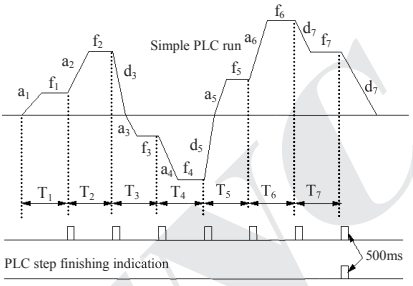



**Fig.6-21 simple PLC run**

EDS800 serial inverter simple PLC run function provide 7 kinds of multi-step speed run mode，see below an example of 7 step speed. In Fig.6-22，$a_1$~$a_5$, $d_1$~$d_5$ is accelerating or decelerating time of relative step，set by accelerating decelerating time parameter F0.08, F0.09 and F2.18~F2.29 in total 7 kinds of parameter，$f_1$~$f_7$, $T_1$~$T_7$ indicating set frequency and run time set by function code F4.01~F4.14.

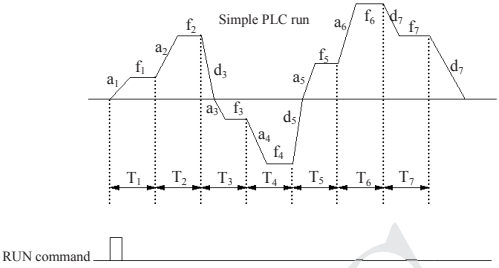



**Fig.6-22 stop after PLC single circle**

PLC step finishing and circle finishing indication can be realized by outputting 500mS pulse indicator signal through open circuit collector terminal OC，detailed function defined by F5.10.

| | | | |
|---|---|---|---|
| **F4.00** | **Simple PLC run setting** | **Range：LED 1st bit：0~3<br>LED 2nd bit：0, 1<br>LED 3rd bit：0, 1<br>LED 4td bit :0, 1,2** | **0000** |

This function code make use of its 1st bit, 2nd bit, 3rd bit to set PLC run mode, PLC rerun mode after interruption, set run time unit, detail as follows:

LED 1st:

**0: no action.** PLC run mode ineffective.

**1: stop after single circle.** As shown in Fig.6-22, the inverter stops automatically after finishing a circle, can only start when another run command is available.

**2: keep final value after single circle.** As shown in Fig.6-23，the inverter keep running according to frequency, direction of final step after finishing a circle，the inverter won't stop according to set decelerating time until the stop command is available.

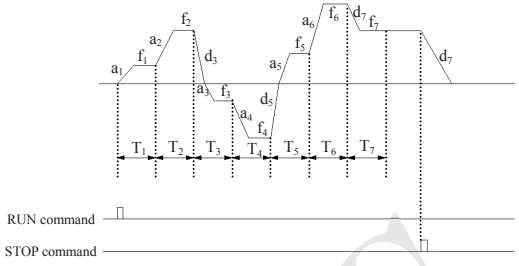



**Fig.6-23 holding mode after PLC single circle**

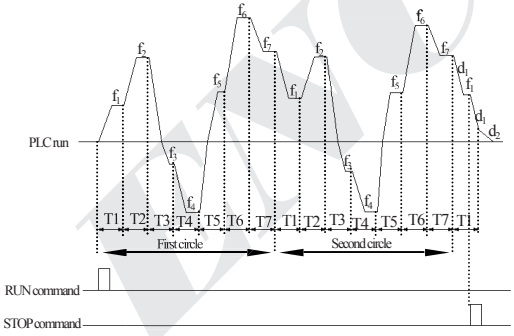



**Fig.6-24 PLC consecutive circle mode**

**3: consecutive circle.** As shown in Fig.6-24，the inverter start next circle automatically after finishing a circle，until there is stop command.

LED 2nd bit:

**0: start from first step.** Stop during running caused by stop command, failure or power off，after restarting the inverter will run from first step.

**1: continue to run from step frequency of interruption moment.** When stop during running caused by stop command or failure，the inverter will record current step used time automatically and enter into this step automatically after restarting，continue to run for residual time according to defined frequency of this step.

shown in Fig.6-25. The inverter will rerun from first step after restarting if power off.

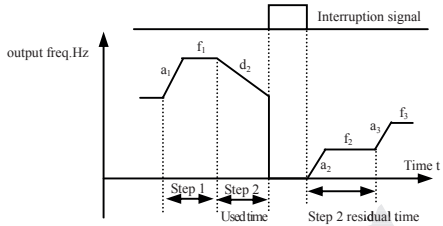



**Fig.6-25 PLC starting mode 1**

LED 3rd bit : PLC run time unit

**0: second; 1: minute**

This unit is only effective to PLC run step time，for accelerating decelerating time of PLC run period, their unit selection is determined by F0.07.

LED 4th bit

**0: power off no memory**

1: the inverter still in the memory running state when the power off, it needs renew run (terminal control exceptional) when power on without automotive start. Make memory of the simple PLC running segments, speed and running time before power off. Automotive read the state of the power off when restart, but the inverter doesn't run directly, (control commands except for the terminal mode), you need to run the command again.

**2: the inverter will record running state when power off and automatically run after restarting.** Make memory of the simple PLC running segments, speed and running time before power off, no need running command again directly run from the state of power off after restart.

note

(1) If run time of PLC segment is set to 0，this segment is ineffective.
(2) can make PLC process a pause, ineffective, work etc. through terminal, for detail please refer to terminal correlative function parameter group F5.

| | | | |
|---|---|---|---|
| **F4.01** | **Step 1 setting** | **Range：000－621** | **000** |
| **F4.02** | **Step 1 runtime** | **Range：0－6000.0** | **10.0** |

| | | | |
|---|---|---|---|
| F4.03 | Step 2 setting | Range：000－621 | 000 |
| F4.04 | Step 2 runtime | Range：0－6000.0 | 10.0 |
| F4.05 | Step 3 setting | Range：000－621 | 000 |
| F4.06 | Step 3 runtime | Range：0－6000.0 | 10.0 |
| F4.07 | Step 4 setting | Range：000－621 | 000 |
| F4.08 | Step 4 runtime | Range：0－6000.0 | 10.0 |
| F4.09 | Step 5 setting | Range：000－621 | 000 |
| F4.10 | Step 5 runtime | Range：0－6000.0 | 10.0 |
| F4.11 | Step 6 setting | Range：000－621 | 000 |
| F4.12 | Step 6 runtime | Range：0－6000.0 | 10.0 |
| F4.13 | Step 7 setting | Range：000－621 | 000 |
| F4.14 | Step 7 runtime | Range：0－6000.0 | 10.0 |

F4.01~F4.14 utilize LED 1st bit, 2nd bit, 3rd bit to separately define frequency setting，direction and accelerating decelerating time of PLC Run, see following for detail:

LED1st bit: frequency setting

**0: multi-step frequency i** i=1~7 is defined by F2.30~F2.44.

**1: frequency is determined by function code F0.00**

LED 2nd bit: run direction selection

**0: forward run**

**1: reverse run**

**2: determined by run command (FWD,REV)**

LED3rd bit: accelerating decelerating time selection

**0: accelerating decelerating time 1**

**1: accelerating decelerating time 2**

**2: accelerating decelerating time 3**

**3: accelerating decelerating time 4**

**4: accelerating decelerating time 5**

**5: accelerating decelerating time 6**

**6: accelerating decelerating time 7**

## 6.6 Terminal correlative function parameter group: F5

| | | | |
|---|---|---|---|
| **F5.00** | **Input terminal X1 function selection** | **Range：0~42** | **0** |
| **F5.01** | **Input terminal X2 function selection** | **Range：0~42** | **0** |
| **F5.02** | **Input terminal X3 function selection** | **Range：0~42** | **0** |
| **F5.03** | **Input terminal X4 function selection** | **Range：0~42** | **0** |
| **F5.04** | **Input terminal X5 function selection** | **Range：0~42** | **0** |
| **F5.05** | **Reserved** | | |
| **F5.06** | **Reserved** | | |
| **F5.07** | **Reserved** | | |

Multi-function input terminal X1~X5 provides 43 kinds of selection mode for the user，can choose based on spot requirement. For parameter function table please see Table 6-3.

**Table 6-3 multifunction input function selection table**

| item | corresponding function | item | corresponding function |
|---|---|---|---|
| 0 | Leave control terminal unused | 1 | Multi-step speed control terminal 1 |
| 2 | Multi-step speed control terminal 2 | 3 | Multi-step speed control terminal 3 |
| 4 | Multi-step speed control terminal 4 | 5 | External forward run jog control |
| 6 | External reverse run jog control | 7 | Accel/Decel time selecting terminal 1 |
| 8 | Accel/Decel time selecting terminal 2 | 9 | Accel/Decel time selecting terminal 3 |
| 10 | External device failure input | 11 | External restoration input |
| 12 | Free stop input | 13 | External stop command |
| 14 | stop DC braking input command DB | 15 | Inverter run prohibition |
| 16 | Frequency increasing command( UP) | 17 | frequency descending command( DOWN) |
| 18 | Accel/Decel prohibited command | 19 | Three-wire run control |
| 20 | Closed-loop ineffective | 21 | PLC ineffective |
| 22 | Simple PLC pause command | 23 | PLC stop status restoration (reset variable of PLC interruption moment, make it restart from first |
| 24 | Frequency provision channel selection 1 | 25 | Frequency provision channel selection 2 |
| 26 | Frequency provision channel selection 3 | 27 | Frequency switched to CCI |
| 28 | Command switched to terminal | 29 | Run command channel selection 1 |

| | | | |
|---|---|---|---|
| 30 | Run command channel selection 2 | 31 | Run command channel selection 3 |
| 32 | Traverse runin | 33 | External interruption input |
| 34 | interior counter clearing end | 35 | interior counter triggering end |
| 36 | Interior timer clearing end | 37 | interior timer triggering end |
| 38 | Pulse frequency input( only effective for X5) | 39 | Reserved |
| 40 | Reserved | 41 | Reserved |
| 42 | Reserved | | |

Now explain listed function in Table 6-3 as follows:

**1~4: Multi-step speed control terminal.** Can set 15 step speed run frequency by choosing ON/OFF combination of these function terminal.

**Table 6-4 multi-step speed run selection table**

| $K_4$ | $K_3$ | $K_2$ | $K_1$ | Frequency setting |
|---|---|---|---|---|
| OFF | OFF | OFF | OFF | Common run frequency |
| OFF | OFF | OFF | ON | Multi-step frequency 1 |
| OFF | OFF | ON | OFF | Multi-step frequency 2 |
| OFF | OFF | ON | ON | Multi-step frequency 3 |
| OFF | ON | OFF | OFF | Multi-step frequency 4 |
| OFF | ON | OFF | ON | Multi-step frequency 5 |
| OFF | ON | ON | OFF | Multi-step frequency 6 |
| OFF | ON | ON | ON | Multi-step frequency 7 |
| ON | OFF | OFF | OFF | Multi-step frequency 8 |
| ON | OFF | OFF | ON | Multi-step frequency 9 |
| ON | OFF | ON | OFF | Multi-step frequency 10 |
| ON | OFF | ON | ON | Multi-step frequency 11 |
| ON | ON | OFF | OFF | Multi-step frequency 12 |
| ON | ON | OFF | ON | Multi-step frequency 13 |
| ON | ON | ON | OFF | Multi-step frequency 14 |
| ON | ON | ON | ON | Multi-step frequency 15 |

Above multi-step frequency can be used in multi-step speed run and simple PLC run, please see below an example of multi-step speed run:

We now define control terminal X1, X2, X3, X4 separately as follows:

After set F5.00=1, F5.01=2, F5.02=3, F5.03=4, X1, X2, X3, X4 are used for realizing multi-step run，as shown in Fig.6-26.

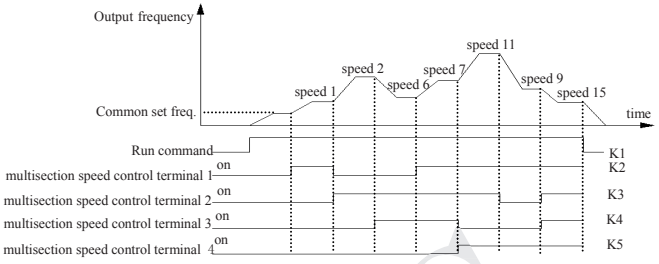
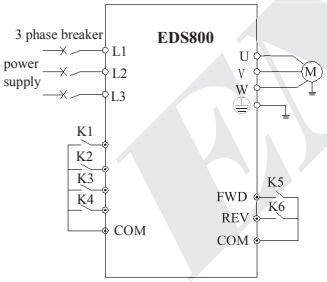



**Fig.6-26 multi-step speed run**

In Fig.6-27 see an example of terminal run command channel，can make forward, reverse run control by K5, K6. In Fig.6-26, by different logic combination of K1, K2, K3, K4，the inverter can run according to common set frequency or multi-step frequency based on above table.



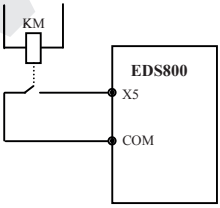




**Fig.6-27 multi-step speed run** **Fig.6-28 exterior device failure always-open input**

**5~6: external jog run control input JOGF/JOGR.** When run command channel is set to terminal run command channel F0.02=1，JOGF is jog forward run，JOGR is jog reverse run，jog operation frequency, jog accelerating decelerating time is defined in F2.06~F2.08 (remark: jog run command channel is determined by F0.02)

**7~9: Accel&Decel time terminal selection**

**Table 6-5 Accel&Decel time terminal selection logic mode**

| Terminal 2 | Terminal 2 | Terminal 1 | Accel/Decel time selection |
|---|---|---|---|
| OFF | OFF | OFF | Accel time 1/ Decel time 1 |
| OFF | OFF | ON | Accel time 2/ Decel time 2 |
| OFF | ON | OFF | Accel time 3/ Decel time 3 |
| OFF | ON | ON | Accel time 4/ Decel time 4 |
| ON | OFF | OFF | Accel time 5/ Decel time 5 |
| ON | OFF | ON | Accel time 6/ Decel time 6 |
| ON | ON | OFF | Accel time 7/ Decel time 7 |

Can realize selection for Accel&Decel time1~7 by ON/OFF combination of Accel&Decel time terminal.

**10 : external equipment fault input.** Can input fault signal of external equipment by this terminal to be convenient for the inverter to monitor fault of external equipment. The inverter displays "E0.14", namely external equipment fault alarm after receiving the external equipment fault signal.

**11 : exterior restoration input.** After the fault alarm takes place in the inverter, can restore the inverter through this terminal. Its function is same as function of (RESET) key on the operation panel.

**12 : free stop input.** This function is same as free stop during running defined in F1.05，but it's realized by control terminal to be convenient for long-distance control.

**13 : exterior stop command.** This command is effective to all run command channel，when this function is effective the inverter stops running in mode set by F1.05.

**14 : DC injection braking input command DB during stop.** Implement DC injection braking to the motor during stop by control terminal，in order to realize urgent parking and accurate orientation of the motor. Braking initial frequency, braking time are defined in F1.06, F1.07.

**15 : inverter run forbiddance.** The inverter during running stops freely when this terminal is effective and forbidden to start in waiting status. Mainly applied to occasion needing safe linkage.

**16~17: frequency increasing command UP/descending command DOWN**

Realize frequency increasing or descending by control terminal, which substitute for keypad to realize long-distance control. Effective during common run if F0.00=2.Increasing descending speed is set by F5.09.

**18 : Accel&Decel speed forbidden command.** Let the motor not effected by any foreign signal(except stop command)，keep running at current frequency.

note Ineffective during normal decelerating stop.

**19 : three-wire run control. Please refer to function description of F5.08 run mode (three-wire run mode).**

**20 : closed-loop ineffective. Realize flexible switch to lower level run mode under closed-loop run status.**

note
(1) can switch between closed-loop and lower level run mode only during closed-loop run(F3.00=1).
(2) start stop control, direction and Accel&Decel time are subject to setting of corresponding run mode when it's switched to lower level run mode.

**21 : PLC ineffective.** Realize flexible switch to lower level run mode under PLC run status.

note
(1) can switch between PLC and lower level run mode only during PLC run(F4.00≠0).
(2) start stop control, direction and Accel&Decel time are subject to setting of corresponding run mode when it's switched to lower level run mode.

**22 : simple PLC pause command.** Implement pause control to PLC process during running，run at zero frequency when this terminal is effective，not time for PLC run .after ineffective implement automatic speed tracking start and continue PLC run. For application method please refer to function description ofF4.00~F4.14.

**23 : PLC stop status restoration.** Under stop status of PLC run mode, will clear PLC run step, runtime, run frequency etc. recorded when PLC run stops if this terminal is effective，please see F4 group function description.

**24~26 : terminal frequency provision channel selection.** Through ON/OFF combination of frequency provision channel selection terminal 24, 25, 26，can realize frequency provision channel switch shown in Table 6-6. For relation of terminal switch and function code F0.00 setting, that is, latter effective.

**Table 6-6 terminal frequency provision channel selection logic mode**

| frequency provision channel selection end 3 | frequency provision channel selection end 2 | frequency provision channel selection end 1 | frequency provision channel selection |
|---|---|---|---|
| OFF | OFF | OFF | hold freq. setting |
| OFF | OFF | ON | potentiometer provision |
| OFF | ON | OFF | keypad number provision |
| OFF | ON | ON | terminal UP/DOWN adjusting provision |
| ON | OFF | OFF | serial port provision |
| ON | OFF | ON | VCI |
| ON | ON | OFF | CCI |
| ON | ON | ON | end PULSE provision |

**27: switch frequency to CCI.** Frequency provision channel is switched to CCI provision compulsorily when this function terminal is effective, frequency provision channel come back to previous status when this function terminal is ineffective.

**28 : command switched to terminal.** Run command channel is switched to terminal run command channel compulsorily when this function terminal is effective.

**29~31: terminal select run command channel**

**Table 6-7 run command channel logic mode**

| Run command channel selection terminal 3 | Run command channel selection terminal 2 | Run command channel selection terminal 1 | Run command channel |
|---|---|---|---|
| OFF | OFF | OFF | hold run command channel |
| OFF | OFF | ON | keypad run command channel |
| OFF | ON | OFF | end run command channel (keypad STOP command ineffective) |
| OFF | ON | ON | end run command channel (keypad STOP command effective) |
| ON | OFF | OFF | serial port run command channel (keypad STOP command ineffective) |
| ON | OFF | ON | serial port run command channel (keypad STOP command effective) |

Can realize control command selection shown in Table 6-7 by ON/OFF

combination of run command channel selection terminal，For relation of terminal switch and function code F0.00 setting, that is, latter effective.

**32 : traverse jump-in.** When traverse start mode is manual jump-in，traverse function effective if this terminal effective，see F6 function parameter description.

**33 : exterior interruption input.** The inverter close off output and run at zero frequency during running upon receiving exterior interruption signal. The inverter implement automatic speed tracking start-up to resume running once external interruption signal is relieved.

**34 : interior counter clearing end.** To clear built-in counter in the inverter with cooperation of counter triggering signal.

**35 : interior counter triggering end.** Counting pulse input port of built-in counter，pulse max. frequency: 200Hz，see function code F5.24, F5.25.

**36 : interior timer clearing end.** To clear built-in timer in the inverter with cooperation of timer triggering signal.

**37 : interior timer triggering end.** Please see function description for parameter F5.27.

**38 : pulse frequency input( only effective to X5).** Only effective for multifunction input terminal X5, this function terminal receive pulse signal as frequency provision, for relation between inputted signal pulse frequency and set frequency in detail, please refer to F7 group parameter.

**39 : reserved**

**40 : reserved**

**41 : reserved**

**42 : reserved**

| F5.08 | FWD/REV run mode selection | Range：0~3 | 0 |
|---|---|---|---|

This parameter defines 4 kinds of exterior terminal control mode for inverter running.

**0: 2-wire control mode 1**

| K2 | K1 | run |
|---|---|---|
| 0 | 0 | stop |
| 1 | 0 | reverse run |
| 0 | 1 | forward run |
| 1 | 1 | stop |

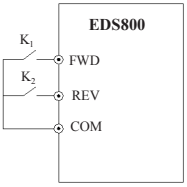



**Fig.6-29 2-wire run mode 1**

**0: 2-wire control mode 2**

| K2 | K1 | run |
|---|---|---|
| 0 | 0 | stop |
| 1 | 0 | stop |
| 0 | 1 | forward run |
| 1 | 1 | reverse run |

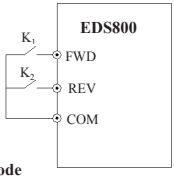



**Fig.6-30 2-wire run mode**

**2: 3-wire control mode 1**

thereinto:

SB1: stop button

SB2: forward run button

SB3: reverse run button

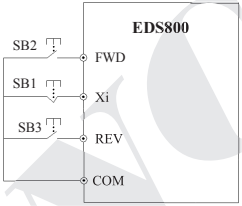


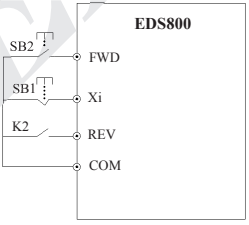

**Fig.6-31 3-wire run mode 1**

Xi is multifunction input terminal of X1~X5, here should define its corresponding terminal function as No. 19 "3-wire run control" function.

**3: 3-wire control mode 2**

SB1: stop button

SB2: run button




| K2 | run direction selection |
|---|---|
| 0 | Forward run |
| 1 | Reverse run |

**Fig.6-32 3-wire run mode 2**

Xi is multifunction input terminal X1~X5, here should define its corresponding terminal function as No. 19 "3-wire run control" function.

The inverter restores after failure and start at once if run command channel selecting terminal and terminal FWD/REV is effective during warning alarm stop.

| F5.09 | UP/DOWN speed | Range：0.01－99.99Hz/s | 1.00Hz/s |
|---|---|---|---|

This function code defines varying rate of the set frequency when it's modified by UP/DOWN terminal.

| | | | |
|---|---|---|---|
| **F5.10** | **Open collector output terminal OC output setting** | **Range：0~24** | **0** |
| **F5.11** | **Reserved** | | |
| **F5.12** | **Reserved** | | |
| **F5.13** | **Reserved** | | |

OC open collector output terminal，Table 6-8 shows option of above 4 function parameter，choosing same output terminal function repeatedly is allowed.

**Table 6-8 output terminal function selection table**

| item | corresponding function | item | corresponding function |
|---|---|---|---|
| 0 | Inverter running signal (RUN) | 1 | Frequency arriving signal (FAR) |
| 2 | Frequency level detectingsignal (FDT1) | 3 | reserved |
| 4 | Overload warning signal( OL) | 5 | Output Freq. reach high limit( FHL) |
| 6 | Output Freq. reach low limit( FLL) | 7 | Inverter stops for under voltage blockage (LU) |
| 8 | Stop for exterior failure( EXT) | 9 | Inverter zero speed running |
| 10 | In PLC run process | 11 | Simple PLC segment run finished |
| 12 | PLC finish one cycle run | 13 | reserved |
| 14 | Inverter is ready for run( RDY) | 15 | Inverter failure |
| 16 | traverse high&low limit restriction | 17 | Interior counter final value arrive |
| 18 | Interior counter specified value arrive | 19 | Set runtime arrive |
| 20 | Interior timer timing arrive | 21 | reserved |
| 22 | FWD running | 23 | REV running |
| 24 | reserved | | |

Now introduce function listed in Table 6-8 as follows:

**0: inverter during running( RUN).** The inverter is in run status，output indicator signal.

**1: frequency arriving signal( FAR).** Refer to function description of F5.14.

**2: Frequency level detecting signal( FDT1).** Refer to function description of F5.15~F5.16.

**3: reserved**

**4: overload warning signal( OL).** Inverter output current exceed F9.05 overload detect level and time exceed F9.06 overload detect time，output indicator signal.

**5: output frequency reach high limit( FHL).** When set frequency≥high limit frequency and run frequency reach high limit frequency，output indicator signal.

**6: output frequency reach low limit( FLL).** When set frequency≤low limit frequency and run frequency reach low limit frequency，output indicator signal.

**7: Inverter stops for under voltage blockage( LU).** When the inverter is running, LED displays“P.OFF” and output indicator signal if DC bus-bar voltage is lower than limitative level.

**8: stop for exterior failure( EXT).** When the inverter give the alarm (E014) and stops for exterior failure, output indicator signal.

**9 : inverter zero speed running.** When the inverter output zero frequency but
in run status, output indicator signal.

**10 : In PLC run process**

**11: Simple PLC segment run finished.** After simple PLC current segment run is finished，output indicator signal(single pulse signal，width 500ms).

**12 : PLC finish one cycle run**

**13 : reserved**

**14 : Inverter is ready for run( RDY).** If this signal is effective, shows that bus-bar voltage is normal and run prohibition terminal is ineffective, the inverter can receive start-up command.

**15 : Inverter fault.** If failure takes place when the inverter is running, the inverter output indicator signal.

**16 : Traverse high&low limit restriction.** After choosing traverse function, if frequency fluctuant range based on center frequency of traverse is above high limit frequency F0.10 or under low limit frequency F0.11, the inverter will output indicator signal, as shown in Fig. 6-33.

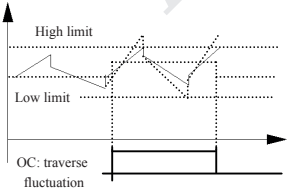



**Fig.6-33 traverse range restriction**

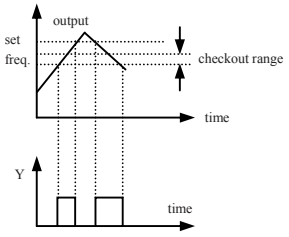



**Fig.6-34 freq. arriving signal output**

**17 : Interior counter final value arrive**

**18 : Interior counter specified value arrive**

17~18 please refer to function description of F5.25~F5.26.

**19 : Set runtime arrive.** When accumulative runtime of the inverter (F2.52) reach set runtime(F2.51)，output indicator signal.

**20 : Interior timer timing arrive.** Refer to function description for F5.27.

**21 : Reserved**

**22 : Reserved**

**23 : Reserved**

**24 : Reserved**

| F5.14 | Freq. arriving(FAR)detect range | Range：0.00－50.00Hz | 5.00Hz |
|---|---|---|---|

This parameter is supplementary definition to No. 1 function in Table 6-8.As shown in Fig.6-34，when output frequency of the inverter is within high&low detect range of set frequency，output pulse signal.

| F5.15 | FDT1（freq. level）electric level | Range：0.00－high limit frequency | 10.00Hz |
|---|---|---|---|
| F5.16 | FDT1 lag | Range：0.00－50.00Hz | 1.00Hz |

F5.15~F5.16 is supplementary definition to No.2 function in Table 6-8, introduce as follows:When output frequency exceed the set frequency (FDT1 electric level)，output indicator signal，till output frequency descend to be some frequency(FDT1 electric level-FDT1 lag) lower than FDT1 electric level，as shown in Fig.6-35.

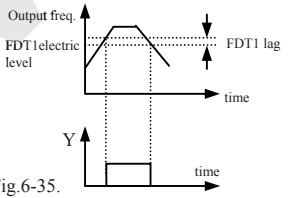



**Fig.6-35 freq. level detecting**

| F5.17 | Analog output（AO）selection | Range：0~9 | 0 |
|---|---|---|---|

**0: output frequency( 0－high limit frequency)**

**1: set frequency( 0－high limit frequency)**

**2: output current( 0－2×rated current)**

**3: output voltage( 0－1.2×load motor rated voltage)**

**4: bus-bar voltage( 0－800V)**

**5: PID provision (0.00-10.00V)**

**6: PID feedback (0.00-10.00V)**

| | | | |
|---|---|---|---|
| F5.18 | Analog output（AO）gain | Rang：0.00－2.00 | 1.00 |
| F5.19 | Analog output（AO）offset | Rang：0.00－10.00V | 0.00 |

For AO analog output, the user can modify display measuring range or emend meter head error by adjusting output gain if necessary.

| | | | |
|---|---|---|---|
| F5.20 | Reserved | | |
| F5.21 | Reserved | | |
| F5.22 | Reserved | | |

| | | | |
|---|---|---|---|
| F5.23 | DO terminal output function selection | Range：0~9 | 0 |

Same as F5.17 function parameter description.

| | | | |
|---|---|---|---|
| F5.24 | DO max. pulse output freq. | Range：0.1－20.0（max. 20KHz） | 10.0 |

DO port max. output pulse frequency corresponds to maximum value optioned by F5.23，for example 0: output frequency，then max. Output pulse frequency corresponds to high limit frequency.

| | | | |
|---|---|---|---|
| F5.25 | Set interior count number arriving provision | Range：0－9999 | 0 |
| F5.26 | Specified interior count number arriving provision | Range：0－9999 | 0 |

F5.25, F5.26 is supplementary definition to No. 17, 18 function in Table 6-8.

Set count number provision，shows that when some number of pulse are inputted to Xi(count triggering signal input function terminal), OC (open collector Output terminal) output a indicator signal.

As shown in Fig.6-36，OC output an indicator signal when the 8th pulse is inputted to Xi. Here F5.25=8.

Specified count number provision，shows that when some number of pulse are inputted to Xi, Yi output a indicator signal，till set count number is reached.

As shown in Fig.6-36，TA, TB, TC start to output an indicator signal when the 5th pulse is inputted to Xi. Until set count number 8 is reached. Here F5.26=5. Specified count number is ineffective when it is bigger than set count number.

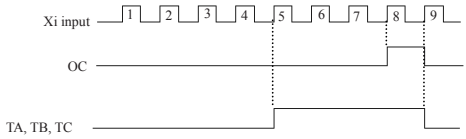



**Fig.6-36 set count number and specified count number provision**

| F5.27 | Interior timer timing setting | Range：0.1－6000.0s | 60.0 |
|---|---|---|---|

This parameter is used to set timing time of interior timer of the inverter.The timer is activated by exterior triggering end(triggering end selected by F5.00~F5.07), the timer begins timing upon receiving exterior triggering signal, after it's up to timing time one effective pulse signal of 0.5s will be outputted from relative OC end

## 6.7 traverse special function parameter group: F6

| F6.00 | traverse function selection | Range：0, 1 | 0 |
|---|---|---|---|

**0: traverse function ineffective**

**1: traverse function effective**

| F6.01 | traverse run mode | Range：LED 1st bit: 0, 1<br>LED 2nd bit: 0, 1 | 00 |
|---|---|---|---|

**0: automatic jump-in mode.** After start-up run at traverse preset frequency for a period of time, then enter into traverse operation automatically.

**1: terminal manual run mode.** When set the multifunction terminal Xi ( Xi=X1~X5)to function 32 and it's effective, enter into traverse state; quit traverse state if ineffective and run frequency is at traverse preset frequency.

LED 2nd bit:

**0: changing amplitude.** Amplitude AW varies with center frequency, for its changing rate please see F6.02 definition.

**1: fixed amplitude.** Amplitude AW is determined by high limit frequency and F6.02.

Traverse center frequency input setting channel is set by F0.00 function.

| F6.02 | traverse amplitude | Range：0.0－50.0(%) | 0.0(%) |
|---|---|---|---|

changing amplitude: AW=center frequency×F6.02

fixed amplitude: AW=high limit frequency×F6.02

note Traverse run frequency is restricted by high limit, low limit frequency；if set improperly，abnormal traverse operaion arise.

| F6.03 | Sudden jumping freq. | Range：0.0－50.0（%） | 0.0(%) |
|---|---|---|---|

As shown in Fig.6-36.If this parameter is set to 0, no jumping frequency.

| F6.04 | traverse cycle | Range：0.1－999.9S | 10.0S |
|---|---|---|---|

Whole time for a cycle including traverse rising, descending process.

| F6.05 | Triangle wave rising time | Range: 0.0-98.0(%)(traverse cycle) | 50.0(%) |
|---|---|---|---|

Define runtime of traverse rising segment=F6.04×F6.05 (s)，runtime of descending segment = F6.04×(1-F6.05) (s). Please refer to description in Fig.6-37.

| F6.06 | Traverse preset frequency | Range：0.00－400.00Hz | 0.00Hz |
|---|---|---|---|
| F6.07 | Traverse preset frequency latency time | Range：0.0－6000S | 0.0S |

F6.06 is used for defining inverter run frequency before entering into traverse operation.

When automatic start-up mode is optioned，F6.07 is used for setting holding time running at traverse preset frequency before enter into traverse operation；When manual start-up mode is optioned，F6.07 setting is ineffective. Please see description in Fig.6-37.

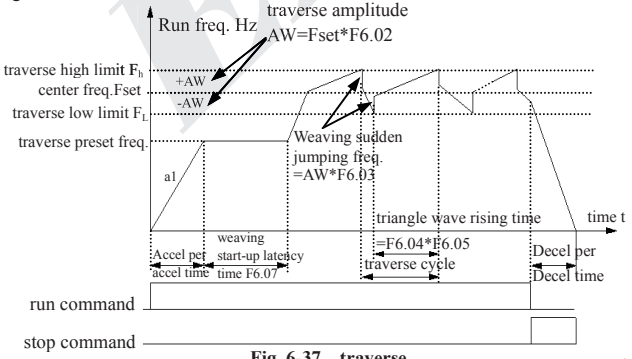



**Fig. 6-37 traverse**

## 6.8 Frequency provision function parameter group: F7

| | | | |
|---|---|---|---|
| F7.00 | VCI minimum provision | Range：0.00－F7.02 | 0.0V |
| F7.01 | Corresponding freq. to VCI minimum provision | Range：0.00－high limit frequency | 0.00Hz |
| F7.02 | VCI max. provision | Range：0.00－10.00V | 10.0V |
| F7.03 | Corresponding freq. to VCI maximum provision | Range：0.00－high limit frequency | 50.00Hz |
| F7.04 | CCI minimum provision | Range：0.00－F7.06 | 0.00V |
| F7.05 | Corresponding freq. to CCI minimum provision | Range：0.00－high limit frequency | 0.00Hz |
| F7.06 | CCI max. provision | Range：0.00－10.00V | 10.00V |
| F7.07 | Corresponding freq. to CCI max. provision | Range：0.00－high limit frequency | 50.00Hz |
| F7.08 | Max. Input pulse width | Range:0.1-999.9ms(whenF0.00=11) | 100.0ms |
| F7.09 | Min. Input pulse width | Range:0.0-F7.11(Max.provision pulse)(whenF0.00=11) | 0.0ms |
| F7.10 | min. provision corresponding freq. | 0.00－high limit frequency | 0.00Hz |
| F7.11 | Max. provision pulse width | Rang:F7.09(Min.provision pulse) -F7.08(Max.provision pulse) | 100.0ms |
| F7.12 | max. provision corresponding freq. | Range: 0.00－high limit frequency | 50.00Hz |

When choose F0.00=11(terminal pulse setting freq.).the function of above parameter effective.

Pulse width in milliseconds ,the freq. of input pulse width can effect the precision of output freq., to assure the precision of output freq.,customer advised use the freq. of pulse width between 1Hz to 100Hz.

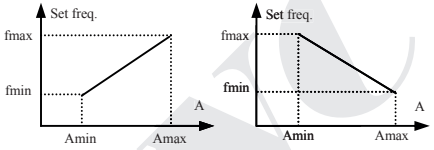
Please don't use these function for the application where there use close freq control.

| | | | |
|---|---|---|---|
| F7.13 | PULSE max. pulse input | Range：0.1－20.0K | 10.0K |
| F7.14 | PULSE minimum provision | Range：0.0－F7.16 | 0.0K |
| F7.15 | Corresponding freq. to PULSE min. provision | Range：0.00－high limit frequency | 0.00Hz |

| | | | |
|---|---|---|---|
| **F7.16** | **PULSE max. provision** | **Range：F7.14(PULSE min. provision)—F7.13(max. input pulse)** | **10.0K** |
| **F7.17** | **Corresponding freq. to PULSE max. provision** | **Range：0.00—high limit frequency** | **50.00Hz** |

F2.00 sets the analog channel filtering time constant，to filter input signal，the more long filtering time is, the more great anti-jamming ability is, but response speed descend; the more short filtering time is, the more fast the inverter respond, but anti-jamming ability is weakened.

See below relation curve of VCI and set frequency:



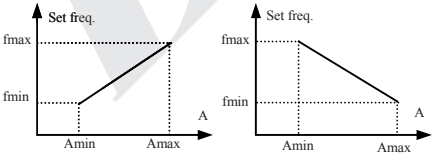

(1) plus characteristic (2) minus characteristic

A:VCI provision

Amin:min. provision fmin:corresponding freq. of min. provision

Amax:max. provision fmax:corresponding freq. of max. provision

See below relation curve of CCI and set frequency:



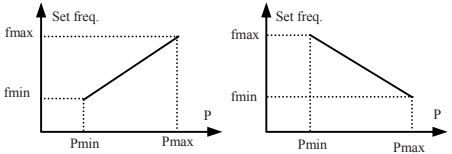

(1) plus characteristic (2) minus characteristic

A: CCI provision

Amin:min. provision fmin:corresponding freq. of min. provision

Amax:max. provision fmax:corresponding freq. of max. provision

See below relation curve of PULSE and set frequency:




(1) plus characteristic (2) minus characteristic

P: PULSE provision

Pmin: min. provision fmin: corresponding freq. to min. provision

Pmax: max. provision fmax: corresponding freq. to max. provision

## 6.9 Motor and vector control function parameter group: F8

| | | | |
|---|---|---|---|
| **F8.00** | **Reserved** | | |
| **F8.01** | **Motor rated voltage** | **Range: 1－480V** | **Depend on device type** |
| **F8.02** | **Motor rated current** | **Range: 0.1－999.9A** | **Depend on device type** |
| **F8.03** | **Motor rated frequency** | **Range: 1.00－400.00Hz** | **Depend on device type** |
| **F8.04** | **Motor rated speed** | **Range: 1－9999r/min** | **Depend on device type** |
| **F8.05** | **Motor pole** | **Range: 2－14** | **Depend on device type** |
| **F8.06** | **Motor rated power** | **Range: 0.1－999.9KW** | **Depend on device type** |
| **F8.07** | **Reserved** | | |
| **F8.08** | **Reserved** | | |
| **F8.09** | **Reserved** | | |
| **F8.10** | **Reserved** | | |
| **F8.11** | **Reserved** | | |
| **F8.12** | **Reserved** | | |
| **F8.13** | **Reserved** | | |
| **F8.14** | **Reserved** | | |
| **F8.15** | **Reserved** | | |
| **F8.16** | **Frequency display offset** | **Range:0.00－2.00Hz** | **0.20Hz** |

| F8.17 | Reserved | | |
|---|---|---|---|

Please set F8.01~F8.06 according to rated data of drived motor for safety.

## 6.10 Protection function parameter: F9

| F9.00 | Reserved | | |
|---|---|---|---|

| F9.01 | failure self-restoration times | Range：0－10 | 0 |
|---|---|---|---|
| F9.02 | failure self-restoration interval | Range：0.5－20.0S | 5.0S |

During run process, failure will take place accidently due to load fluctuation and the inverter will cut off output, here failure self-restoration function can be applied in order to let the device continue to run. During self-restoration, the inverter will try to resume running in speed checking restart mode but stop outputting and failure protected if the inverter can't resume running successfully within set times. Self-restoration function will be shut down if failure self-restoration times is set to 0.

(1) To use failure self-restoration function must take device allowance and no essential failure in the inverter as preconditions.
(2) Self-restoration function is ineffective to failure protection caused by overload and over heat.

| F9.03 | Motor overload protection mode selection | Range：0, 1 | 1 |
|---|---|---|---|

This parameter defines protecting action mode when overload, overheat take place in the inverter.

**0: no action.** No motor overload protection characteristic(apply with caution), here the inverter have no overload protection for load motor;

**1: inverter cut off output at once.** The inverter cut off output and motor stop freely when overload, overheat take place.

| F9.04 | motor overload protection coefficient | Range：20.0-120.0(%) | 100.0(%) |
|---|---|---|---|

This parameter sets sensibility of the inverter implementing thermal relay protection to load motor, can implement correct heat protection to the motor by setting this value when output current value of load motor don't match rated current of the inverter, as shown in Fig.6-38.

Value of this parameter can be determined by following formula:

$$F9.04=\frac{\text{motor rated current}}{\text{inverter rated output current}}\times 100$$

**note** The inverter will lose thermal relay protection function when a piece of inverter drive multiple motors in parallel. Please assemble heat protection relay at input side of each motor to protect them effectively.

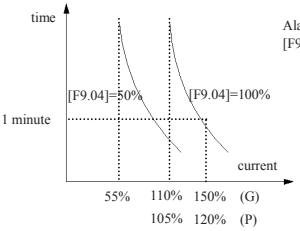



**Fig.6-38 electronic thermal relay protection**

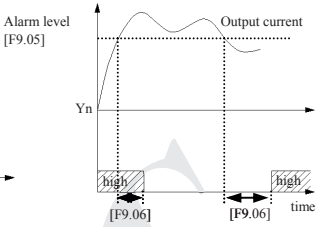



**Fig.6-39 overload alarm**

| | | | |
|---|---|---|---|
| **F9.05** | **overload alarm checkout level** | **Range：20－200(%)** | **130(%)** |
| **F9.06** | **overload alarm delay time** | **Range：0.0－20.0S** | **5.0S** |

If output current exceeds electric level set by parameter F9.05 continuously, open collector outputs effective signal(refer to Fig.6-39 and interrelated description of parameter F5.10 ) after delay time set by F9.06 passed.

| | | | |
|---|---|---|---|
| **F9.07** | **Overvoltage stall selection** | **Range：0, 1** | **1** |
| **F9.08** | **Stall overvoltage point** | **Range：120－150(%)** | **140(%)** |

**0: banned**

**1: allowed**

Actual descending rate of motor speed may be lower than that of output frequency due to effect from load inertia when the inverter is in decelerating run process, here the motor will feed electric energy back to inverter which will make DC bus-bar voltage of the inverter increase, overvoltage protection will takes place if not take steps. Overvoltage stall protection function, indicates that output frequency of the inverter stops descending if bus-bar voltage detected during run process exceed stall voltage point defined by F9.08 (relative to standard bus-bar voltage) and the inverter continue to implement decelerating run when bus-bar voltage detected again is lower than stall overvoltage point. As shown in Fig. 6-40.

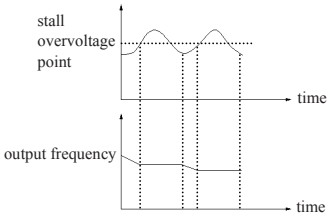



**Fig.6-40 overvoltage stall function**

| | | | |
|---|---|---|---|
| **F9.09** | **automatic current limiting level** | **Range：110－200(%)** | **150(%)** |
| **F9.10** | **frequency descending rate during current limiting** | **Range：0.00－99.99Hz / S** | **10.00Hz/S** |
| **F9.11** | **automatic current limiting action selection** | **Range：0, 1** | **0** |

By automatic current limiting function the inverter can limit load current not to exceed automatic current limiting level set by F9.09 to avoid tripping out for failure caused by rushing current. This function is especially suitable for some biggish inertia or acutely changing load occasion.

Automatic current limiting (F9.09) defines current threshold value of automatic current limiting action, its value is the percentage relative to inverter rated current. Frequency descending rate during current limiting (F9.10) defines adjusting rate to output frequency during automatic current limiting action.

If frequency descending rate during automatic current limiting F9.10 is too small，inverter isn't easy to get rid of automatic current limiting state which may cause overload failure finally；If descending rate F9.10 is too big, the inverter may be in generating state for long time which will cause overvoltage protection.

Automatic current limiting function is effective in accelerating decelerating state and whether it's effective in constant speed run state is determined by automatic current limiting action selection (F9.11).

F9.11=0 indicates that automatic current limiting is ineffective during constant speed running；

F9.11=1 indicates that automatic current limiting is effective during constant speed running；

Output frequency may varies during automatic current limiting action，so automatic current limiting function is not suitable for occasion demanding stable output frequency during constant speed run.

## 6.11 Failure record function parameter: Fd

| | | | |
|---|---|---|---|
| Fd.00 | previous one failure record | Range: 0~23 | 0 |
| Fd.01 | previous two failure record | Range: 0~23 | 0 |
| Fd.02 | previous three failure record | Range: 0~23 | 0 |
| Fd.03 | previous four failure record | Range: 0~23 | 0 |
| Fd.04 | previous five failure record | Range: 0~23 | 0 |
| Fd.05 | previous six failure record | Range: 0~23 | 0 |

0: no failure

1~23: failure E0.01~E0.23，please see chapter 7 for specified failure type.

| | | | |
|---|---|---|---|
| Fd.06 | Set freq. at previous failure | Range: 0-high limit | 0 |
| Fd.07 | Output freq. at previous failure | Range: 0-high limit | 0 |
| Fd.08 | output current at previous failure | Range: 0-999.9A | 0 |
| Fd.09 | output volt. at previous failure | Range: 0-999V | 0 |
| Fd.10 | DC bus-bar vlot. at previous failure | Range: 0~800V | 0 |
| Fd.11 | Load motor speed at previous failure | Range: 0~9999 | 0 |
| Fd.12 | Module temp. at previous failure | Range: 0~100 | 0 |
| Fd.13 | Input end state at previous failure | | 0 |
| Fd.14 | Accu. runtime at previous failure | Range: 0~65535h | 0 |

## 6.12 Code and manufacturer function parameter: FF

| | | | |
|---|---|---|---|
| **FF.00** | **user password** | **Range： 0000－9999** | **0000** |

User password setting function is used for prohibiting unauthorized personnel from consulting and modifying function parameter.

Set this function code to 0000 when user password function isn't wanted.

First input 4 bits number as user password and press ENTER DATA key to confirm, then the password will come into effect at once.

Password modification:

Enter into password verification state by pressing ESC MENU key, after inputting primary 4 bits password parameter editing state is available，choose FF.00(here FF.00=0000)，input new password and press ENTER DATA key to confirm，then the password come into effect at once.

**note** Please keep the password you set without fail, in case the password is missing please consult the manufacturer.

| | | | |
|---|---|---|---|
| **FF.01** | **manufacturer password** | **Range：0000－9999** | **0000** |

Setting function for the manufacturer, user need not modify it.

# 7 Troubleshooting

## 7.1 Failure and countermeasure

Possible failure types in EDS800 are shown in Table 7-1 and failure code is from E001 to E023. Some failure code is reserved for intelligent automatic diagnosis function which will be executed continuously in future. When failure takes place in the inverter, the user should check according to note of this table first and record failure phenomena detailedly. Please contact our after-sale service and technical support Department or agent in your local place when technical service is needed.

**Table 7-1 failure type and the countermeasure**

| failure code | failure type | possible reason | countermeasure |
|---|---|---|---|
| E001 | overcurrent during accelerating process | Accelerating time is too short | Prolong accelerating time |
| | | Improper V/F curve | Adjust V/F curve setting，adjust manual torque boost or change to automatic torque boost |
| | | Restart rotating motor | Set speed checking restart function |
| | | Low power source voltage | Check input power supply |
| | | Too small power of the inverter | Choose inverter with high-power |
| E002 | overcurrent during decelerating process | Decelerating time is too short | Prolong decelerating time |
| | | Have potential energy load or big inertia load | Increase braking power of external energy consumption braking subassembly |
| | | Power of inverter is a bit small | Choose inverter with high-power |
| E003 | overcurrent during constant speed process | Load change suddenly or Have unwonted phenomena | Check or reduce break of the load |
| | | Accel/Decel time is set to too short | Prolong accelerating decelerating time properly |
| | | low power source voltage | Check input power supply |
| | | Power of inverter is a bit small | Choose inverter with high-power |
| E004 | overvoltage during accelerating process | Unwonted input voltage | Check input power supply |
| | | Accel time is set to too short | Prolong accelerating time properly |
| | | Restart rotating motor | Set speed checking restart function |

| | | | |
|---|---|---|---|
| E005 | overvoltage during decelerating process | Decelerating time is too short | Prolong decelerating time |
| | | Have potential energy load or big inertia load | Increase braking power of external energy consumption braking subassembly |
| E006 | Overvoltage during constant speed process | Unwonted input voltage | Check input power supply |
| | | Accel/Decel time is set to too short | Prolong accelerating decelerating time properly |
| | | Input voltage change abnormally | Assemble reactor |
| | | Load inertia is a bit big | Use energy consumption subassembly |
| E007 | controlpower supply overvoltage | Unwonted input voltage | Check input power supply or look for service |
| E008 | Inverter overload | Accel time is set to too short | Prolong accelerating time |
| | | DC injection braking is too big | Reduce DC injection braking current, prolong braking time |
| | | improper V/F curve | Adjust V/F curve and torque boost |
| | | Restart rotating motor | Set speed checking restart function |
| | | power source voltage is too low | check power source voltage |
| | | Load is too big | Choose inverter with high-power |
| E009 | Motor overload | improper V/F curve | Adjust V/F curve and torque boost |
| | | power source voltage is too low | check power source voltage |
| | | General motor run at low speed with big load | Can choose frequency conversion motor for long time low speed run |
| | | motor overload protection factor set incorrectly | to set motor overload protection factor correctly |
| | | motor blocked up or load change too suddenly and quickly | Check the load |
| E010 | inverter over heating | Air-path blocked | To clear air-path or improve ventilation condition |
| | | Ambient temperature is too high | Improve ventilation condition, lower carrier frequency |
| | | Fan damaged | Replace the fan |
| E011 | reserved | reserved | reserved |
| E012 | reserved | reserved | reserved |

| | | | |
|---|---|---|---|
| E013 | Inverting module protection | Transient overcurrent of the inverter | Refer to countermeasure for overcurrent |
| | | phase to phase short circuit or earthing short circuit of output 3 phase | wiring again |
| | | Air-path blocked or fan damaged | To clear air-path or replace the fan |
| | | Ambient temperature is too high | Lower ambient temperature |
| | | Connecting wire or insert on control board loose | Check and connect the wire again |
| | | Unwonted current wave caused by missing output phase etc. | Check wiring |
| | | Assistant power supply damaged and drive voltage lacking | Look for service from manufacturer or agent |
| | | Unwonted control board | Look for service from manufacturer or agent |
| E014 | external device failure | use sudden stop STOP key in non-keypad run mode | Look up operation mode |
| | | Use sudden stop STOP key under condition of stall | Set running parameter correctly |
| | | Sudden stop terminal for external failure closed | Open external failure terminal after external failure is settled |
| E015 | current detecting circuit failure | Connecting wire or insert on control board loose | Check and connect the wire again |
| | | Assistant power supply damaged | Look for service from manufacturer or agent |
| | | Hall component damaged | Look for service from manufacturer or agent |
| | | Unwonted amplifying circuit | Look for service from manufacturer or agent |
| E016 | RS485 communication failure | Baud rate set improperly | set Baud rate properly |
| | | Serial port communication error | press STOP/RESET key to reset，look for service |
| | | Failure warning parameter set improperly | Modify F2.16, F2.17 |
| | | Upper device doesn't work | Check if upper device work and wiring is correct |

| | | | |
|---|---|---|---|
| E017 | PID Disconnection fault | PID feedback amount lost | Check the PID feedback loop wiring is good or not |
| | | PID value instantly becomes very small | Check the equipment abnormal or not |
| E018 | reserved | reserved | reserved |
| E019 | Under voltage | Under voltage | check spot input voltage |
| E020 | System disturbance | Serious disturbance | Reset by pressing STOP/RESET key or add mains filter at power supply input side |
| | | Main control DSP read and write wrongly | Reset by the key-press, look for service |
| E021 | reserved | reserved | reserved |
| E022 | reserved | reserved | reserved |
| E023 | $E^2$PROM read and write wrongly | Mistake take place when read or write control parameter | Reset by pressing STOP/RESET Look for service from manufacturer or agent |
| P.OFF | Under voltage | Under voltage | check spot input voltage |

## 7.2 Failure record lookup

This series inverter can record latest 6 failure code and inverter run parameter of the last failure, to search these informations can redound to finding out reason of the failure.

Failure information is all stored in Fd group parameter，please enter into Fd group parameter to see about information by referring to keypad operation method.

| code | content | code | Content |
|---|---|---|---|
| Fd.00 | previous one failure record | Fd.08 | output current at previous failure |
| Fd.01 | previous two failure record | Fd.09 | output volt. at previous failure |
| Fd.02 | previous three failure record | Fd.10 | DC bus-bar vlot. at previous failure |
| Fd.03 | previous four failure record | Fd.11 | load motor speed at previous failure |
| Fd.04 | previous five failure record | Fd.12 | module temp. at previous failure |
| Fd.05 | previous six failure record | Fd.13 | input end state at previous failure |
| Fd.06 | set freq. at previous failure | Fd.14 | Accu. runtime at previous failure |
| Fd.07 | output freq. at previous failure | — | — |

## 7.3 Failure reset

(1) Before reset you must find out reason of failure downright and eliminate it, otherwise may cause permanent damage to the inverter.
(2) If can't reset or failure takes place again after resetting, should look for reason and continuous resetting will damage the inverter.
(3) Reset should take place 5 minutes after overload, overheat protection action.

To resume normal running when failure takes place in the inverter, you can choose following any kind of operation:

⑴Set any one terminal of X1~X5 to external RESET input (F5.00~F5.04=11), open it after connected to COM.

⑵When failure code is displayed，press STOP/RESET key after restoration is confirmed.

⑶Cut off power supply.

# 8 Maintenance

## 8.1 Routine maintenance

When you use EDS800 series you must assemble and operate it according to demand listed in this《service manual》strictly. During run state, temperature, humidity, vibration and aging parts may affect it. To avoid this, it is recommended to perform routine inspections.

**Table 8-1 Daily inspection items**

| period | | Inspection item | Inspection content | Criterion |
|---|---|---|---|---|
| daily | periodic | | | |
| √ | | Run state parameter | (1)output current | (1)within range of rated value |
| | | | (2)output voltage | (2)within range of rated value |
| | | | (3)inside temp. | (3)temp. increment < 35℃ |
| √ | | Cooling system | (1)installing ambient | (1)good ventilation, unblocked air-path |
| | | | (2)local fan | (2)rotate normally without abnormal noise |
| √ | | Motor | (1)heating | (1)no abnormality |
| | | | (2)noise | (2)even |
| | √ | Inverter | (1) vibration, heating | (1)vibration balanced, proper wind temp. |
| | | | (2)noise | (2) without abnormal sound |
| | | | (3)fixation of lead, terminal | (3)fixed screw don't loose |
| √ | | Run ambient | (1)temperature, humidity | (1)-10℃~+40℃<br>40℃~50℃used in lower volume or execute compulsory heat dissipating |
| | | | (2)dust, water and leakage | (2)no water leakage imprint, no dust |
| | | | (3)gas | (3)no peculiar smell |

Recommend to inspect with following instrument:

Input voltage: electric voltmeter; output voltage: rectifying voltmeter; input output current: pincers ammeter.

## 8.2 Inspection and replacement of damageable parts

Some component parts in the inverter will be abraded or bear descending performance for long-term usage，to assure that the inverter can run stably and reliably, it is recommended to perform defending maintenance and replace corresponding parts if necessary.

(1) cooling fan

Abnormal noise, even oscillation may take place if the fan have wearing bearing, aging blade, here replacement of the fan should be considered.

(2) filter electrolyte capacitance

When frequent-changing load causes increasing pulsant current and aging electrolyte under high ambient temperature, the electrolyte capacitance may be damaged and here should replace it.

## 8.3 Repair guarantee

(1) Within 18 months from purchasing date, if failure caused by inverter itself takes place under normal conservation and usage, we will provide free repair service.

(2) We will take some upkeep if one of following situations takes place within period of repair guarantee.

a. If did not use the inverter according to《service manual》strictly or did not use it under ambient demanded in《service manual》, which cause failure.

b. Failure caused by applying the inverter to non-normal function;

c. Failure caused by self-repair, refit which is not already allowed;

d. Damage caused by bad keeping, falling down from high place or other extrinsic factor after purchasing the inverter;

e. Failure caused by natural disaster or its reason such as unwonted voltage, thunderbolt, water fog, fire, salt corroding, gas corroding, earthquake and storm etc.;

f. Make bold to tear up product logo (such as: nameplate etc.); Body serial number don't accord with that in repair guarantee card.

(3) We calculate service fee based on actual cost, which is subject to contract if any.

(4) You can contact the agent and also our company directly if you have questions. After repair guarantee period, we shall also provide lifetime charged repair service for our products.

**note** Our company will also provide lifetime repair service with fee for inverter which is not within period of repair guarantee.

## 8.4 Storage

The user must pay attention to following points for temporary storage and long-term storage after purchasing the inverter:

(1) Avoid storing the inverter in high temperature, moist place and place of dust, metal powder and assure good ventilation.

(2) Longtime storage will cause electrolyte capacitance of low quality, so must assure that it's electrified for one time within 2 years and electrification time is not shorter than 5 hours and input voltage must be increased to rated value gradually by voltage adjustor.

# 9 Examples

## 9.1 Common speed regulation running

### 9.1.1 Basic wiring diagram

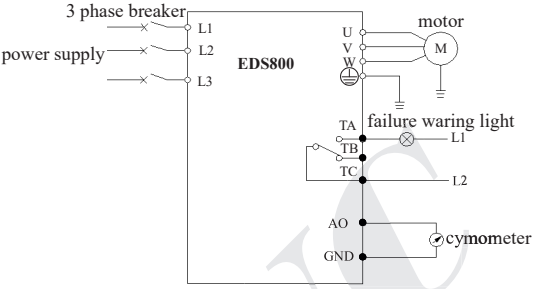



**Fig. 9-1**

### 9.1.2 Set following basic parameter:

(1) set parameter F8.01-F8.06 according to rated value of the inverter.
(2) set F0.00 parameter to 0，choose keypad analog potentiometer to set frequency.
(3) set F0.02 parameter to 0，choose keypad to control start-up, stop.
(4) use F0.03 parameter to set run direction.

note

(1) Press key to set frequency.
(2) To press STOP/RESET key，the inverter will stop.
(3) To press ENTER/DATA key，inverter enter into next menu or confirm data.
(4) Press ▲▼ key to increase or decrease the data.

### 9.1.3 Realized function

(1) realize stepless speed regulation to the motor, use keypad to control start/stop and keypad analog potentiometer to adjust frequency.
(2) bear failure warning function.
(3) connect with cymometer，which indicates output frequency of the inverter.

### 9.1.4 Application field

Used for common speed regulation field，such as: transportation machine, china machine, baccy machine, metallurgy machine etc.

## 9.2 Terminal control running

### 9.2.1 Basic wiring diagram

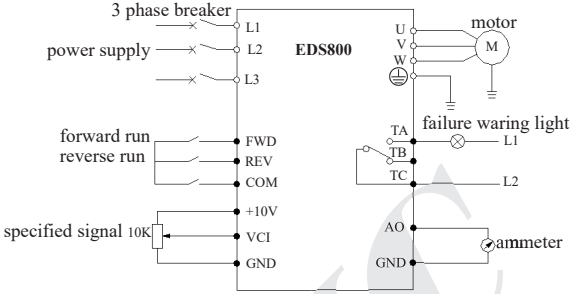



**Fig. 9-2**

### 9.2.2 Parameter setting

(1) set parameter F8.01-F8.06 according to rated value of the inverter.

(2) set F0.00 parameter to 4, 5 to choose VCI, CCIaccordingly, can accept frequency set signal within 0~10V.

(3) set F0.02 parameter to 1，to choose terminal run command channel.

**note**

(1) if F5.08=0,namely 2 wire control mode 1：FWD and COM are closed，moter is in forward run；REV and COM are closed，motor is in reverse run FWD, REV and COM are closed or opened together，the inverter stop.

(2) set frequency is specified through VCI analog channel.

### 9.2.3 Realized function

(1) control forward run/reverse run of the motor by external on-off quantum.

(2) control speed of the motor by 0~10V signal.

(3) bear failure warning and output current indication function.

### 9.2.4 Application field

Used in field where need long-distance control to start/stop of the motor such as blower, food, chemical machine, packing machine, transportation machine etc.

## 9.3 Multi-step speed control running

### 9.3.1 Parameter setting

(1) set parameter F8.01-F8.06 according to rated value of the inverter. set F0.02

parameter to 1，to choose terminal run command channel.

(2) F2.30-F2.44: multi-step speed frequency setting.

(3) F5.00-F5.04 set multi-step speed terminal control function.

(1) If F5.08=0,namely 2 wire control mode 1：FWD and COM are closed，moter is in forward run；REV and COM are closed，motor is in reverse run；FWD, REV and COM are closed or opened together，the inverter stop.

(2)If any one or more terminal of X1, X2, X3 and COM are closed together, the inverter will run according to multi-step speed frequency determined by X1, X2, X3 (multi-step speed frequency set value are determined by F2.30-F2.44).Can realize manual control and automatic control for multiple frequency，and also control for forward run, reverse run, free stop, reset, warning protection.

### 9.3.2 Basic wiring diagram

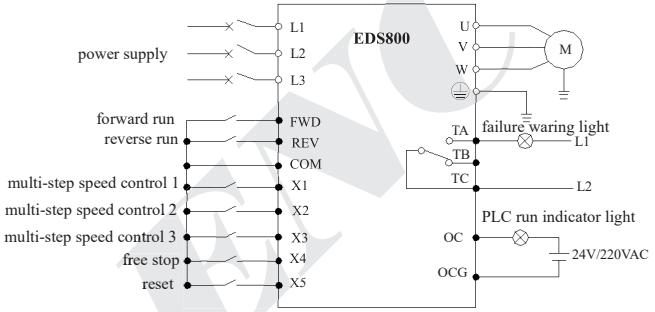



**Fig.9-3**

### 9.3.3 Realized function

(1) make use of external on-off quantum signal to control start/stop of the motor.

(2) make use of external on-off quantum signal to make the motor run at set frequency.

(3) bear free stop and reset function by utilizing external on-off quantum signal.

(4) bear warning alarm and PLC run indication function.

### 9.3.4 Application field:

Applied in field where need frequent multi-speed adjustment to motor speed such as toughened glass, weaving, paper making, chemical etc..

## 9.4 Closed-loop control system

### 9.4.1 Parameter setting

(1) set parameter F8.01～F8.06 according to rated value of the inverter.

(2) F3.00=1: setting channel selection，here PID closed loop run control is effective.

(3) F3.01=1: setting channel selection，here choose VCI as provision channel of PID adjustor.

(4) F3.02=1: feedback channel selection，here choose CCI as feedback channel, 4-20mA/0-10V feedback signal.

(5) F3.08-F3.10, set according to spot requirement.

### 9.4.2 Basic wiring diagram

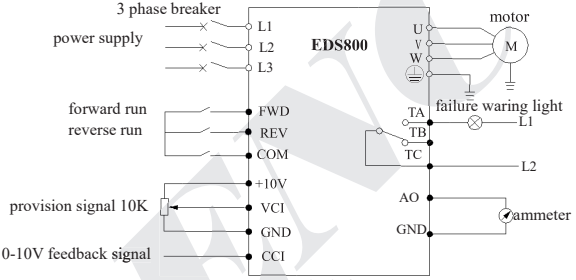



Fig.9-4

### 9.4.3 Realized function

(1) The inverter can adjust output automatically according to feedback signal to make constant voltage, constant temperature, constant current etc. available.

(2) can control start/stop of the motor from long distance.

(3) bear failure alarm and current indicator function.

### 9.4.4 Application field

Applied in field where need stable system, pressure, flux such as blower pump, constant pressure water supply, air compressor, air conditioner, freezer cooling tower, music fountain, heat supply etc..

## 9.5 Consecutive action running

### 9.5.1 Basic wiring diagram

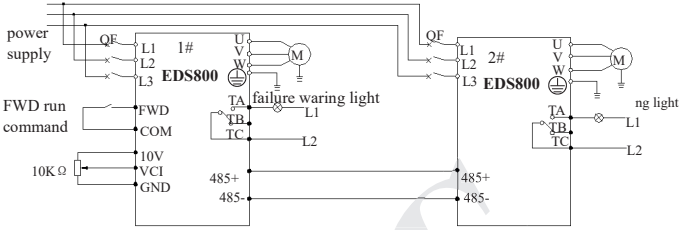



**Fig.9-5**

### 9.5.2 Parameter setting

set 1# inverter as follows:

(1) F0.02=1: terminal run command control.

(2) F5.23=0: DO terminal output pulse signal for 1# inverter output frequency.

(3) F5.10=0: 1# inverter running signal is outputted by digital output terminal OC.

set 2# inverter as follows:

(5) F0.00=7: terminal pulse setting is frequency provision for 2# inverter.

(6) F0.02=1: terminal run command control.

(7) F5.04=38：X5 is for pulse frequency input.

After above setting, can use digital/pulse output quantum of 1# inverter to realize consecutive action of 2# inverter.

### 9.5.3 Operation description

After receive forward run command from external switch(closed) and frequency specified value( 0~10V)from analog input terminal VCI, 1# inverter run at this frequency value. At the same time, already running state of 1# inverter，make 2# inverter get forward run command through open circuit collector output end OC，here，run frequency value from high-speed pulse output terminal of 1# inverter is passed to 2# inverter through X5 terminal.

### 9.5.4 Application field

Applied in field such as conveyer belt, coiler, factory production line, food chemistry, piece drawer etc.

# 10 Modbus communication protocol

## 10.1 Summarization

We provide general RS485 communication interface in our inverters (such as EDS800 series, EDS1000 series and etc.) for the user. Through this communication interface upper device (such as HMI, PC, PLC controller and etc.) can perform centralized monitor to the inverter (such as to set inverter parameter, control run of inverter, read work state of the inverter).

This communication protocol is interface criterion file designed for realizing above-mentioned function, please read it earnestly and program according to it so that realize long-distance and network control to the inverter.

## 10.2 Communication net buildup mode

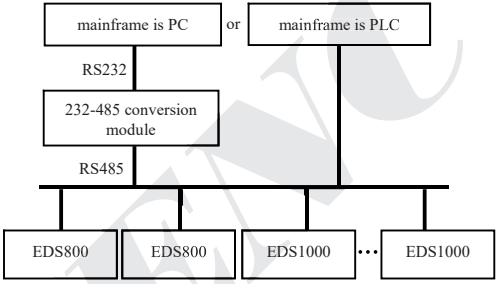



Fig.10-1 net buildup graph

## 10.3 Communication mode

At present, EDS800 inverter can be used only as auxiliary device in RS485 net. Can realize communication between inverters through PC, PLC or HMI if it's needed. Specific communication mode is as mentioned below:

(1) PC or PLC as mainframe，inverter as auxiliary device, point-to-point communication between mainframe and auxiliary device.

(2) Auxiliary device don't response when mainframe send out command by broadcast address.

(3) User can set local address, baud rate and data format of the inverter through auxiliary device keypad or serial communication mode.

(4) EDS800 provides optional RS485 interface.

(5) Default mode: Asynchronous serial，semiduplex transport mode. RTU mode. Default format and transport rate: 8-N-1, 9600bps.

## 10.4 RTU Communication Mode:

### 10.4.1 Data frame format

Using RTU mode, messages are sent at least 3.5 character time interval pause. The first transmitted field is device address, the character you can transfer is hexadecimal 0x00 ~ 0xFF. Network equipment Continuously monitor the bus, including pauses. When the address field is received, all equipment determine whether it is sent to their own. when the last character of the packet transfer is complete, at least a 3.5 character times pause mean the end of the message. A new message can begin after this pause.

The entire message frame must be transmitted as a continuous flow. If a new message start transmitting in less than 3.5 character times after a message and then receiving device will consider it a continuation of the previous message. This will cause an error, because in the final CRC field value can not be right.

RTU frame format as the talbe below:

| | |
|---|---|
| Frame Header | 3.5 characters time pause |
| Slave address | Slave value：1~127 |
| Communication command code | 03H：read slave parameter<br>06H：write slave parameter |
| Data content DATA | The contents of packet:<br>Parameter address（16bit）;<br>Number of parameter or bytes of parameter value;<br>Parameter value（16bit） |
| Data content DATA | |
| …… | |
| …… | |
| CRC check value low byte | 16bit Unsigned check value |
| CRC check value high byte | |
| Closing Flag | 3.5 characters time pause |

Regarding generation method of CRC check value, please refer to part 10.8 for check method.

### 10.4.2 Host read slave parameter

Command code 03H. Host can read or one or more parameter( up to ten) by initiating a communication transaction .

E.g., read 2 contiguous inverter parameter values from the address 0000H of inverter whoes address is 01, the contents of host command:

| | |
|---|---|
| ADR | 01H |
| CMD | 03H |
| Parameters initial address high byte | 00H |
| Parameters initial address low byte | 00H |
| Number of parameter high byte | 00H |
| Number of parameter low byte | 02H |
| CRC check value low byte | Be calculated |
| CRC check value high byte | Be calculated |

The contents of slave reply:

| | |
|---|---|
| ADR | 01H |
| CMD | 03H |

| | |
|---|---|
| Parameter value bytes | 04H |
| Address 0000H content high byte | 00H |
| Address 0000H content low byte | 01H |
| Address 0001H content high byte | 13H |
| Address 0001H content low byte | 88H |
| CRC check value low byte | Be calculated |
| CRC check value high byte | Be calculated |

### 10.4.3 Host write slave parameter

Command code 06H. Host can write an parameter by initiating a communication transaction .

E.g.,The decimal system 5000 (1388H) written to the inverter 0001H address whose slave address is 02，host command including：

| | |
|---|---|
| ADR | 02H |
| CMD | 06H |
| Parameter address high byte | 00H |
| Parameter address low byte | 01H |
| Parameter value high byte | 13H |
| Parameter value low byte | 88H |
| CRC check value low byte | Be calculated |
| CRC check value high byte | Be calculated |

The contents of slave reply：

| | |
|---|---|
| ADR | 02H |
| CMD | 06H |
| Parameter address high byte | 00H |
| Parameter address low byte | 01H |
| Address 0903H content high byte | 13H |
| Address 0903H content low byte | 88H |
| CRC check value low byte | Be calculated |
| CRC check value high byte | Be calculated |

## 10.5 Data communication address allocation

### 10.5.1 Function code Fd-F0 group communication address

Inverter function parameter's MODBUS communication address addressing process follows PPnn way: PP means high byte of the address, corresponding to function parameter's group number; nn means low byte of the address, corresponding to function code parameter's group internal code. For example: F3.21 function code's communication address is 0315H, 03H is the hex form of group number 3, 15H is the hex form of grop internal code 21.

F0.00~F9.11 communication address is 0000H~090BH, Fd group fault record parameter start address is 0D00H.

### 10.5.2 control command and status word communication address

| Variable Name | Communication address | Reading-writing attribute | Command data or response value meaning |
|---|---|---|---|
| run command word | 2000H | Writing only | 1: inching run |
| | | | 2: inching stop |
| | | | 3: forward inching run |
| | | | 4: reversal inching run |
| | | | 5: run |
| | | | 6: stop |
| | | | 7: forward run |
| | | | 8: reversal run |
| | | | 9: fault reset |
| | | | 10: emergency stop |
| Serial port frequency provision | 2001H | Reading and writing | Lower frequency ~ upper frequency |
| Inverter status | 2100H | Reading only | 1: forwarder running<br>2: reversal running<br>3: stop<br>4: alarm status |
| Alarm code | 2180H | Reading only | 0: without alarm<br>1~23:mean E001~E023 alarm |

### 10.5.3 Monitor parameter communication address

| Monitor parameter | Name | Communication address (Reading only) |
|---|---|---|
| C-00 | Set frequency | 1000H |
| C-01 | Output frequency | 1001H |
| C-02 | Output current | 1002H |
| C-03 | Output voltage | 1003H |
| C-04 | DC bus-bar vlotage | 1004H |
| C-05 | Load motor speed | 1005H |
| C-06 | module temperature. | 1006H |
| C-07 | Power on running time | 1007H |
| C-08 | Accumulative running time | 1008H |
| C-09 | Input terminal status | 1009H |
| C-10 | Output terminal status | 100AH |
| C-11 | Analog input VCI value | 100BH |
| C-12 | Analog input CCI value | 100CH |
| C-13 | reserved | |
| C-14 | External impulse frequency | 100EH |

## 10.6 Communication error processing

Inverter receiving data packet detection error, it finds reading&writing parameter address or parameter value invalid, so reply to the host with communication error response packet. Communication error response packet (host command code +80H) as command code, with 1 byte error code.

Format for communication error response packet as follows:

| | |
|---|---|
| ADR | 01H |
| CMD | 83H/86H |
| communication error code | 01H~06H (for details, please check below table) |
| Low byte of CRC checksum | Obtain by calculating |
| High byte of CRC checksum | Obtain by calculating |

Meaning for each communication error code value as follows:

| Communication error code value | Type of communication error |
|---|---|
| 0x01 | CRC checksum error |
| 0x02 | Command code illegal |
| 0x03 | Register address visited illegal |
| 0x04 | Value to register illegal |
| 0x05 | Not allow to modify parameters |
| 0x06 | Register number read illegal |

## 10.7 Data frames examples

### 10.7.1 start 1# inverter running

| Data Field | Auxiliary Inverter Address | Order code | Register address High byte | Register address Low byte | Data High byte | Data Low byte | CRC high bit | CRC Low bit |
|---|---|---|---|---|---|---|---|---|
| host command frames | 01 | 06 | 20 | 00 | 00 | 05 | 42 | 09 |
| Auxiliary respond frames | 01 | 06 | 20 | 00 | 00 | 05 | 42 | 09 |

### 10.7.2 Stop 1# inverter running

| Data Field | Auxiliary Inverter Address | Order code | Register address High byte | **Register** address Low byte | Data High byte | **Data Low byte** | CRC **high bit** | CRC Low bit |
|---|---|---|---|---|---|---|---|---|
| host command frames | 01 | 06 | 20 | **00** | 00 | **06** | 02 | 08 |
| Auxiliary respond frames | 01 | 06 | 20 | 00 | **00** | 06 | 02 | 08 |

### 10.7.3 Set 1# inverter given value to 50Hz

| Data Field | Auxiliary Inverter Address | **Order code** | **Register address High byte** | Register address Low byte | Data High byte | Data Low byte | CRC high bit | CRC Low bit |
|---|---|---|---|---|---|---|---|---|
| host command frames | 01 | 06 | 20 | 01 | 13 | 88 | DE | 9C |
| Auxiliary respond frames | 01 | 06 | 20 | 01 | 13 | 88 | DE | 9C |

### 10.7.4 Read 1# inverter running state

| Data Field | Auxiliary Inverter Address | Order code | Register address High byte | Register address Low byte | Data High byte | Data Low byte | CRC high bit | CRC Low bit |
|---|---|---|---|---|---|---|---|---|
| host command frames | 01 | 03 | 21 | 00 | 00 | 01 | 8E | 36 |
| Auxiliary respond frames | 01 | 03 | (Respond value byte count ) 02 | | 00 | 00 | B8 | 44 |

## 10.8 CRC checksum mode

CRC checksum value calculating function written by C language is as follows:

```
unsigned int cal_crc_value (unsigned char *pval, unsigned char len)
{
  unsigned int crc_value=0xFFFF;
  unsigned int i;

  while(len--)
  {
        crc_value ^= *pval++;
        for(i=0; i<8; i++)
        {
              if(crc_value & 0x0001)
              {
                    crc_value >>= 1;
                    crc_value ^= 0xA001;
              }
              else
              {
                    crc_value >>= 1;
              }
        }
  }
  return(crc_value);
}
```

# Appendix 1 Serial port 485 communication protocol

## 1.1 Summarization

We provide general RS485/RS232 communication interface in our inverters(such as EDS2000 series，EDS2800 series，EDS1000 series etc.) for the user. Through this communication interface upper device (such as PC, PLC controller etc.) can perform centralized monitor to the inverter (such as to set inverter parameter, control run of inverter, read work state of the inverter) and also long-distance control keypad can be connected to realize various usage requirement of the user.

This communication protocol is interface criterion file designed for realizing above-mentioned function, please read it earnestly and program according to it so that realize long-distance and network control to the inverter.

## 1.2 Protocol content and description

### 1.2.1 Communication net buildup mode

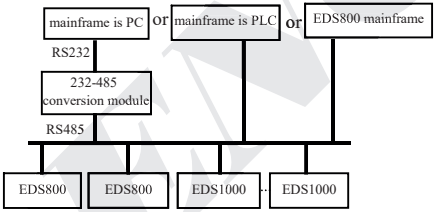



Fig.1 Net buildup graph

### 1.2.2 Communication mode

At present, EDS800 inverter can be used only as auxiliary device in 485 net. Can realize communication between inverters through PC or PLC if it's needed. Specific communication mode is as mentioned below:

(1) PC or PLC as mainframe，inverter as auxiliary device，point-to-point communication between mainframe and auxiliary device.

(2) Auxiliary device don't response when mainframe send out command by broadcast address.

(3) User can set local address, baud rate and data format of the inverter through auxiliary device keypad or serial communication mode.

(4) Auxiliary device report current failure information to mainframe in the lo

response frame.

(5) EDS800 provides 485 interface.

### 1.2.3 Transport mode

Asynchronous serial，semiduplex transport mode. Default format and transport rate: 8-N-1，9600bps.For specific parameter setting please see description for F2.14～F2.17 group function code.

(remark： Below definition is only effective under series port RS485 communication mode, and definition for other parameters are the same as original)

| | | | | | |
|---|---|---|---|---|---|
| F2.14 | Communication configuration | LED first bit：baud rate selection<br>0：1200BPS<br>1：2400BPS<br>2：4800BPS<br>3：9600BPS<br>4：19200BPS<br>5：38400BPS<br>LED second bit：data format<br>0：1-8-1 format，no checkout<br>1：1-8-1 format，even checkout<br>2：1-8-1 format，odd checkout | 1 | 03 | × |
| F2.15 | Local address | 0－127，127 is broadcast address | 1 | 1 | × |
| F2.16 | Communication timeout detection time | 0.0－1000.0s | 0.1s | 0.0s | × |
| F2.17 | Local response delay | 0－200ms | 1ms | 5ms | × |
| F2.53 | RS485/232 communication frame format selection | 0: a ASCII frame of 14 byte or 18 byte<br>1: a hex frame of 8 byte or 10 byte, original response not changed<br>2: a hex frame of 8 byte or 10 byte, 12 command has no response<br>3: a hex frame of 8 byte or 10 byte, 14 command has no response<br>4: a hex frame of 8 byte or 10 byte, both 12 and 14 command have no response | 1 | 0 | × |

### 1.2.4 Data command frame format

| main device command frame format | | | | | | | | | | | | | | | | | |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| sending order | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 |
| | frame head | auxiliary device address | auxiliary device address | main device command | main device command | assistant index | assistant index | command index | command index | set data | set data | set data | set data | checkout sum | checkout sum | checkout sum | checkout sum | frame end |
| Defi-nition | head | address | | command area | | Index area | | | | setting data area | | | | checkout area | | | | end |
| sending byte | 1 | 2 | | 2 | | 4 | | | | 4 | | | | 4 | | | | 1 |

| auxiliary device response frame format | | | | | | | | | | | | | | | | | | |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| sending order | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 |
| | frame head | auxiliary device address | auxiliary device address | auxiliary device reponse | auxiliary device reponse | failure index | failure index | command index | command index | run data | run data | run data | run data | checkout sum | checkout sum | checkout sum | checkout sum | frame end |
| Definiti-on | head | address | | reponse area | | Index area | | | | Run data area | | | | Checkout area | | | | end |
| sending byte | 1 | 2 | | 2 | | 4 | | | | 4 | | | | 4 | | | | 1 |

**Fig.1-2 command/response frame format**

Remark:

(1) “Setting data area” and “run data area” may not be existent in some command/data frame format, so in protocol command list it’s marked with “nothing”.

(2) In protocol effective character set is: ~, 1, 2, 3, 4, 5, 6, 7, 8, 9, A, B, C, D, E, F and hex data 0DH，ASCII lowercase a, b, c, d, e, f are invalid.

(3) Effective command frame length is 14 or 18 byte.

### 1.2.5 Explanation and description for format

(1) frame head

It’s character “~” ( namely hex 7E),single byte.

(2) auxiliary device address

Data meanings: local address of auxiliary device, double byte. ASCII format. Inverter factory default is 01.

(3) mainframe command/auxiliary device respond

Data meanings: mainframe send out command and auxiliary device respond to the command. Double byte, ASCII format.

Response code function classification:

Species 1>: command code= “10 ”, mainframe ask auxiliary device to report current preparation state and control situation.

**Table 1 response code meanings for command code “10”**

| response code ASCII | meanings | | |
|---|---|---|---|
| | preparation state of auxiliary device | Control from mainframe is allowed | To set frequency is allowed |
| 10 | Don’t get ready | no meaning | |
| 11 | get ready | allow | allow |
| 12 | get ready | allow | allow |
| 13 | get ready | don’t allow | don’t allow |
| 14 | get ready | don’t allow | don’t allow |
| 20 | frame error | | |

Species 2>: command code= “11” ~ “15 ” , 5 kinds of function command which mainframe send to auxiliary device, for detail please see protocol command list.

**Table 2 response code meanings for command code "11~15"**

| response code ASCII | Meanings of response code | description |
|---|---|---|
| 00 | Auxiliary device communication and control is normal; function code modification is effective; password is correct. | |
| 20 | (1) frame checkout error;<br>(2)"command area"data overrun;<br>(3)"index area"data overrun;<br>(4) frame length error/non ASCII byte exist in area except frame head, frame end. | When this response code is reported, data of "command area", "index area" and "running data area" are not reported. |
| 30 | (1) control to auxiliary device is ineffective;<br>(2)ineffective function code parameter modification;<br>(3)"setting/running data"area data overrun.<br>(4) password error. | Whether report this response code relate to current set state of auxiliary device. When report data of area", "index area" and "run data area"are reported according to protocol requirement. |

(4) auxiliary index/command index/failure index

Data meanings: include auxiliary index byte and command index byte.

For mainframe, auxiliary index, command index are used for cooperating mainframe command in realizing specific function.

For auxiliary device, auxiliary index, command index are used for reporting failure state code, command index are reported without modification.

Data type: hex，4 byte, ASCII format.

Command index occupy 2 low byte, data range: "00"～"FF".

Auxiliary index occupy 2 high byte, data range: "00"～"FF".

Auxiliary device failure state occupy "auxiliary index" byte，see Appendix table 3.

**Table 3 failure type description**

| failure code | description | failure code | description |
|---|---|---|---|
| 1 | Accelerating run over current | 13 | Converting module protection |
| 2 | decelerating run over current | 14 | External device failure |

| | | | |
|---|---|---|---|
| 3 | constant speed run over current | 15 | current detecting circuit failure |
| 4 | accelerating run over voltage | 16 | RS485 communication failure |
| 5 | decelerating run over voltage | 17 | reserved |
| 6 | constant speed run over voltage | 18 | reserved |
| 7 | controller power supply over voltage | 19 | Under voltage |
| 8 | Inverter overload | 20 | System disturbance |
| 9 | Motor overload | 21 | Reserved |
| 10 | Inverter over heat | 22 | Reserved |
| 11 | reserved | 23 | $E^2$PROM read and write error |
| 12 | reserved | | |

(5) checkout sum

Data meanings: frame checkout，4 byte, ASCII.

Calculation method: accumulative sum of ASCII code value of all byte from “auxiliary device address” to “run data”.

(6) frame end

Hex 0D，single byte.

### 1.2.7 Protocol command list

Frame 7E and frame end 0D, address, checkout sum，ASCII character format are omitted in following description.

**Table 4 protocol command table**

| Name | main-frame order | auxi-liary index | order index | run data setting range | mainframe sending example，such as PC control operation of inverter(C language cluster format，auxiliary deviceaddress is set to 01) | run data precision | Descripti-on |
|---|---|---|---|---|---|---|---|
| look up auxiliary motor state | 10 | 00 | 00 | no | ~010A00000192\r | 1 | |

| | | | | | | | | |
|---|---|---|---|---|---|---|---|---|
| Read parameter of auxiliary motor | current set freq. | 11 | 00 | 00 | no | ~010B00000193\r | 0.01Hz | |
| | current run freq. | 11 | 00 | 01 | no | ~010B00010194\r | 0.01Hz | |
| | Output voltage | 11 | 00 | 02 | no | ~010B00020195\r | 1V | |
| | Output current | 11 | 00 | 03 | no | ~010B00030196\r | 0.1A | |
| | Bus-bar voltage | 11 | 00 | 04 | no | ~010B00040197\r | 1V | |
| | Load motor speed | 11 | 00 | 05 | no | ~010B00050198\r | 1rpm | |
| | Module temp. | 11 | 00 | 06 | no | ~010B00060199\r | $1^0$C | |
| | Runtime | 11 | 00 | 07 | no | ~010B0007019A\r | 1h | |
| | accumulative time | 11 | 00 | 08 | no | ~010B0008019B\r | 1h | |
| | Input terminal | 11 | 00 | 09 | no | ~010B0009019C\r | no | |
| | output terminal | 11 | 00 | 0A | no | ~010B000A01A4\r | no | |
| | analog input VCI | 11 | 00 | 0B | no | ~010B000B01A5\r | 0.01V | |
| | analog input CCI | 11 | 00 | 0C | no | ~010B000C01A6\r | 0.01V | |
| | reserved | 11 | 00 | 0D | no | ~010B000D01A7\r | 0.01V | |
| | exterior pulse input | 11 | 00 | 0E | no | ~010B000E01A8\r | 0.01Hz | |
| | read inverter state | 11 | 00 | 0F | no | ~010B000F01A9\r | no | |
| Run control and adjusting function | auxiliary device run command | 12 | 00 | 00 | no | ~010C00000194\r | no | |
| | set current run frequency provision of auxiliary device | 12 | 00 | 01 | 0Hz~ high limit freq. | ~010C00010FA0027C\r | 0.01Hz | Set freq. =40.00Hz |
| | auxiliary device run with run freq. provision | 12 | 00 | 02 | 0Hz~ high limit freq. | ~010C00020FA0027D\r | 0.01Hz | auxiliary device run set freq. =40.00Hz |
| | auxiliary device forward run | 12 | 00 | 03 | no | ~010C00030197\r | no | |
| | auxiliary device reverse run | 12 | 00 | 04 | no | ~010C00040198\r | no | |

| | | | | | | | | |
|---|---|---|---|---|---|---|---|---|
| | auxiliary device forward run with run freq. provision | 12 | 00 | 05 | 0Hz~ high limit freq. | ~010C00050FA00280\r | 0.01Hz | forward run boot-strap set freq. =40.00Hz |
| | auxiliary device reverse run with run freq. provision | 12 | 00 | 06 | 0Hz~ high limit freq. | ~010C00060FA00281\r | 0.01Hz | reverse run boot-strap set freq. =40.00Hz |
| | auxiliary device stop | 12 | 00 | 07 | no | ~010C0007019B\r | no | |
| | auxiliary device jog run | 12 | 00 | 08 | no | ~010C0008019C\r | no | |
| | auxiliary device forward jog run | 12 | 00 | 09 | no | ~010C0009019D\r | no | |
| | auxiliary device reverse jog run | 12 | | 0A | no | ~010C000A01A5\r | no | |
| | auxiliary device stop jog run | 12 | 00 | 0B | no | ~010C000B01A6\r | no | |
| | auxiliary device failure restoration | 12 | 00 | 0C | no | ~010C000C01A7\r | no | |
| | auxiliary device urgent stop | 12 | 00 | 0D | no | ~010C000E01A8\r | no | |
| Read function code parameter | Run freq. digital setting F0.01 | 13 | 00 | 01 | no | ~010D00010196\r | 0.01Hz | |
| | Run direction setting F0.03 | 13 | 00 | 03 | no | ~010D00030198\r | 1 | |
| | accelerating time1 F0.08 | 13 | 00 | 0A | no | ~010D000E01AA\r | 0.1S | |
| | decelerating time1 F0.09 | 13 | 00 | 0B | no | ~010D000F01AB\r | 0.1S | |

| | | | | | | | | |
|---|---|---|---|---|---|---|---|---|
| Set function code parameter | Run freq. digital setting F0.01 | 14 | 00 | 01 | 0Hz~ high limit freq. | ~010E00011388026B\r | 0.01Hz | Set function code F0.01= 50.00Hz |
| | Run direction setting F0.03 | 14 | 00 | 03 | 0, 1 | ~010E00030001025A\r | 1 | Set function code F0.03 to reverse run |
| | accelerating time1 F0.08 | 14 | 00 | 09 | 0~8CA0 | ~010E000E03E8028B\r | 0.1S | Set function code F0.08 to 10.0s |
| | decelerating time1 F0.09 | 14 | 00 | 0A | 0~8CA0 | ~010E000F03E8028C\r | 0.1S | Set function code F0.09 to 10.0s |
| Software version query order | Query auxiliary device software version | 15 | 00 | 00 | no | ~010F00000197\r | 1 | |

**Table 5 response state word meanings of reading inverter state command**

| bit | signification | | |
|---|---|---|---|
| | description | 0 | 1 |
| Bit0 | Stop/run state | stop | run |
| Bit1 | Logo for under voltage | normal | Under voltage |
| Bit2 | FWD/REV run logo | Forward run | Reverse run |
| Bit3 | traverse run mode logo | ineffective | effective |
| Bit4 | Common run mode logo | ineffective | effective |
| Bit5 | jog run mode logo | no | Jog |
| Bit6 | PLC run mode logo | no | Yes |
| Bit7 | multi-step freq. run mode logo | no | Yes |
| Bit8 | PI closed loop run mode logo | no | Yes |

| | | | |
|---|---|---|---|
| Bit9 | Set counting value arriving logo | no | Yes |
| Bit10 | specified counting value arriving logo | no | Yes |
| Bit11~15 | reserved | | |

**Table 6 read auxiliary device function code parameter**

| function definition | Read auxiliary device function code parameter: all function code parameter except user password and manufacturer password | | | | | | |
|---|---|---|---|---|---|---|---|
| meanings | frame head | address | order | order index | run data | checkout sum | frame end |
| mainframe order | 7EH | ADDR | 13 | see remark | none | BCC | 0DH |
| byte quantity | 1 | 2 | 2 | 4 | 0 | 4 | 1 |
| auxiliary device respond | 7EH | ADDR | 06 | see remark | Function code para. | BCC | 0DH |
| byte quantity | 1 | 2 | 2 | 4 | 4 | 4 | 1 |

remark:

Command index=combinated by function code group number and hex code of function code number. For instance:
If want to read parameter of F0.05 function code, order index=000B;
If want to read parameter of F2.11 function code, order index =020B;
If want to read parameter of F2.15 function code, order index =0212;
If want to read parameter of F2.13 function code, order index =0210;

Corresponding relation between decimal and hex value of function code group No.

| function group | decimal | hex | function group | decimal | hex |
|---|---|---|---|---|---|
| F0 | 0 | 00H | F6 | 6 | 06H |
| F1 | 1 | 01H | F7 | 7 | 07H |
| F2 | 2 | 02H | F8 | 8 | 08H |
| F3 | 3 | 03H | F9 | 9 | 09H |
| F4 | 4 | 04H | FD | 13 | 0DH |
| F5 | 5 | 05H | FF | 15 | 0FH |

| | |
|---|---|
| virtual data | 0~FFFF (namely 0~65535) |

Please input correct “user password” before you set user function code parameter.

## Table 7 set auxiliary device function code parameter

| function definition | Set auxiliary device function code parameter: all function code parameter except user password and manufacturer password | | | | | | |
|---|---|---|---|---|---|---|---|
| meanings | frame head | address | order | order index | run data | checkout sum | frame end |
| mainframe order | 7EH | ADDR | 14 | see remark | No | BCC | 0DH |
| byte quantity | 1 | 2 | 2 | 4 | 0 | 4 | 1 |
| auxiliary device respond | 7EH | ADDR | 06 | see remark | Function code para. | BCC | 0DH |
| byte quantity | 1 | 2 | 2 | 4 | 4 | 4 | 1 |

remark

Command index=combinated by function code group number and hex code of function code number. For instance:
If want to set parameter of F0.05 function code, order index=000B;
If want to set parameter of F2.11 function code, order index =020B;
If want to set parameter of F2.15 function code, order index =0212;
If want to set parameter of F2.13 function code, order index =0210;

Corresponding relation between decimal and hex value of function Code group No.

| function group | decimal | hex | function group | decimal | hex |
|---|---|---|---|---|---|
| F0 | 0 | 00H | F6 | 6 | 06H |
| F1 | 1 | 01H | F7 | 7 | 07H |
| F2 | 2 | 02H | F8 | 8 | 08H |
| F3 | 3 | 03H | F9 | 9 | 09H |
| F4 | 4 | 04H | FD | 13 | 0DH |
| F5 | 5 | 05H | FF | 15 | 0FH |

| Virtual data | 0~FFFF (namely 0~65535) |
|---|---|

# Appendix 2 Braking resistance

## 1.1 Braking resistance

The motor's electric potential energy will charge inverter's capacitance up reversely if speed of the motor decends too quickly or load of the motor wobbles too quickly while the inverter is running, which will increase the voltage upon power modules suddenly and is easy to make the inverter damaged. The inverter will control it according to load size and performance. You have to connect external resistance to realize timely energy discharge when the braking is not enough. To connect external resistance is a kind of energy consumption braking mode, as all the energy is consumed by the braking resistance.

EDS800-2S0002N~EDS800-2S0015N have built-in braking unit,you can add external braking resistance ,but the external resistance need booking.

**External braking resistance configuration table**

| Type | Braking resistance | Qty. | Power of braking resistance | Remark |
|---|---|---|---|---|
| EDS800-2S0002N | 500Ω | 1 | 60W | External braking resistance |
| EDS800-2S0007N | 500Ω | 1 | 60W | External braking resistance |
| EDS800-2S0015N | 500Ω | 1 | 60W | External braking resistance |
| EDS800-4T0007N | 800Ω | 1 | 60W | External braking resistance |
| EDS800-4T0015N | 800Ω | 1 | 60W | External braking resistance |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