## G3000



General	Input voltage: 3Phase 380V
	Adaptable Motor:
	3Phase 380V 0.75kW-400kW 1hp-450hp
	Control Mode: Vector Control (SVC, FVC), V/f
	Start Torque: 0.5Hz 150%(SVC);0Hz 180%(FVC)

specification	Items		Specifications	
	Control	Max. frequency	Vector control: 0~300 Hz; V/F control: 0~3200 Hz	
		Carrier frequency	0.5~16 kHz	
		Input frequency resolution	Digital setting: 0.01 Hz;	
			Analog setting: max. frequency x 0.025%	
		Control mode	Sensorless vector control (SVC); Flux vector control (FVC); Voltage/Frequency (V/F) control	
		Startup torque	0.5Hz/150% (SVC); 0Hz/180% (FVC)	
		Speed range	1:100 (SVC)	1:1000 (FVC)
		Speed stability precision	±0.5% (SVC)	±0.02% (FVC)
		Torque control precision	±5% (FVC)	
		Overload capacity	60s for 150% rated current, 3s for 180%	
		Torque boost	Fixed boost; Customized boost 0.1%~30.0%	
		V/F Curve	Straight-line V/F curve	
			Multi-point V/F curve	
			N-power V/F curve (1.2-power, 1.4-power, 1.6-	
			power, 1.8-power, square)	
		V/F Separation	Complete separation; Half separation	
		Ramp mode	Straight-line ramp; S-curve rampFour kinds of acceleration/deceleration time with the range of 0.0~6500.0s	
	Operation	Running commandSource	Operation panel; Control terminals; Serial communication port	
		Frequency source	Total 10 types, such as digital Setting; analog voltage setting; analog current setting; pulse setting and serial communication port setting	
		Auxiliary frequencySource	Total 10 types. It can implement fine tuning of auxiliary frequency and frequency synthesis.	
		Input terminal	Standard: 5 digital inp	` '
				Hz high-speed pulse input;
			analog input(AI); 1 only supports 0~10V voltage	
			input; 1 supports 0~10V voltage input or 4~20mA	

		current input.
		Expanding capacity: 5 DI
		1 AI supports -10~10V voltage input and also
		supports PT100\PT1000
		Standard:
		1 high-speed pulse output (open-collector) that
		supports 0-100 kHz square wave signal output
		digital output(DO); 1 relay output; 1 analog
	Output terminal	output(AO) that supports 0~20mA current out
		or 0~10 V voltage output
		Expanding capacity:
		1 DO; 1 relay output; 1 AO supports 0~2mA
		current output or 0~10 V voltage output
Display &	LED display	It displays the parameters.
Operation Panel	Key locking and function selection	It can lock the keys partially or completely and
		define the function range of some keys so as to
		prevent mistake operation.
		Motor short-circuit detection at power-on,
	Protection mode	input/output phase loss protection, over curre
		protection, overvoltage protection
Environment		Indoor, free from direct sunlight, dust, corros
	Installation location	gas,combustible gas, oil smoke, vapour, drip o
		salt.
	Altitude	Lower than 1000 m
	Ambient temperature	-10°C~+40°C
	Humidity	Less than 95%RH, without condensing
	Vibration	Less than 5.9 m/s2 (0.6 g)
	Storage temperature	

function		When the power supply instantaneous stop, the load can feedback
	Instantaneous power stop	energy to compensates the voltage reduction, ensure the LV VFD can
		continuous operation for a short time.
	Virtual I/O	Five groups of virtual DI/Do can realize simple logic control.
	Timing control	Setting time range: 0.0min.~ 6500.0min.
	Multi-motor switchover	Four motors can be switched over via four groups of motor parameters.
	Multiple	It supports 3 types communication via RS-485, Profibus-DP, CAN.
	communicationprotocols	
	Motor overheatprotection	The optional I/O extension card enables AI3 to receive the motor
	Wotor overneatprotection	temperature sensor input.
	Multiple encoder types	It supports various encoders such as differential encoder, open-
	Multiple elicodel types	collector encoder, resolver and UVW encoder.
	Overvoltage / Over current	The current and voltage are limited automatically during the running
	stall control	process so as to avoid frequent tripping due to
	Stall Colltion	overvoltage/overcurrent.
	Rapid current limit	It helps to avoid frequent over current faults of the AC drive.
	Torque limit and control	It can limit the torque automatically and prevent frequent over current



tripping during the running process. Torque control can be implemented in the FVC mode.

